

Looking For the Best Motors



Brushless Motor

DC Brushless Motor Catalogue

Ver.



Company Profile | Quality, Technic, Service of TROY

TROY Enterprise Co., Ltd. was established in August 1996. We specialize in the designing and manufacturing of Motors, Gearhead, Motor Driver and Motor controller series.

From August 1998, ISO9001 and ISO14001 were introduced into the company to establish a customer-oriented service system to fulfill the quality policy "Providing the customers with good products and services". In September 1999, we passed the audit conducted by TÜV Germany and got certificates of ISO9001 and ISO14001. We also got the certificate of ISO9001 of year 2008 version again in 2009.

TROY is a company with creativity and ideal. Based on our capability, we will continue our commitment to innovation and supported you in finding the proper products for your application. With our belief Quality, Technic, and Service, we can always meet your motion control needs and be your best partner.



Taiwan patent



China patent





The difference in content between version of 2013.12 and this version

P.3,7,8,10, 11,19,20, 26.32.38

9D \square H series to add to the reduction ratio of 120 to 360 Related specifications

P.5,6

UBD Driver are changed to -N series

P.5,6,7,14 61,62,63,68^{New adding -PH specification data}

P.7	New adding product net weight / gross weight table
P.8	New adding gear technology information
P.10	New adding Planetary Gearhead information
P.11	New Motor and Gearhead combination fixation
P.14	Driver -1N, -2N type changed to SBS, UBS only)
D 47 04 00	

P.17,21,22, New adding Driver wiring and 29,33,34,41 New adding briver wiring a instructions
New adding system wiring diagram

30W, 50W gear shaft type, brake pinion shaft type has passed RoHS certificate P.18 9D□ H series to add to the reduction ratio of 120 to 360, P.19,31 speed range, allowable torque, allowable load, inertia

P.24,25,26, **36,37,38,47** Plus cable diameter Ø 48,57,58,67

9BM085S-3(M),9BM150S-3(M) P.25 Axial size change

P.27,39,49,59 New adding power supply noise filter dimension drawing

9B120S-2M has passed RoHS **P.30** certificate

Correcting the current value
60W, 90W gear shaft type, brake
pinion shaft type has passed
CCC certificate P.42

▶60W, 90W round shaft brake type has passed RoHS certificate

Correcting the current value
Driver changed to -N type
60W, 90W gear shaft type, brake
pinion shaft type has passed
CCC certificate
60W, 90W round shaft brake P.52

type has passed RoHS certificate

Panel menu, dimensional drawing change to -N type P.55,59







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Offer good products and services to customers, assistant customer for better competition is promise from TROY!!

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Features 1

LOW TEMPERATURE HIGH EFFICIENCY POWER SAVING



DC brushless Motor

When full load the highest operating temperature won't be exceed the 50℃. The efficiency can reach to 80%~85%

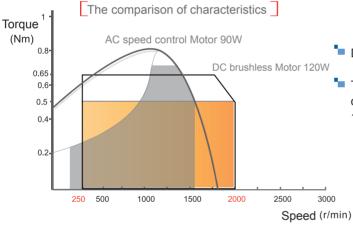


AC speed control Motor

The operating temperature in usual between 70~80℃ The efficiency probably only 40%~50%

Features 2

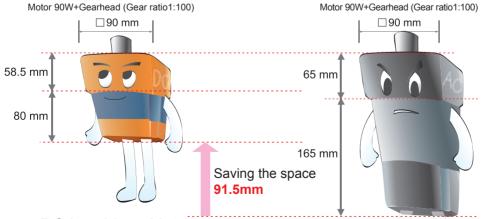
POSSESSING THE SAME TORQUE DURING HIGH & LOW SPEED



- DC brushless→Motor flat torque within 250~2000rpm
- The torque of AC speed control Motor will be changed by different speed. The torque of low speed is smaller. It only has 1/3 of high speed

Features 3

SMALL VOLUME·SAVING THE SPACE



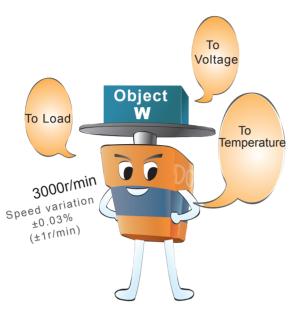
DC brushless Motor

Motor 90W Dimension: □90mmx80mm Gearhead(Gear ratio1:100):58.5mm Total length:80mm+58.5mm=138.5mm AC speed control Motor

Motor 90W Dimension: □90mmx165mm Gearhead(Gear ratio+100):65mm Total length:165mm+65mm=230mm

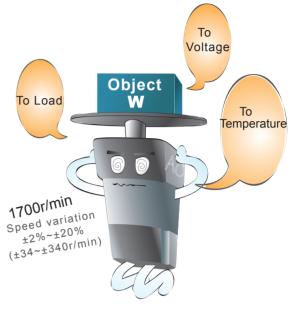
Features 4

LOW SPEED VARIATION·HIGH SPEED STABILITY· POSSESSING THE SPEED TRACING COMPENSATION FUNCTION



DC brushless Motor

► At 3000r/min rated load, speed variation within ±0.03%(±1r/min)

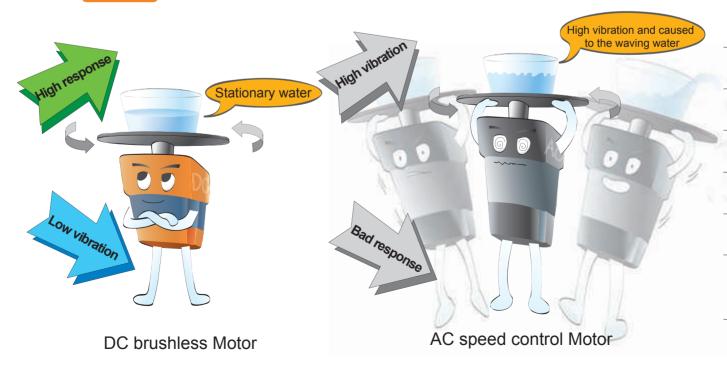


AC speed control Motor

Speed variation between ±2%~±20% $(\pm 34 \sim \pm 340 \text{r/min})$

⁼eatures 5

HIGH RESPONSE·LOW VIBRATION·OPERATING SMOOTHLY



High response, Low vibration, Operation smoothly

Bad response, High vibration, Operation unstable



■ Motor/Driver

Produc	ct series	Input voltage	Speed control range	Speed variation rate	Application
BMS	Standard	3 phase AC220~230V	30~150W: 250~3000 r/min	• Loading±0.05% • Voltage±0.05%	Transmission, moving require high speed stability
DIVIO	E/M brake	3 phase AC220~230V (E/M Brake: DC24V)	200W: 250~2500 r/min	• Temperature±0.05%	Transmission, moving require high speed stability, move up and down, or with loading function
D0	Standard	Single phase 110~115V Single phase AC220~230V	20~120W: 300~3000 r/min	• Loading±0.05% • Voltage±0.05%	Transmission, moving require high speed stability
BS	E/M brake	Single phase 110~115V Single AC220~230V (E/M Brake: DC24V)	200W: 250~2500 r/min	Temperature±0.05%	Transmission, moving require high speed stability, move up and down, or with loading function
SBS	Standard	Single phase 110~115V Single AC220~230V	250~2000 r/min	• Loading-1%	Transmission requires fast response, high transmission action frequency
363	E/M brake	Single phase 110~115V Single AC220~230V (E/M Brake: DC24V)	250~2000 f/min	Voltage±2% Temperature±2%	Transmission requires fast response, high transmission action frequency, move up and down, or with loading function
UBS	Standard	Single phase 110~115V Single AC220~230V	250~2000 r/min	• Loading-1%	Simple operation, easy to control transmission application
UBS	E/M brake	Single phase 110~115V Single AC220~230V (E/M Brake: DC24V)	250~2000 1/111111	Voltage±2%Temperature±2%	Simple operation, easy to control transmission application, move up and down, or with loading function
DBS	Standard	DC24V	250~3000 r/min	• Loading-2%	Transmission with DC power
ספת	E/M brake	DC24V (E/M Brake: DC24V)	200 -3000 1/111111	Voltage±2% Temperature±3%	Transmission with DC power, move up and down, or with loading function

■ Gearhead

Product series	Motor	Max. torque	Gear ratio
6D□series	☐ 60mm gear shaft Motor (20~50W type)	6.5Nm	3~360 Ratio (26 ratios)
6D□H series	☐ 90mm gear shaft Motor (60~150W type)	40Nm	3~360 Ratio (26 ratios)
9D□H series	☐ 90mm gear shaft Motor (200 type)	50Nm	3~360 Ratio (26 ratios)

■ Accessories

Product series	Application	Page no.
D/A speed set	Convert PLC output signal from digital to analog to control Motor turning speed	70
Power supply	It can input AC100 ~ 240V AC voltage into a DC voltage output DC24V 1.25A	70
Extension cable	For longer Motor and Driver connection	71
Tachometer	Display speed of Motor output shaft or with Gearhead (Gearhead output shaft)	71

Inst	allation	□60m	nm			Insta	llation	□90m	m			Application	Page
20W	30W	40W	50W	60W	75W	85W	90W	100W	120W	150W	200W		
	•		•			♦				•	•	LCD moving/cleaning, LED testing, wafer/fiber polishing,	16
	•		•			♦				♦	•	vacuum coating, stencil/solder paste printing	. •
♦		♦			•				♦		•	LCD moving/cleaning, LED testing, wafer/fiber polishing,	28
♦		♦			♦				♦		•	vacuum coating, stencil/solder paste printing	
•		♦		•			•					PCB board sending, receiving machines, food/cosmetic filling	40
•		♦		•			•					packaging machines, coating machine, shoe machine	40
•		♦		•			♦					PCB clean machines, CD manufacturing equipment,	50
*		•		•			*					other transmission application	50
•		•		•				•				Bio/medical equipment, drilling	
•		•		•				•				head research, or equipment with DC power suppliers	60
	1	I.				ı	1						



