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LM4500A High Fidelity FM Stereo Demodulator with Blend

Absolute Maximum Rating	gs		
If Military/Aerospace specified device	es are required,	Storage Temperature Range	$-65^\circ\text{C}$ to $+150^\circ\text{C}$
please contact the National Semic	onductor Sales	Lamp Drive Voltage	001/
	specifications.	Max Voltage at Pin 7 with Lamp "Off"	300
Power Supply Voltage	16V	Lamp Current	100 mA
Power Dissipation (Package Limitation) 1800 mW		Blend Control Input Voltage (Pin 11)	10V
Derate above $T_A = +25^{\circ}C$	15 mW/°C	Lead Temperature (Soldering 10 sec.)	260°C
Operating Temperature Range (Ambient)	-40°C to +85°C		200 0

**Electrical Characteristics** Unless otherwise noted:  $V_{CC} = 12 V_{DC}$ ,  $T_A = 25^{\circ}C$ , Vp-p standard multiplex composite signal with L or R channel only modulated at 1.0 kHz and with 10% pilot level, using circuit of *Figure 1* 

Parameter	Conditions	Min	Тур	Max	Units
Stereo Channel Separation	Unadjusted Optimized on Other Channel (Note 1)	30 40			dB dB
Measured Voltage Gain (Note 1)		0.8	1	1.2	
THD	2.5 Vp-p Composite Input Signal 1.5 Vp-p Composite Input Signal		0.15 0.08	0.3	%
Signal-to-Noise Ratio	DIN45405 Quasi Peak Reading rms 20 Hz-15 kHz		83 88		dB dB
Ultrasonic Frequency Rejection	19 kHz 38 kHz		31 45		dB dB
Stereo Switch Level	19 kHz Input Level for Lamp "On"	12	16	20	mVrms
Hysteresis			8		dB
Output Voltage Change	With Mono/Stereo Switching (Note 2)		3	20	mV <sub>DC</sub>
Stereo Blend Control Voltage (Pin 11) (See <i>Figure 8</i> )	3 dB Separation 30 dB Separation		0.7 1.7		V V
Minimum Separation	Pin 11 at 0V			1	dB
Monaural Channel Imbalance	Pilot Tone Off		0.03	0.3	dB
Sub-Carrier Harmonic Rejection	76 kHz 114 kHz 152 kHz		80 70 83		dB dB dB
Supply Ripple Rejection	f = 1 kHz		57		dB
Input Impedance			50		kΩ
Output Impedance			100		Ω
Blend Control Current (Note 1)			-100	-300	μA
Capture Range			±4		%
Operating Supply Voltage		8		16	v
Current Drain	Lamp Disconnected		35		mA

Note 1: See Applications Information and Circuit Description.

Note 2: This test is done with the stereo indicator lamp disconnected in order to remove DC shift due to thermal changes. These shifts have long time constants (100 ms) and therefore do not produce audible transients.





## **Circuit Description** INTRODUCTION

The LM4500A is a phase-lock-loop stereo decoder which incorporates a variable separation control, and in which sensitivity to the third harmonics of both the pilot and subcarrier frequencies has been eliminated by the use of appropriate, digitally generated, waveforms in the phase-lock-loop and decoder sections.

The variable separation control may be operated manually, or by a receiver's AGC or S meter signals, to provide smooth transitions between monaural and stereo reception. It operates only during stereo reception: the circit switches automatically to monaural if the 19 kHz pilot tone is absent. The elimination of sensitivity to the third harmonic of the sub-carrier (114 kHz) excludes interference from the sidebands of adjacent transmitters, while the elimination of sensitivity to the third harmonic of the pilot tone (57 kHz) excludes interference from the ARI\* system which employs this frequency.

## **CIRCUIT OPERATION**

The block diagram of the circuit, shown in Figure 2, consists of three sections, the phase-lock-loop, including the digital waveform generator, the stereo switch, and the decoder, in which the composite stereo signal is demodulated and matrixed to separate L and R channels.

In the phase-lock-loop the internal RC oscillator, operating at 228 kHz, feeds a 3-stage Johnson counter, via a binary divider, to generate a series of 19 kHz square waves. By the use of suitably connected NAND and EXCLUSIVE OR gates, the waveforms shown in Figure 3, which are used to drive the various modulators in the circuit, are developed. \*Auto Radio Information - used in Europe

The use of such drive waveforms produces the modulating functions also shown in Figure 3. The usual square waveforms have been replaced in the PLL and decoder sections by 3-level forms which contain no third harmonic (actually no harmonics which are mulliples of 2 or 3 are present). This eliminates the frequency translation of interference from these bands into the low frequency region. Such translation may produce audible components in the decoder section from the sidebands of adjacent channel FM signals, and may produce phase jitter, and consequent intermodulation distortion, in the PLL, from the modulated 57 kHz tones of the ARI system. The LM4500A is inherently free from these effects.

The stereo switch section is of conventional form (e.g. LM1310).