Product Type Index

■ Motor/Driver/Gearhead

Dunale		Land and the same		Installation [
Produ	uct series	Input voltage	20W	30W	40W	50W
BMS	Standard	3 phase AC220~230V		6BM030□-3 BMD030-3 (6D□)		6BM050□-3 BMD050-3 (6D□)
DIVIO	E/M brake	3 phase AC220~230V (E/M Brake: DC24V)		6BM030□-3M BMD030-3 (6D□)		6BM050□-3M BMD050-3 (6D□)
	Standard	Single phase 110~115V	6B020 □ -1 Note 1 DB020-1 (6D □) Note 2		6B040□-1 DB040-1 (6D□)	
BS	Staridard	Single phase AC220~230V	6B020□-2 DB020-2 (6D□)		6B040□-2 DB040-2 (6D□)	
ВО	E/M brake	Single phase 110~115V (E/M Brake: DC24V)	6B020□-1M DB020-1 (6D□)		6B040□-1M DB040-1 (6D□)	
	L/IVI DIAKE	Single AC220~230V (E/M Brake: DC24V)	6B020□-2M DB020-2 (6D□)		6B040□-2M DB040-2 (6D□)	
	Ota in danid	Single phase 110~115V	6B020□-1N SBD020-1N (6D□)		6B040□-1N SBD040-1N (6D□)	
000	Standard	Single AC220~230V	6B020□-2N SBD020-2N (6D□)		6B040□-2N SBD040-2N (6D□)	
SBS	E/M brake	Single phase 110~115V (E/M Brake: DC24V)	6B020□-1NM SBD020-1N (6D□)		6B040□-1NM SBD040-1N (6D□)	
	L/IVI DI ake	Single AC220~230V (E/M Brake: DC24V)	6B020□-2NM SBD020-2N (6D□)		6B040□-2NM SBD040-2N (6D□)	
	Standard	Single phase 110~115V	6B020□-1N UBD020-1N (6D□)		6B040□-1N UBD040-1N (6D□)	
UBS	Staridard	Single AC220~230V	6B020□-2N UBD020-2N (6D□)		6B040□-2N UBD040-2N (6D□)	
OBO	E/M brake	Single phase 110~115V (E/M Brake: DC24V)	6B020□-1NM UBD020-1N (6D□)		6B040□-1NM UBD040-1N (6D□)	
		Single AC220~230V (E/M Brake: DC24V)	6B020□-2NM UBD020-2N (6D□)		6B040□-2NM UBD040-2N (6D□)	
D. 2.0	Standard	DC24V	6B020□-D DBD020-D (6D□)		6B040□-D DBD040-D (6D□)	
DBS	E/M brake	DC24V (E/M Brake: DC24V)	6B020□-DM DBD020-D (6D□)		6B040□-DM DBD040-D (6D□)	

Note 1: Motor $6B020\Box -1...$ etc, please fill shaft type in \Box . $\underline{\mathbb{S}}$: for round shaft type, $\underline{\mathbb{PH}}$ or $\underline{\mathbb{PD}}$ or $\underline{\mathbb{PD}}$: for pinion shaft type.

Note 2 : Gearhead 6B020□-1...etc. please fill gear ratio in □.

			Installation	n □90mm				Page
60W	75W	85W	90W	100W	120W	150W	200W	i ago
		9BM085□-3 BMD085-3 (9D□)				9BM150□-3 BMD150-3 (9D□)	9BM200□-3 BMD200-3 (9D□H)	16
		9BM085□-3M BMD085-3 (9D□)				9BM150□-3M BMD150-3 (9D□)	9BM200□-3M BMD200-3 (9D□H)	
	9B075□-1 DB075-1 (9D□)				9B120□-1 DB120-1 (9D□)		9B200□-1 DB200-1 (9D□H)	
	9B075□-2 DB075-2 (9D□)				9B120□-2 DB120-2 (9D□)		9B200□-2 DB200-2 (9D□H)	28
	9B075□-1M DB075-1 (9D□)				9B120□-1M DB120-1 (9D□)		9B200□-1M DB200-1 (9D□H)	20
	9B075□-2M DB075-2 (9D□)				9B120□-2M DB120-2 (9D□)		9B200□-2M DB200-2 (9D□H)	
9B060□-1N SBD060-1N (9D□)			9B090□-1N SBD090-1N (9D□)					
9B060□-2N SBD060-2N (9D□)			9B090□-2N SBD090-2N (9D□)					40
9B060□-1NM SBD060-1N (9D□)			9B090□-1NM SBD090-1N (9D□)					40
9B060□-2NM SBD060-2N (9D□)			9B090□-2NM SBD090-2N (9D□)					
9B060□-1N UBD060-1N (9D□)			9B090□-1N UBD090-1N (9D□)					
9B060□-2N UBD060-2N (9D□)			9B090□-2N UBD090-2N (9D□)					50
9B060□-1NM UBD060-1N (9D□)			9B090□-1NM UBD090-1N (9D□)					30
9B060□-2NM UBD060-2N (9D□)			9B090□-2NM UBD090-2N (9D□)					
9B060□-D DBD060-D (9D□,9D□H)				9B100□-D DBD100-D (9D□,9D□H)				60
9B060□-DM DBD060-D (9D□)				9B100□-DM DBD100-D (9D□)				00

■ Motor/Driver

		BM	IS		В	3		SBS/L	IBS		DI	BS	
		Name	Net weight(g)	Gross weight(g)	Name	Net weight (g)	Gross weight(g)	Name	Net weight(g)	Gross weight(g)	Name	Net weight(g)	Gross weight(g)
		6BM030S-3	685	1035	6B020S-1,-2	655	1005	6B020S-1N,-2N	655	1005	6B020S-D	655	1005
S t	Round	6BM050S-3	1080	1440	6B040S-1,-2	1050	1410	6B040S-1N,-2N	1050	1410	6B040S-D	1050	1410
a n	shaft	9BM085S-3	1525	1865	9B075S-1,-2	1465	1805	9B060S-1N,-2N	1465	1805	9B060S-D	1525	1865
d a	type	9BM150S-3	2530	2600	9B120S-1,-2	2380	2750	9B090S-1N,-2N	2380	2750	9B100S-D	1525	1865
r		9BM200S-3	2530	2880	9B200S-1,-2	2530	2880	_	-	_	-	_	_
d		6BM030P-3	680	1030	6B020P-1,-2	650	1000	6B020P-1N,-2N	650	1000	6B020P-D	650	1000
s e	Pinion	6BM050P-3	1070	1430	6B040P-1,-2	1040	1400	6B040P-1N,-2N	1040	1400	6B040P-D	1040	1400
r i	shaft	9BM085PD-3	1500	1840	9B075PD-1,-2	1440	1780	9B060PD-1N,-2N	1440	1780	9B060PD-D	1500	1840
e s	type	9BM150PD-3	2500	2570	9B120PD-1,-2	2350	2720	9B090PD-1N,-2N	2350	2720	9B100PD-D	1500	1840
		9BM200P-3	2500	2850	9B200P-1,-2	2500	2850	_	_	_	_	_	_
E	Round	6BM030S-3M	1085	1435	6B020S-1M,-2M	1055	1405	6B020S-1NM,-2NM	1055	1405	6B020S-DM	1055	1405
e		6BM050S-3M	1480	1840	6B040S-1M,-2M	1450	1810	6B040S-1NM,-2NM	1450	1810	6B040S-DM	1450	1810
t r		9BM085S-3M	2275	2615	9B075S-1M,-2M	2215	2555	9B060S-1NM,-2NM	2215	2555	9B060S-DM	2275	2615
o m		9BM150S-3M	3280	3350	9B120S-1M,-2M	3130	3500	9B090S-1NM,-2NM	3130	3500	9B100S-DM	2275	2615
a g n		9BM200S-3M	3280	3630	9B200S-1M,-2M	3280	3630	_	_	_	_	_	_
e		6BM030P-3M	1080	1430	6B020P-1M,-2M	1050	1400	6B020P-1NM,-2NM	1050	1400	6B020P-DM	1050	1400
i C	Pinion	6BM050P-3M	1470	1830	6B040P-1M,-2M	1440	1800	6B040P-1NM,-2NM	1440	1800	6B040P-DM	1440	1800
b	shaft type	9BM085PD-3M	2250	2590	9B075PD-1M,-2M	2190	2530	9B060PD-1NM,-2NM	2190	2530	9B060PD-DM	2250	2590
r a k	31	9BM150PD-3M	3250	3320	9B120PD-1M,-2M	3100	3440	9B090PD-1NM,-2NM	3100	3440	9B100PD-DM	2250	2590
e		9BM200P-3M	3250	3600	9B200P-1M,-2M	3250	3600	_	_	_	_	_	_
		BMD030-3	840	1300	DB020-1,-2	660	950	SBD020-1N,-2N SBD040-1N,-2N			DBD020-D	210	470
		BMD050-3	840	1300	DB040-1,-2	660	960	SBD060-1N,-2N	530	830	DBD040-D	210	470
Driv	/er	BMD085-3	840	1300	DB075-1,-2	670	990	SBD090-1N,-2N UBD020-1N,-2N			DBD060-D	290	530
		BMD150-3	840	1560	DB120-1,-2	680	990	UBD040-1N,-2N UBD060-1N,-2N	520	760	DBD100-D	290	530
		BMD200-3	840	1560	DB200-1,-2	680	1270	UBD090-1N,-2N			_	_	_

^{*}Motor net weight : Motor body+ rubber insulated cables 600mm ; Motor gross weight : Motor body+ rubber insulated cables 600mm+pack

Gearhead

5.0	6D□		6D□N		9D□		9D□H		9D□N		9D□U	
Ratio	Net weight(g)	Gross weight(g)	Net weight (g)	Gross weight (g)								
3~20	300	400	295	395	860	1170	860	1170	810	1120	835	1145
25~100	325	425	320	420	1125	1490	1125	1490	1075	1440	1100	1465
120~360	365	470	360	460	1265	1630	1265	1630	1215	1580	1240	1605

^{**}Gearhead net weight : Gearhead body ; Gearhead gross weight : Gearhead body+screw package+pack

Accessories

D/A sw	D/A switching adaptor Power supply			ly	Extension ca	able-standard	Extension of	cable-flexible	Tachometer			
Name	Net weight (g)	Gross weight (g)	Name	Net weight(g)	Gross weight (g)	Name	Net /Gross (g) weight (g)	Name	Net Gross weight (g)	Name	Net weight (g)	Gross weight (g)
						CB-010	110	CB-010F	130			
					CB-020	210	CB-020F	240				
TRDAC	180	180 230	230 PA30-24-F	4-F 121	182	CB-030	300	CB-030F	350	TMR-F	110	170
INDAG	100	250	17100 241			CB-050	500	CB-050F	570	TIVITY	110	170
						CB-070	700	CB-070F	800			
						CB-100	1000	CB-100F	1200			

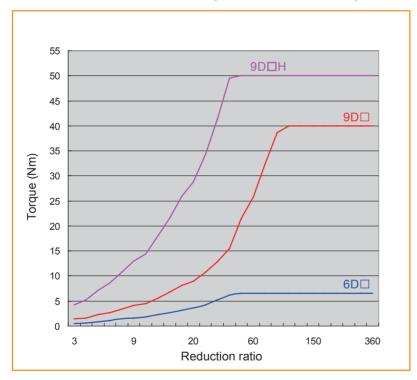
[%]Driver net weight : Driver body+terminals+foot ;

Driver gross weight: Driver body+terminals+foot+variable resistor+ regenerative resistor(Only BMD150W/200W,BS200W attached)+Noice filter (DBS series no attached this part)+pack

■ Gearhead transmission efficiency

						1							
Ratio	3	3.6	5	6	7.5	9	10	12.5	15	18	20		
6D□ 9D□ 9D□H		Efficiency 90%											
Ratio	25	;	30	36	50		60	75	90)	100		
6D□ 9D□ 9D□H		Efficiency 86%											
Ratio	120		150	180)	200		250	300		360		
6D□ 9D□ 9D□H	Efficiency 81%												

■ Gearhead maximum permissible torque



Product series	Maximum permissible torque
6D□ series	6.5Nm
9D□ series	40Nm
9D□H series	50Nm

Output torque after linking Gearhead

After connecting Gearhead output torque is caculated as following:

Output torque

T_G: Output torque of Gearhead terminal

TM: Motor rated torque

i : Gearhead reduction ratio

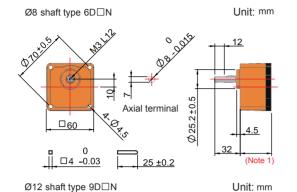
η : Gearhead transimission efficiency

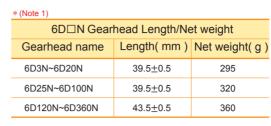
% If the calculated value of TG (gear side output torque) < Gearhead maximum allowable torque value, at this time, after connecting Gearhead output torque: the value is TG value.

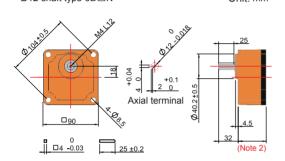
If the calculated value of TG (gear torque output side)> Gearhead maximum allowable torque value, at this time, after connecting reducer output torque: please refer to the maximum allowable torque value Gearhead prevail.

Brushless Gearhead specification

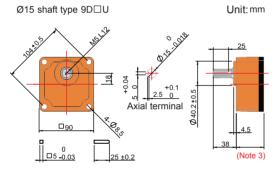
■ 【Parallel shaft-General-type】 Dimemsion size of Ø8 × Ø12 × Ø15 shaft Gearhead





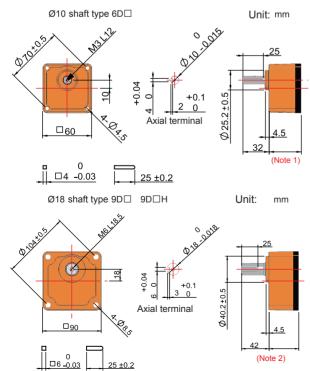


* (Note 2)							
9D□N Gearhead Length/Net weight							
Gearhead name	Length(mm)	Net weight(g)					
9D3N~9D20N	45.5±0.5	810					
9D25N~9D100N	58.5±0.5	1075					
9D120N~9D360N	64.5±0.5	1215					



* (Note 3)							
9D□U Gearhead Length/Net weight							
Gearhead name	Length(mm)	Net weight(g)					
9D3U~9D20U	45.5±0.5	835					
9D25U~9D100U	58.5±0.5	1100					
9D120U~9D360U	64.5±0.5	1240					

■ [Parallel shaft-General-type] Dimemsion size of Ø10 · Ø18 shaft Gearhead



* (Note 1)		
6D□ Gearh	ead Length/Net	t weight
Gearhead name	Length(mm)	Net weight(g)
6D3~6D20	39.5	300
6D25~6D100	39.5	325
6D120~6D360	43.5	365

* (Note 2)						
9D□ Gearhead Length/Net weight						
Gearhead name	Length(mm)	Net weight(g)				
9D3~9D20	45.5	860				
9D25~9D100	58.5	1125				
9D120~9D360	64.5	1265				

9D□H Gearhead Length/Net weight							
Gearhead name	Length(mm)	Net weight(g					
9D3H~9D20H	45.5	860					
9D25H~9D100H	58.5	1125					
9D120H~9D360H	64.5	1265					

^{*} Figure above dimensions tolerance values are not shown on normal manufacturing tolerances, the control mode refer to P.12, other marked tolerance values marked mainly by drawing.



■ [Right angle] Gearhead

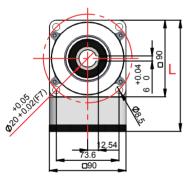
Specification

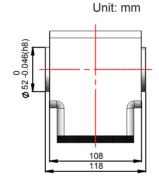
Туре		Hallow shaft 9VD□(H) / Uniaxial-solid shaft VD□A(H) / Biaxial-solid shaft 9VD□B(H)												
Ratio	7.5	7.5 9 12.5 15 18 20 25 30 36 50 60 75 90								100				
Transmission efficiency	70% 75% 80% 85%													
Rotation direction		Axial rotation direction opposite to the Motor body												
Allowable load inertia	And parallel shaft gear specifications identical (due to limited Motor shaft strength, please refer to the specification of every series of Motor)													
Туре	ŀ	Hallow shaft 9VD□(H) / Uniaxial-solid shaft VD□A(H) / Biaxial-solid shaft 9VD□B(H)												
Ratio	12	20	15	50	18	80	20	00	2	50	3	00	36	30
Transmission efficiency	90%													
Rotation direction	Axial rotation direction same to the Motor body													
Allowable load inertia	And parallel shaft gear specifications identical (due to limited Motor shaft strength, please refer to the specification of every series of Motor)													

^{*} Gearhead 9VD□(H)/9VD□A(H)//9VD□B(H),Please fill in the number of gear ratio in□

◆ Dimension

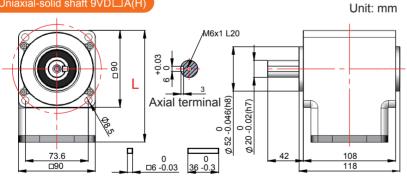




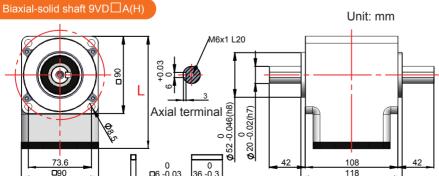


Ratio	LengthL(mm)	Weight(g)
7.5~100	130.6	3000
120~360	143.6	3500

Uniaxial-solid shaft 9VD□A(H)



Ratio	Length <mark>L</mark> (mm)	Weight(g)
7.5~100	130.6	3370
120~360	143.6	3870



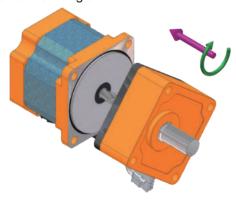
	Ratio	Length <mark>L</mark> (mm)	Weight(g)
_	7.5~100	130.6	3450
	120~360	143.6	3950

^{*}Figure above size is not marked tolerance values are among the general manufacturing tolerances, the control mode, refer to P.12, others have marked tolerance values marked according to the main drawing.

Brushless Motor and Gearhead combination fixation

■ When the Motor and Gearhead combination, set within the Motor and gear unit opposite edge, to avoid Motor shaft and the gear teeth cut portion of a metal plate or gear collide with each other, and do according to the following sequence diagram combine assembly, in order to avoid causing improper assembly gear bumps.

(Step 1.) Motor and Gearhead distance of about 35mm, showed 45 $^{\circ}$ angle.



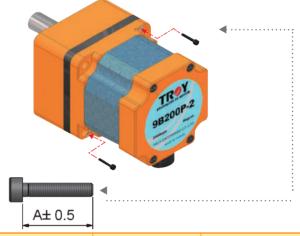
(Step 2.) Gearhead clockwise screwed with the Motor combination, the Motor and Gearhead stick flat, showed 35 $^{\circ}$ angle.



(Step 3.) Motor gear stick flat end surface, and clockwise rotation of ascertaining that the Motor and Gearhead have really engaged.



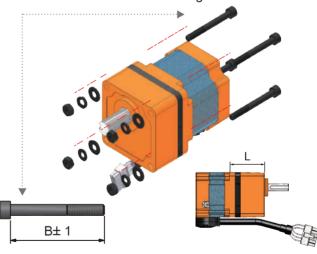
(Step 4.) Lock into the Motor and Gearhead fixing two small screws.



Gearhead Name	Screws specification	Small screw Length (A)mm
6D□	M2P0.4	8
9D□	M3P0.5	12
9D□H	M3P0.5	12

©Fixed with small screws to the Gearhead included product

(Step 5.) Panel mounting method : the lock into the Motor and Gearhead mounting 4 screws.



Combood Name	Screws	Small screw Length	Gearhead + Motor cover
Gearhead Name	specification	(B)mm	(L)mm
6D3(N)~6D100(N)	M4P0.7	60	47.5
6D120(N)~6D360(N)	10141 0.7	70	51.5
9D3(N)(U)~9D20(N)(U)	M8P1.25	75	56.5
9D25(N)(U)~9D100(N)(U)		90	69.5
9D120(N)(U)~9D360(N)(U)		95	75.5
9D3H~9D20H		75	56.5
9D25H~9D100H	M8P1.25	90	69.5
9D120H~9D360H		95	75.5

Mounting screws are included for the Gearhead products

В

D

Notes on the Motor Installation

- 1.Ambient temperature0ĭC~+40ĭC, relative humidity below 85%.
- 2. Avoid environment of direct sunlight, moisture, oil, and dust.
- 3. Avoid intense shock and vibration to the occasion, as well as environments of gas explosion, corrosive gas.
- 4.Installation: Motor body may be mounted in a horizontal or vertical direction. (But the Motor cable extraction direction cannot be changed)
- 5. Note that when you install and institutions linked to the center position. When the position of if accurate, will produce vibration motor or shorten the service life of gear bearings, mechanical fatigue will lead to more serious damage.
- 6. When installing couplings, pulleys, gears and other transmission mechanism on the Motor or gearbox axis, the axis is not available on tap directly mounted to the tool, otherwise it will cause the Motor or the Gearhead bearing damage.
- 7 Combined with the load fixation

Motor shaft: Right angle cut planar manner can be used directly two fixing screws a 90 degree angle, the locking mechanism is fixed to the axis.