The decoder section consists of a modulator (driven by the waveforms shown in Figure 3) whose outputs are the inverted and non-inverted channel difference signals. These signals pass to the output amplifiers via the variable blend circuit in which they are partially combined, and hence mutually attenuated, according to the control voltage applied.

Matrixing occurs at the inputs of the output amplifiers, where the unmodified composite signal is added to the blended channel difference signals. The stereo separation may be progressively reduced from maximum to zero; dependent on the blending. The control law has been made non-linear, as the major redistribution of sound energy occurs at very low separation levels. For monaural, or very weak stereo signals, the modulator in the decoder section is deactivated by the stereo switch circuit. The variable separation control is thus, also, automatically disabled.



# **Applications Information**

## GAIN AND DE-EMPHASIS

The gain and de-emphasis characteristics of the circuit are defined by shunt feedback via the external RC networks (R3, C5, R4, C7 of *Figure 1*) around the output amplifiers. The gain is unity when resistors of 5.1 k $\Omega$  are used. Higher gains may be obtained by using networks of the form shown in *Figure 4*.



## FIGURE 4. Output Amplifier Feedback Networks

The resistors R6, R7 are added to correct the output quiescent voltage levels which are optimized for R3, R4 =  $5.1 \text{ k}\Omega$  and which would, if uncorrected, become too low with higher value resistors. Suitable network values are as follows:

Gain (dB) B3 B4		C6, C7		86 B7
aan (ab) 110,114	<b>50</b> μ <b>s</b>	<b>75</b> μ <b>s</b>		
0	5.1 kΩ	10 nF	15 nF	
3	6.8 kΩ	6.8 nF	10 nF	47k ± 10%
6	10k	4.7 nF	6.8 nF	$27k \pm 10\%$

The maximum output level is 1 Vrms; consequently the max input is limited to 1.4 Vp-p if the gain is set to 6 dB.

#### SEPARATION ADJUSTMENT

A separation adjustment may be added, as shown in *Figure 5*, to compensate for the receiver's IF characteristics.

This network reduces the amplification of the channel sum signal in the decoder, to compensate the attenuation of the channel difference signal in the receiver's IF section. The network shown will compensate for up to 2 dB attenuation at 38 kHz. The decoder gain is, obviously, reduced by an amount equal to the compensation required. When used as described, the adjustment also corrects the inherent separation of the decoder, which may be optimized on one channel. Optimization of both channels is possible if separate potentiometers are used to feed each output amplifier.



FIGURE 5. Networking Providing Adjustable Separation

#### VARIABLE SEPARATION (BLEND) CONTROL AND 19 kHz OUTPUT

To retain the 16-Pin package the blend control has been combined with the 19 kHz output on Pin 11. The internal circuit providing this combination is shown in *Figure 6*.

If Pin 11 is left open-circuit the 19 kHz signal appears at a mean DC level of 4V. The blend circuit is inoperative at this level and the decoder provides full separation. The 19 kHz signal can be used to tune the internal oscillator.

To reduce the separation the voltage on Pin 11 is reduced. At 3.2V T2 ceases conduction and the 19 kHz signal disappears.

At 2.0V the blend circuit comes into operation and the separation decreases according to the curve shown in *Figure 8.* 



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#### **Oscillator Tuning**

If the variable separation facility is not required Pin 11 is left open-circuit and the 19 kHz signal which then appears may be used to indicate the oscillator frequency. If the variable separation is used, and the drive circuit prevents access to the 19 kHz signal, then the oscillator frequency must be measured directly. A test point should be obtained by modifying the oscillator RC network as in *Figure 7*.

The output is a pulse train of appoximately 1.5V amplitude. Connecting frequency counters of up to 300 pF input capacitance produces less than 0.3% change of the oscillator frequency, which should be set to 228 kHz.

### HIGH LOOP GAIN COMPONENTS

For applications demanding operation under low pilot level (e.g. car radio) the following component changes to *Figure 1* are recommended.

R1 = 12k	C3 = 150 pF
R2 = 1.5k	C4 = 330 pF
R8 = 330	C5 = 150 pF
P1 = 10k	

## EXTERNAL MONO-STEREO SWITCHING AND OSCILLATOR KILLING

If required the LM4500A can be forced into mono mode simply by grounding Pin 9 (see *Figure 1*). The 228 kHz oscillator will be automatically stopped.

The conditions governing mono/stereo switching on Pin 9 are the following:

Quiescent voltage: +2.3 V<sub>DC</sub>

Current required to ensure mono operation (with 100 mVrms pilot level): 10  $\mu$ A (from Pin 9 to ground) Hysteresis: 0.7  $\mu$ A

Stereo/mono switching & oscillator killing; less than  $+\,500~\text{mV}$ 

Maximum stray capacitance between Pin 9 and ground: 100  $\ensuremath{\mathsf{pF}}$ 

## EXTERNAL COMPONENT FUNCTIONS

- P1 19 kHz frequency adjustment.
- P2 Channel separation adjustment and compensation for IF roll-off.
- R3, R6 Gain fixing resistors. The values shown in the schematic are for unity gain.

C6, C7 De-emphasis capacitors. Value to give: RC = 50  $\mu s.$ 





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