Gearhead shaft: Using keyway fixed way, h7 tolerance design, please reserve when installation space agency "parallel button" assembly and mounting screw mechanism is fixed to the axis.

8. No tolerance values marked on the external dimensions are a general machining tolerances, the control mode in the following table:

> Standard tollerance level IT14 unit: mm

Size	Tolerance				
>0	0.3				
>6	0.5				
>30	0.7				
>80	0.9				
>120	1.0				
>180	1.2				
>250	1.3				
>315	1.4				
>400	1.6				
>1000	2.0				

- * Detail axis dimensions, please refer to "Motor overall dimensions."
- *Our company is to promote and improve product performance, product design modifications carried out will not be notified individually, if you need more detailed information, please contact each business unit.



Brushless Specification certificates

Products

1. ← (€

: Europe safety certification



The machine selling to the Europe must accordance with Europe safety standards and mark on the CE or TÜV.

2. USA and Canada safety certification

Regconized by cTÜVus Rheinland and indicated the product meets American & Canadian safety requirements. The product that can selling to the USA and CANADA.

3.♦ (**(((**)) : China compulsory certification system certificated

All the products import/export to the China for selling or producing. They must accordance with CCC certificated and marked on CCC.

4.♦ RoHS

: Restriction of Hazardous Substances



RoHS, the European Union Directive 2002/95/EC, on the restriction of the use of certain hazardous substance apply to any equipment for use or import into an EU member state beginning July 2006. The restricted substance include; Lead(Pb), Mercury(Hg), hexavalent Chromium Cr(VI), Polybrominated biphenyls-PBB, Polybrominated diphenyl ether(PBDE) and Cadmium(Cd). Electrical and electronics equipment must conform to the maximum concentration value.

(Request for the RoHS certification, please contact with the sales representatives.)

5. ◆ IP54 : IP (or "Ingress Protection") ratings are defined as levels of sealing effectiveness of electrical enclosures against intrusion from foreign bodies (tools, dirt etc) and moisture. IP5X First Digit (intrusion protection) Protected against dust under normal condition that may harm equipment.

> IPX4 Second Digit (moisture protection) Protected against water spray from all directions at 10liter/min. for 10 minutes.











(1)

(2)

В

Motor

BM

200

Output power

Shaft style

Installation size

6 __60mm \square 90mm 9

Product series

BS В SBS UBS DBS series

BM BMS series

020 20W 085 030 30W 090 040 40W 050 50W

85W S Round shaft 90W Gear shaft 100 100W Gear shaft PH Gear shaft 120 120W

Input power voltage Single phase AC110~115V 1 Single phase 2 AC220~230V

Three phase 3 AC220~230V D DC24V

E/M Brake Max. speed

2500r/min None (and) above 2000r/min

Economy None M E/M brake

Driver

200

020

030

040

050

060

075

200

Output power

20W

30W

40W

75W

060

075

60W

75W

150 150W

200 200W

Input power voltage

Single phase AC110~115V Single phase 2 AC220~230V Single phase

AC110~115V (For SBS **1N** 50W and UBS) 60W Single phase

AC220~230V 2N (For SBS and UBS) Three phase

AC220~230V

DC24V

085 85W 3 090 90W D

100 100W 120 120W 150 150W

200W

Gearhead

Brushless

5

Gear ratio

н

Strength

None standard type

High strength type

Installation size

Motor only \Box 60mm

□90mm 9

3 1/3 36 1/36 3.6 1/3.6 50 1/50 5 1/5 60 1/60 6 1/6 75 1/75 1/7.5 7.5 90 1/90 9 1/9 1/100 100

1/10 1/120 10 120 12.5 1/12.5 150 1/150 1/15 1/180 15 180 1/18 1/200 18 200 20 1/20 250 1/250 25 1/25 300 1/300

1/30

30

360 1/360

BMD

Product series BMD BMS series

DB BS series

SBD SBS series **UBD** UBS series

DBD DBS series



Products





XAbove are standard models, all BMS, BS, SBS, UBS, DBS series have E/M brake types, if needs please contact sales representatives.



BMS series

-Three phase power supply with stable speed demand

Page
17 System wiring diagrams

18 Specifications and characteristics of Motor/Driver

19 Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD2)

20 Motor allowable radial load/axial load

21 Speed - Torque characteristic diagrams

21 Driver panel functions and wiring instructions

23 Motor electromagnetic brake wiring instructions

24 Dimensions - Motor/Gearhead

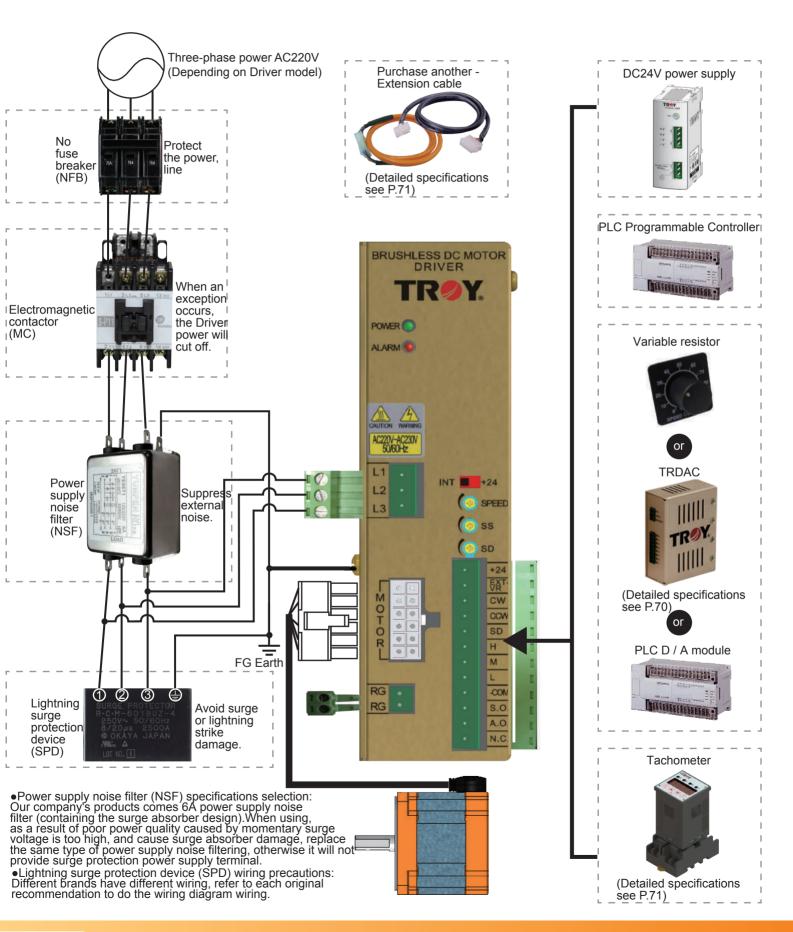
26 Dimensions - Driver

27 Dimensions - Variable resistor/Regenerative resistance/Power supply noise filter



DC brushless Motor-BMS series

■ System wiring diagrams



■ Specifications and characteristics of Motor/Driver

■ Spe	cifications and c	haracterist	ics of Moto	r/Driver			TRøy-		
	tput power	30W	50W	85W	150W	200W			
Round shaft Motor (M: E/M brake type)		6BM030S-3(M)	6BM050S-3(M)	9BM085S-3(M)	9BM150S-3(M)	9BM200S-3(M)	Chara of		
Pinion sha	aft Motor (M: E/M brake type)	6BM030P-3(M) 6BM050P-3(M		9BM085PD-3(M)	9BM150PD-3(M)	9BM200P-3(M)	acteris Motor		
Motor spe	ecification certificates		, A c Us	RoHS @ IP5	i 4	I	tics P		
Driver		BMD030-3	BMD050-3	BMD085-3	BMD150-3	BMD200-3	roduct		
Driver sp	ecification certificates		, A c Us	CE E RoHS) ©	I	index		
	vpe 3 Phase Max. Current (A)	1.2	1.2	1.2	1.3	1.5	Characteristics Product index Product names Product weight of Motor		
voltage 50/6	20~230V 0 HZ Rated Current (A)	0.3	0.5	0.7	1	1.3	ct name		
Starting To	orque (Nm)	0.13	0.22	0.37	0.64	1	es Pro		
Rated Tord	que (Nm)	0.1	0.17	0.28	0.49	0.8	duct v		
Allowable	load inertia GD²(Kgcm²)	7.85	12.8	18.7	31.4	113	veight		
* - 0	Input line voltage(V)	DC	D24	DC	C24	DC24			
Only E/have E	Consumption power(W)	6	.5	7	.5	7.5	Gea		
Input line voltage(V) Consumption power(W) Maintenance(Nm) Attraction time(ms) Release time(ms)		0	.3	0	.5	0.5	Gearhead		
ke serie	Attraction time(ms)		30		3	33	ad Installation		
S	Release time(ms)	8	37	ę	95	95	Inst		
Speed con	ntrol range(r/min)	250~3000 250~2500							
	To load	±0.05%Max. at 3000r/min(200W: at 2500r/min), no load~rated load.							
Speed var	· ·	±0.05% Voltage variation ±15%, at 3000r/min(200W: at 2500r/min), no load.							
	To Temperature	250~3000 250~2500							
Slow start/	Slow down time set up	30~150W:0 5~15coc Motor from 0~3000r/min or from 0~3000r/min							
		●Control from external variable resistor (resistance 20KΩ) ●Control from external DC voltage							
Speed cor	ntrol method	200W:0.8~15sec, Motor from 0~2500r/min or from 0~2500r/min •Control from external variable resistor (resistance 20ΚΩ) •Control from internal variable resistor (also work with external variable resistor for 2 sections speed switch control) •Work with D/A speed setter TRDAC (Option)							
		Option) Option) Option)							
Signal inpu	ut/output methods	●Transistor Open Collector output interface							
		■ Zero point control, can connect to PLC or Transistor, Relay type I/O module ■ Within speed control range, motor sets Flat Torque output S							
Function		Can operate in pai150/200W have re	generative resistor c	onnection terminals,	can based on custon e regenerated energy	ners' load y (regenerated energy	8 S U		
		absorption prote	ction : start operatior	at up down, Coiling	or inertial load opera	tion)	B S		
		·	•		y, Driver alarm signals	s output	D B		
		Overload protection: starts when Motor activate torque for more than 5 sec Over heat protection: starts when Driver internal heat sink over 80°C							
Protection function		Over voltage protection: (1) starts when up down, coiling or over inertial load (2) starts when driver input AC voltage appears transient high voltage Transient over current protection: When driver AC input power connects in parallel with large power for Power on, easy activates by large transient current							
		Transient over current protection: When driver AC input power connects in parallel with large power for Power on, easy activates by large transient current							
		Lack of phase protection: starts when motor power cable has bad connection, broken cable or feedback signal suffers interference							
Insulation	impedance			t, power, F.G grounding	g, I/O terminal resistan	ice value is over 100MΩ	Motor selection		
Insulation	high voltage	Power and F.G conconnectors pass with	nect to ground, termi th 3KV/60Hz high vo	nals pass with 1.8KV Itage for 1 minute, no	/60Hz high voltage, postportion	power and I/O	ection		
Ambient te	emperature/Humidity range	0~+40°C, under 85% relative humidity (avoid dust and erosion, combustion gas)							



BMS series

■ Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD²)

Gear	ratio	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30
Speed range	High speed	1000	883	600	500	400	333	300	240	200	166	150	120	100
(r/min)	Low speed	83.4	69.5	50	41.7	33.4	27.8	25	20	16.7	13.9	12.5	10	8.4
Allowable orque (Nm)	6BM030P-3(M) + 6D□	0.27	0.32	0.45	0.54	0.68	0.81	0.9	1.1	1.4	1.6	1.8	2.2	2.6
Allowable iner	tia load GD ² (kgcm ²)	3.53	5.09	9.81	14.1	22.1	31.8	39.3	61.3	88.3	127	157	245	353
Allowable orque (Nm)	6BM050P-3(M) + 6D□	0.45	0.54	0.74	0.89	1.1	1.3	1.5	1.9	2.2	2.7	3	3.5	4.3
Allowable iner	tia load GD² (kgcm²)	5.77	8.31	16.0	23.1	36.1	52.0	64.2	100	144	208	257	401	577
Allowable orque (Nm)	9BM085PD-3(M) + 9D□	0.76	0.91	1.3	1.5	1.9	2.3	2.5	3.2	3.8	4.5	5	6	7.2
Allowable iner	tia load GD ² (kgcm ²)	30.0	43.2	83.2	120	187	270	333	520	749	1079	1332	2081	2997
Allowable orque (Nm)	9BM150PD-3(M) +9D□	1.3	1.6	2.2	2.6	3.3	4	4.4	5.5	6.6	7.9	8.8	10.5	12.6
Allowable inert	tia load GD² (kgcm²)	50.2	72.3	139	201	314	452	558	871	1254	1806	2230	3484	5018
	High speed	833	694	500	416	333	277	250	200	166	138	125	100	83
Speed range (r/min)	Low speed	83.4	69.5	50	41.7	33.4	27.8	25	20	16.7	13.9	12.5	10	8.4
Allowable orque (Nm)	9BM200P-3(M) + 9D□H	2.2	2.6	3.6	4.3	5.4	6.5	7.2	9	10.8	13	14.4	17.2	20.6
Allowable iner	rtia load GD² (kgcm²)	181	260	501	722	1128	1624	2006	3134	4512	6498	8022	12534	18050

Gea	r ratio	36	50	60	75	90	100	120	150	180	200	250	300	360
Speed range	High speed	83	60	50	40	33	30	25	20	16	15	12	10	8
(r/min)	Low speed	7	5	4.2	3.4	2.8	2.5	2.1	1.7	1.4	1.3	1	0.9	0.7
Allowable torque (Nm)	6BM030P-3(M) + 6D□	3.1	4.3	5.2		6.5					6.5			
Allowable inert	tia load GD ² (kgcm ²)	509			625						625			
Allowable torque (Nm)	6BM050P-3(M) + 6D□	5.1			6.5			6.5						
Allowable inerti	ia load GD ² (kgcm ²)	625				625								
Allowable torque (Nm)	9BM085PD-3(M) +9D□	8.7	12	14.4	18.1	21.7	24.1	27.2	34			40		
Allowable inerti	ia load GD ² (kgcm ²)	4320	8320		110	00					11000			
Allowable torque (Nm)	9BM150PD-3(M) +9D□	15.2	21.1	25.3	31.6	37.9	40				40			
Allowable inert	tia load GD² (kgcm²)	7230			11000						11000			
		00	50	4.4	0.0	0.7	0.		4.0	4.0	4.0	40		
Speed range (r/min)	High speed	69	50	41	33	27	25	20	16	13	12	10	8	6
(1/111111)	Low speed	7	5	4.2	3.4	2.8	2.5	2.1	1.7	1.4	1.3	1	0.8	0.7
Allowable torque (Nm)	9BM200P-3(M) + 9D□H	24.8	34.4	41.3		50		50						
Allowable iner	tia load GD² (kgcm²)	25991			45000						45000			

^{*}Gearhead 6D□/9D□/9D□H, please fill gear ratio in □.

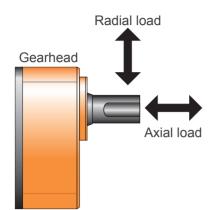
^{*} In above table stands for after installation of Gearhead, the axis rotation direction is reversed with Motor axis direction; without marking stands for the same direction as Motor axis rotation.

^{*1}Nm = 10.197Kgcm.

^{*} The Gearheads of all series have ROHS @ certificate.

^{*}Also available orthogonal Gearhead: hollow shaft type $9VD\Box(H)$, the solid single shaft type $9VD\Box A(H)$, the solid biaxial shaft type $9VD\Box B(H)$, and size please refer to P.10.

■ Motor allowable radial load/axial load



- (1) Radial load (hanging load): loading is vertical to gearhead axis power output
- (2) Axial load (thrust load): loading is in the direction of gearhead axis power output

◆ Round shaft type

Model	Permissible overhun	Permissible thrust load			
Model	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)		
6BM030S-3(M)	8	9	Permissible axial loading, not more than 1/2 of motor weight.		
6BM050S-3(M)	8	9	But please try to avoid applying force in the horizontal direction		
9BM085S-3(M)	13	15	(axial) of motor shaft, when exceeds that will reduce motor service life.		
9BM150S-3(M)	16	17	If axial loading is needed, we recommend applying indirect		
9BM200S-3(M)	16	17	transmission, such as: couplings, belts, chains, etc		

◆ Pinion shaft type (Gearhead attached)

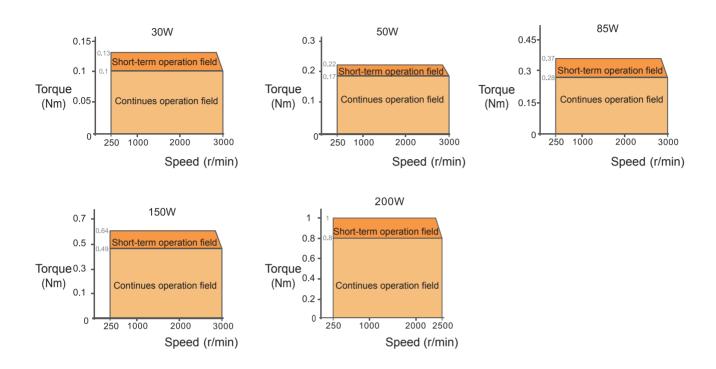
		Permissible overhu	ing load (Unit: Kg f)	Permissible thrust load	
Model	Gear ratio	Gear ratio 10mm from output shaft front 20mm		(Unit: Kg f)	
6BM030P-3(M)	3, 3.6, 5	10	15		
+ 6D□ 6BM050P-3(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	15	20	4	
+ 6D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	20	30		
9BM085PD-3(M)	3, 3.6, 5	30	40		
+ 9D□ 9BM150PD-3(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	40	50	15	
+ 9D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	50	65		
	3, 3.6, 5	30	40		
9BM200P-3(M) + 9D□H	6, 7.5, 9, 10, 12.5, 15,18, 20	40	50	15	
	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	50	65		

^{*}Gearhead 6D□/9D□/9D□H, please fill gear ratio in □.

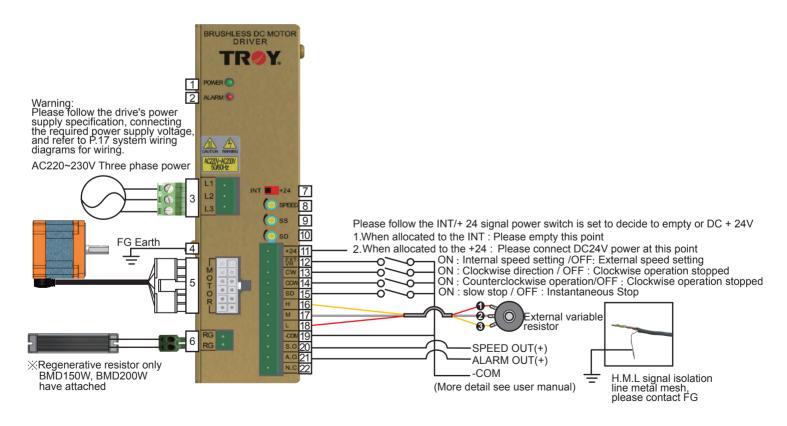


BMS series

■ Speed - Torque characteristic diagrams



■ Driver panel functions and wiring instructions

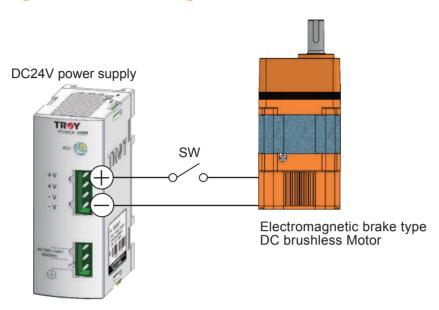


Number	Panel marked	Function	Explanation				
1	POWER	Power indicator	When input power LED (green) lights				
2	ALARM	Unusual indicator	Overload, overheating, overvoltage, instantaneous overcurrent, under equal any protective function will activate LED (red) lights				
3	L1 L2 L3	Power voltage input terminal	AC power voltage input connecting L1, L2, L3 : three-phase power type				
4	FG	Power ground terminal	Power ground connecting				
5	MOTOR	Motor wiring connector	Motor and Driver connecting				
6	RG	No connecting Regenerative resistor connection terminal	30/50/85W: do not make any link (no effect) 150/200W: According to customer load conditions selected external regenerative resistance, regenerative energy consumption				
7	INT/+24	Signal power switch	INT: When Driver is controlled using the internal power supply DC24V (for relays, switches and control applications) +24: When using an external power supply DC24V control (PLC control applicable to the case)				
8	SPEED	Internal speed setting button	30~150W speed control range : 250~3000r/min 200W speed control range : 250~2500r/min				
9	SS	Slow start time setting button	30~150W: 0.5~15sec 200W: 0.8~15sec				
10	SD	Slow stop time setting button	30~150W: 0.5~15sec 200W: 0.8~15sec				
11	+24	Signal input power DC24V	When an external DC24V power control, external DC24V power connects to the terminal				
12	EXT-VR	Speed setting switch to select the input mode	External/Internal speed setting mode switch selection				
13	CW	Clockwise operation input	Clockwise operation/stop switch input				
14	CCW	Counterclockwise operation input	Counterclockwise operation/stop switch input				
15	SD	Stop mode switch to select the input	Slow (depending on SD button to set the time for the slow stopped)/instantaneous stop mode select switch				
16	Н	•	An external connection terminal variable resistor or external DC voltage (0 ~ 5V) control of				
17	М	External speed setting input	30~150W speed control range : 250~3000r/min				
18	L		200W speed control range : 250~2500r/min				
19	-COM	Control signal grounding	GND contact inputs and outputs a control signal common ground line, and the external power DC24V				
20	S.O.	Speed signal output	Detecting Motor speed using : 30 ~ 200W digital signal output 24 pulse/rev				
21	A.O.	Abnormal warning signal output	Overload, overheating, overvoltage, overcurrent moment, when any one of the less tequal protection function is activated, Motor will stop naturally, and outputs an abnormality warning signal				
22	N.C.	No connection	Do not make any connection				



BMS series

■ Motor electromagnetic brake wiring instructions



Operation instruction

Motor start/Motor stop with external electromagnetic brake operating procedures: Motor start: Must energize external electromagnetic brake before the Motor starts

Step:	External electromagnetic brake power ON
	External dissiliating field brake power ore
	Attracting waiting time (This is the time of the external electromagnetic brake actuation, the purpose: to keep the force is released)
	Motor Driver starting signal ON
	Motor starts running
Motor Stop :	The Motor is stopped before the operation do not yet fully external electromagnetic brake power.
Step:	Motor Driver stop signal ON
	Wait 0.2sec (reference value, this is the operation of the Motor to a complete stop time)
	External electromagnetic brake power is turned OFF
	Waiting for the release time (This is the external electromagnetic brake actuation time, purpose: To generate holding force)
	Motor stopped (a holding force)

Precautions

- 1. This series of external electromagnetic brake using the brake power is part of the hold-type.

 2. External electromagnetic brake is designed to allow the Motor stops when the holding force has to be used as a safety brake, electromagnetic brake, do not use this as a Motor positioning or emergency brake applications.
- or emergency brake applications.

 3. Always to pull the Motor before starting the external electromagnetic brake energized (means no brakes); Motor stopped before the operation do not yet fully external electromagnetic brake power (expressed brakes).
- 4.External electromagnetic brake suction time and release time value refer to the product specification.
 5.Motor brakes to stop for about 0.2sec (test conditions in the Motor no-load speed 3000r / min, the electromagnetic brake is energized, the brake actuator signal ON time of the Driver, this time as a reference base, but the actual length of time will stop according to the inertia load or frictional load ... different load patterns and has fluctuated.

Weight: 1470g+W

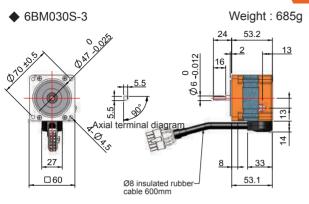
Unit: mm

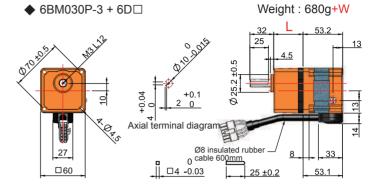
Round shaft type

■ Dimensions - Motor/Gearhead

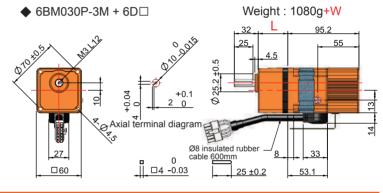
Pinion shaft type

30W/□60mm



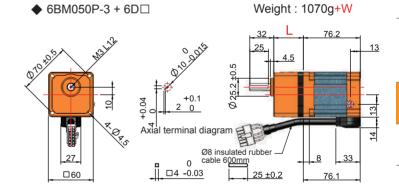


6BM030S-3M Weight:1085g 970,195 □60 Ø8 insulated rubber cable 600mm 53.1



50W/□60mm

Weight: 1080g ◆ 6BM050S-3 970,1013 Axial terminal diag 27 □ 60 76.1 Ø8 insulated rubber cable 600mm



6BM050P-3M + 6D□

6BM050S-3M Weight: 1480g 118.2 070,505 0-0.015 27 Ø8 insulated rubber cable 600mm

3 Axial terminal diagran Ø8 insulated rubber cable 600mm 4 -0.03

* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

* 6BM pinion shaft type 6D3-6D360, Gearhead length L and weight W specification as following:

	Model	6D3~6D20	6D25~6D100	6D120~6D360
Gearhead	Length L (mm)	39.5	39.5	43.5
	Weight W (g)	300	325	365



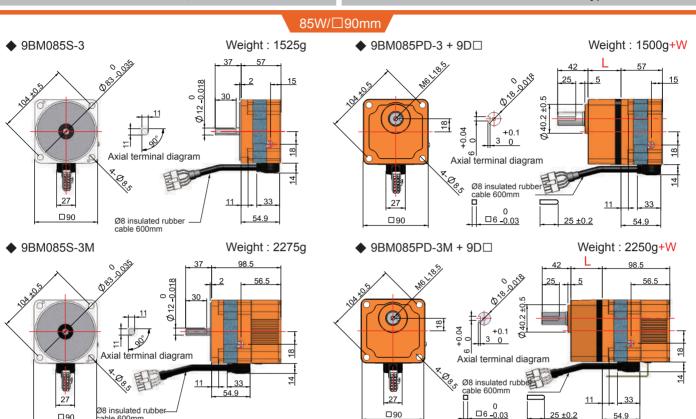
■ Dimensions - Motor/Gearhead

Unit: mm

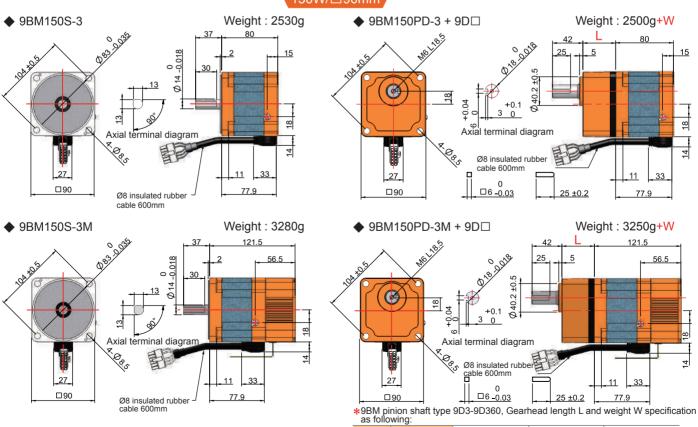
Round shaft type

Pinion shaft type

25 ±0.2



150W/□90mm



* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

9D3~9D20 Model 9D25~9D100 9D120~9D360 45.5 58.5 64.5 Gearhead Length L (mm 860 1125 1265 Weight W (g)

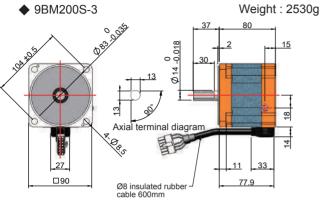
Unit: mm

Weight: 840g

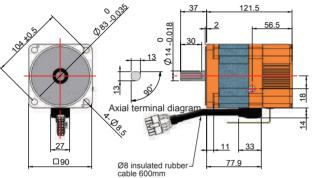
■ Dimensions - Motor/Gearhead

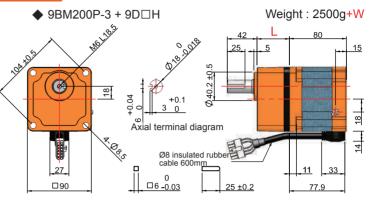
Round shaft type Pinion shaft type

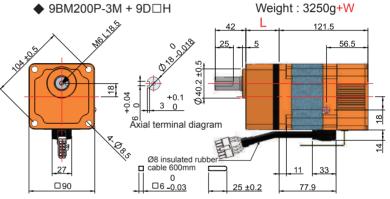
200W/□90mm



◆ 9BM200S-3M Weight: 3280g







* 9BM pinion shaft type 9D3-9D360, Gearhead length L and weight W specification as following:

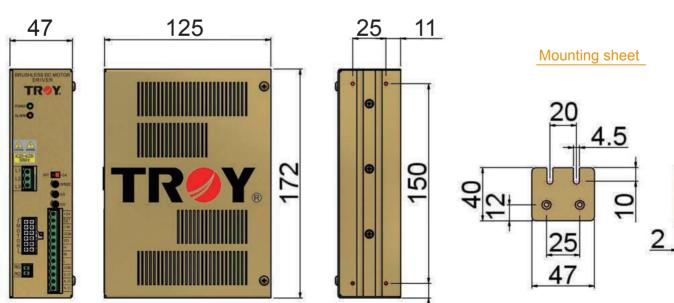
40 10110	9.			
	Model	9D3H~9D20H	9D25H~9D100H	9D120H~9D360H
Gearhead	Length L (mm)	45.5	58.5	64.5
	Weight W (g)	860	1125	1265

■ Dimensions - Driver

Names: BMD030-3 / BMD050-3

BMD085-3 / BMD150-3 / BMD200-3

Dimensions are common

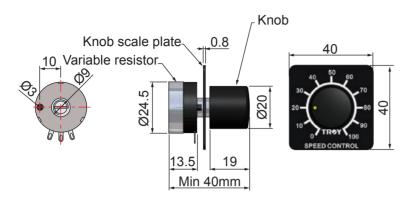


* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.



BMS series

■ Dimensions - Variable resistor



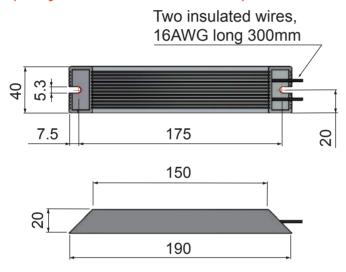
■ Dimensions - Regenerative resistance dimensions (Only 150 / 200W attached)

Weight: 260g

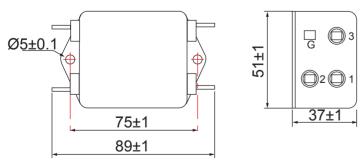
Weight: 170g

Weight: 30g

Unit: mm



■ Dimensions - Power supply noise filter



* Figure above dimensions tolerance values are not label on general maching tolerances, the control mode refer to P.12, others have marked tolerance values according to the drawing labeled based.



BS series

-For high stable speed demand

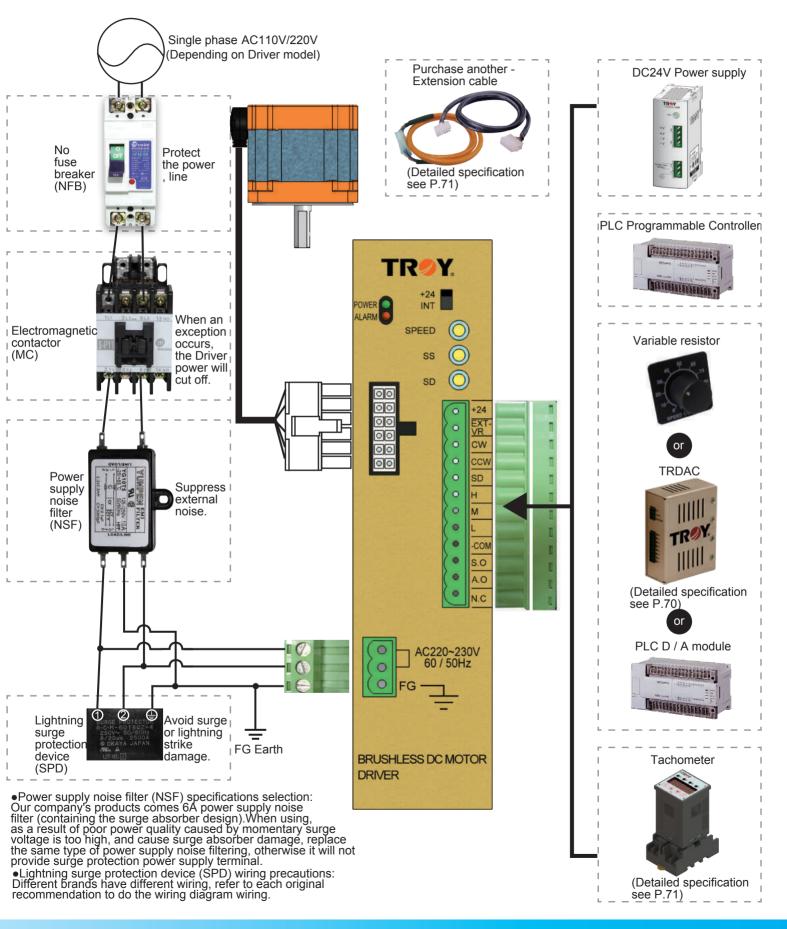
<u> 29</u>	System wiring diagrams	
30	Specifications and characteristics of Motor/Driver	
31	Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (G	3D
32	Motor allowable radial load/axial load	

- 33 Speed Torque characteristic diagrams
- 33 Driver panel functions and wiring instructions
- 35 Motor electromagnetic brake wiring instructions
- 36 Dimensions Motor/Gearhead
- 38 Dimensions Driver
- 39 Dimensions Variable resistor/Regenerative resistance/Power supply noise filter



DC brushless Motor- BS series

System wiring diagrams





■ Specifications and characteristics of Motor/Driver

Motor output power			ver	20W	40W	75W	120W	200W		
		haft Motor (Maft Motor (Ma	M: E/M brake type) E/M brake type)	6B020S-□(M) (Note1) 6B020P-□(M)	6B040S-□(M) 6B040P-□(M)	9B075S-□(M) 9B075PD-□(M)	9B120S-□(M) 9B120PD-□(M)	9B200S-□(M) 9B200P-□(M)		
Mo	tor sp	ecification	-1 Type		cous RoHS ⊕ IP54					
certificates -2 Type			-2 Type		Œ	(((°) RoHS (e)	P54			
Dri	ver			DB020-□	DB040-□	DB075-□	DB120-□	DB200-□		
Dri	ver sp	ecification of	certificates		, A c us	CE (A) RoH	s e			
⊒			Max. Current (A)	2.8	2.8	2.8	3.3	4.9		
Input power voltage	AC110 50/60)~115V HZ	Rated Current (A)	0.65	1.2	1.95	2.7	4		
wer v			Max. Current (A)	1.6	1.6	1.6	1.75	2.8		
oltage	AC220 50/60	0~230V HZ	Rated Current (A)	0.35	0.65	1.05	1.45	2.3		
	arting T	orque (Nm)		0.08	0.16	0.33	0.5	1		
Ra	ted To	rque (Nm)		0.065	0.14	0.25	0.4	0.8		
		load inertia	GD ² (Kgcm ²)	4.78	9.55	17.45	23.99	112.81		
	» «	Input line vo	oltage(V)	DC	24	DC	24	DC24		
Ш)nly erie	Consumption	on power(W)	6	.5	7	.5	7.5		
≤ B	E/M s ha	Maintenanc	e(Nm)	0	.3	0	.5	0.5		
E/M Brake	* Only E/M brake series have E/N	Attraction tir	, ,	3	30	3	33	33		
	≥6	Release tim	ie(ms)	8	37	9	95			
Sp	eed co	ntrol range(r/	min)	300~3000 250~2500						
			To load	±0.05%Max. at 3	000r/min(200/400\	N: at 2500r/min), n	o load~rated load.			
Spe	ed va		To voltage		•	•	0/400W: at 2500r/n	nin), no load.		
			To Temperature		40°C at 3000r/min(`	• • • • • • • • • • • • • • • • • • • •			
Slo	w start	/Slow down t	time set up		sec, Motor from 0~ sec, Motor from 0~					
Spe	eed co	ntrol method		 Control from external variable resistor (resistance 20ΚΩ) Control from internal variable resistor (also work with external variable resistor for 2 sections speed switch control) Control from external DC voltage (DC0~5V/1 mA above) Work with D/A speed setter TRDAC (Option) 						
Sig	nal inp	ut/output me	thods	Photo coupler input interface Transistor Open Collector output interface						
Fui	nction			 Zero point control, can connect to PLC or Transistor, Relay type I/O module Within speed control range, Motor sets Flat Torque output Instant brake stop, Slow up/Slow down Can operate in parallel 120W/200W have regenerative resistor connection terminals, can based on customers' load condition to select external resettable resistors to consume regenerated energy (regenerated energy absorption protection: start operation at up down, Coiling or inertial load operation) 						
Protection function Insulation impedance				Overload protectio Over heat protectio Over voltage prote Transient over curr for Power on, eas	n: starts when Motor on: starts when Drive ction: (1) starts when (2) starts whe rent protection: Wher by activates by large to ection: starts when M	activate torque for m r internal heat sink or n up down, coiling or en Driver input AC vo n driver AC input pow transient current	ver 80°C	nt high voltage el with large power		
				Applies DC500V high	resistance meter test,	, power, F.G grounding	g, I/O terminal resistand	ce value is over 100M		
Ins	ulation	high voltage		Power and F.G connect to ground, terminals pass with 1.8KV/60Hz high voltage, power and I/O connectors pass with 3KV/60Hz high voltage for 1 minute, no abnormal condition						
Am	bient t	emperature/l	Humidity range	0~+40°C, under 85% relative humidity (avoid dust and erosion, combustion gas)						
Note1 : Please fill the power in the box-□, ⓓ indicates AC110V~115V , ② indicates AC220V~230V. ※ 1 Nm=10.19716Kg								=10.19716Kgcm		



BS series

■ Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD²)

Gear ratio		3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30
Speed range	High speed	1000	883	600	500	400	333	300	240	200	166	150	120	100
(r/min)	Low speed	100	83.4	60	50	40	33.4	30	24	20	16.7	15	12	10
Allowable torque (Nm)	6B020P-□(M) +6D□	0.18	0.21	0.29	0.35	0.44	0.53	0.59	0.73	0.88	1.1	1.2	1.4	1.7
Allowable inertia load GD ² (kgcm ²)		2.25	3.24	6.25	9.00	14.1	20.3	25.0	39.1	56.3	81.0	100	156	225
Allowable torque (Nm)	6B040P-□(M) +6D□	0.35	0.42	0.59	0.7	0.88	1.1	1.2	1.5	1.8	2.1	2.3	2.8	3.4
Allowable inertia	a load GD ² (kgcm ²)	4.50	6.48	12.5	18.0	28.1	40.5	50.0	78.1	113	162	200	313	450
Allowable torque (Nm)	9B075PD-□(M) +9D □	0.68	0.81	1.1	1.4	1.7	2	2.3	2.8	3.4	4.1	4.5	5.4	6.5
Allowable inertia load GD ² (kgcm ²)		27.9	40.2	77.6	112	175	251	310	485	698	1005	1241	1939	2792
Allowable torque (Nm)	9B120PD-□(M) +9D □	1.1	1.3	1.8	2.2	2.7	3.2	3.6	4.5	5.4	6.5	7.2	8.6	10.3
Allowable inertia	a load GD ² (kgcm ²)	38.4	55.3	107	154	240	345	426	666	960	1382	1706	2666	3838
	High speed	833	694	500	416	333	277	250	200	166	138	125	100	83
Speed range (r/min)	Low speed	83.4	69.5	50	41.7	33.4	27.8	25	20	16.7	13.9	12.5	10	8,4
Allowable torque (Nm)	9B200P-□(M) +9D□H	2.2	2.6	3.6	4.3	5.4	6.5	7.2	9	10.8	13	14.4	17.2	20.6
	a load GD² (kgcm²)	181	260	501	722	1128	1624	2006	3134	4512	6498	8022	12534	18050
Allowable illertia	a load GD (kgclii)	101	200	501	122	1120	1024	2000	0104	4012	0430	0022	12004	10000
Gea	r ratio	36	50	60	75	90	100	120	150	180	200	250	300	360
Speed range	High speed	83	60	50	40	33	30	25	20	16	15	12	10	8
(r/min)	Low speed	8.4	6	5	4	3.4	3	2.5	2	1.7	1.5	1.2	1	0.9
Allowable torque (Nm)	6B020P-□(M) +6D□	2	2.8	3.4	4.2	5	5.6	6.3	6.5					
Allowable inertia	a load GD ² (kgcm ²)	324			625				625					
Allowable torque (Nm)	6B040P-□(M) +6D□	4	5.6		6	.5		6.5						
Allowable inertia load GD ² (kgcm ²)		625					625							
Allowable torque (Nm)	9B075PD-□(M) +9D □	7.7	10.8	12.9	16.1	19.4	21.5	24.3	30.4	36.5	40			
Allowable inertia	a load GD ² (kgcm ²)	4020	7756		110	00		11000						
Allowable torque (Nm)	9B120PD-□(M) +9D □	12.4	17.2	20.6	25.8	31	34.4	38.9 40						
Allowable inertia load GD ² (kgcm ²)		5527	10662	0662 11000				11000						
Speed range (r/min)	High speed	69	50	41	33	27	25	20	16	13	12	10	8	6
	Low speed	7	5	4.2	3.4	2.8	2.5	2.1	1.7	1.4	1.3	1	0.8	0.7
Allowable torque (Nm)	9B200P-□(M) +9D□H	24.8	34.4	41.3		50		50						
Allowable inertia load GD ² (kgcm ²)		25991	45000				45000							

^{*} Gearhead 6D \square /9D \square /9D \square H, please fill gear ratio in \square .

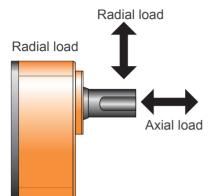
^{*} In above table stands for after installation of Gearhead, the axis rotation direction is reversed with Motor axis direction; without marking stands for the same direction as Motor axis rotation.

^{* 1}Nm = 10.197Kgcm.

^{*}The Gearheads of all series have ROHS @ certificate.

^{*} Also available orthogonal Gearhead: hollow shaft type $9VD\Box(H)$, the solid single shaft type $9VD\Box A(H)$, the solid biaxial shaft type $9VD\Box B(H)$, and size please refer to P.10.

■ Motor allowable radial load/axial load



- (1) Radial load (hanging load): loading is vertical to Gearhead axis power output
- (2) Axial load (thrust load): loading is in the direction of Gearhead axis power output

◆ Round shaft type

	Permissible overhung	Permissible thrust load		
Model	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)	
6B020S-□(M) 6B040S-□(M) 9B075S-□(M) 9B120S-□(M) 9B200S-□(M)	8 8 13 16 16	9 9 15 17 17	Permissible axial loading, not more than 1/2 of motor weight. But please try to avoid applying force in the horizontal direction (axial) of motor shaft, when exceeds that will reduce motor service life. If axial loading is needed, we recommend applying indirect transmission, such as: couplings, belts, chains, etc	

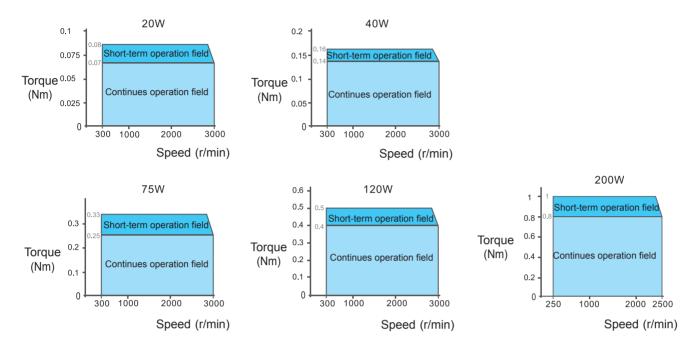
◆ Pinion shaft type (Gearhead attached)

		Permissible overhur	Permissible thrust load		
Model	Gear ratio	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)	
6B020P-□(M)	3, 3.6, 5	10	15	4	
+ 6D□ 6B040P-□(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	15	20		
+ 6D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	20	30		
9B075PD-□(M)	3, 3.6, 5	30	40	15	
+ 9D□ 9B120PD-□(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	40	50		
+ 9D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	50	65		
	3, 3.6, 5	30	40		
9B200P-□(M) + 9D□H	6, 7.5, 9, 10, 12.5, 15,18, 20	40	50	15	
	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	50	65		

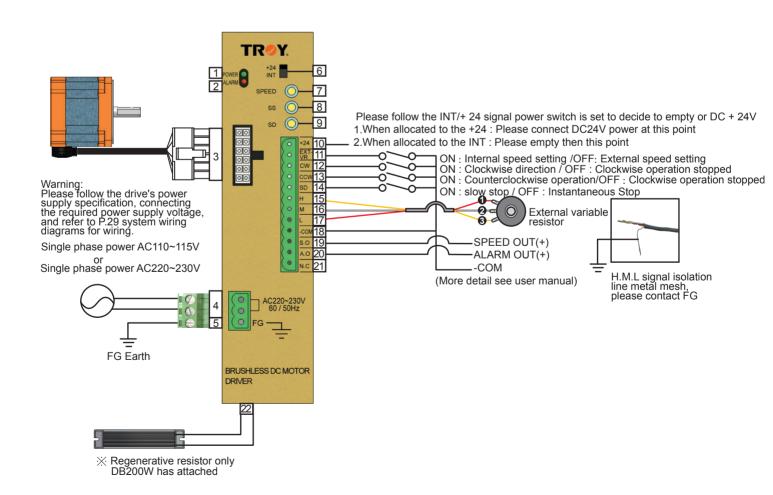
^{*} Motor 6B020S- \square (M)...etc, please fill in \square with line power voltage. \square : stand for single phase AC110~115V, ②: stand for single phase AC220~230V. *Gearhead 6D□/9D□/9D□H, please fill gear ratio in □.



■ Speed - Torque characteristic diagrams



Driver panel functions and wiring instructions

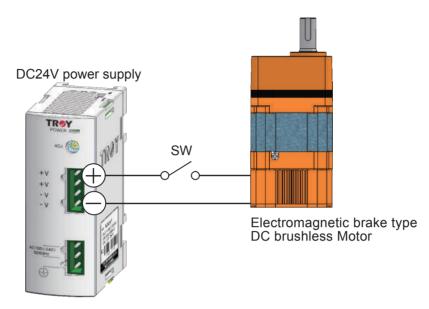


Number	Panel marked	Function	Explanation
1	POWER	Power indicator	When input power LED (green) lights
2	ALARM	Unusual indicator	Overload, overheating, overvoltage, instantaneous overcurrent, under equal any protective function will activate LED (red) lights
3	MOTOR	Motor wiring connector	Motor and Driver connection
4	AC110~115V or 220~230V 60/50Hz	Power voltage input terminal	AC power voltage input connection
5	FG	Power ground terminal	Power ground connecting
6	+24/INT	Signal power switch	+24: When using an external power DC24V control (PLC control applicable to the case) INT: Using Driver internal DC24V power control (for relays, switches and control applications)
7	SPEED	Internal speed setting button	20~120W speed control range : 300~3000r/min 200W speed control range : 250~2500r/min
8	SS	Slow start time setting button	20~120W: 0.5~15sec 200W: 0.8~15sec
9	SD	Slow stop time setting button	20~120W: 0.5~15sec 200W: 0.8~15sec
10	+24	Signal input power DC24V	When an external DC24V power control, external DC24V power connects to the terminal
11	EXT-VR	Speed setting switch to select the input mode	External/Internal speed setting mode switch selection
12	CW	Clockwise operation input	Clockwise operation/stop switch input
13	CCW	Counterclockwise operation input	Counterclockwise operation/stop switch input
14	SD	Slow stop time setting button	Slow (depending on SD button to set the time for the slow stopped)/instantaneous stop mode select switch
15	Н		An external connection terminal variable resistor or external DC voltage (0 ~ 5V) control of
16	M	External speed setting input	20~120W speed control range : 300~3000r/min
17	L		200W speed control range : 250~2500r/min
18	-COM	Control signal grounding	GND contact inputs and outputs a control signal common ground line, and the external power DC24V
19	S.O.	Speed signal output	Detecting Motor speed using : 20 ~ 120W digital signal output 12 Pulse/rev 200W digital signal output 24 Pulse/rev
20	A.O.	Abnormal warning signal output	Overload, overheating, overvoltage, overcurrent moment, when any one of the less equal protection function is activated, Motor will stop naturally, and outputs an abnormality warning signal
21	N.C.	No connection	Do not make any connection
22	RG	None Regenerative resistor connection terminal	20/40/75W: No this connection terminal 120/200W: According to customer load conditions selected external regenerative resistance, regenerative energy consumption



BS series

■ Motor electromagnetic brake wiring instructions



Operation instruction

Motor start/Motor stop with external electromagnetic brake operating procedures: Motor start: Must energize external electromagnetic brake before the Motor starts

	5
Step :	External electromagnetic brake power ON
	Attracting waiting time (This is the time of the external electromagnetic brake actuation, the purpose: to keep the force is released)
	Motor Driver starting signal ON
	Motor starts running
Motor Stop :	The Motor is stopped before the operation do not yet fully external electromagnetic brake power.
Step:	Motor Driver stop signal ON
	Wait 0.2sec (reference value, this is the operation of the Motor to a complete stop time)
	External electromagnetic brake power is turned OFF
	Waiting for the release time (This is the external electromagnetic brake actuation time, purpose: To generate holding force)
	Motor stopped (a holding force)

Precautions

- 1. This series of external electromagnetic brake using the brake power is part of the hold-type.
- 2.External electromagnetic brake is designed to allow the Motor stops when the holding force
- has to be used as a safety brake, electromagnetic brake, do not use this as a Motor positioning or emergency brake applications.

 3. Always to pull the Motor before starting the external electromagnetic brake energized (means no brakes); Motor stopped before the operation do not yet fully external electromagnetic brake power (expressed brakes).
- 4.External electromagnetic brake suction time and release time value refer to the product specification. 5.Motor brakes to stop for about 0.2sec (test conditions in the Motor no-load speed 3000r / min, the electromagnetic brake is energized, the brake actuator signal ON time of the Driver, this time as a reference base, but the actual length of time will stop according to the inertia load or frictional load ... different load patterns and has fluctuated.
- 6.We recommend to do the actual measuring device operating time at the time of commissioning.

Weight: 1440g+W

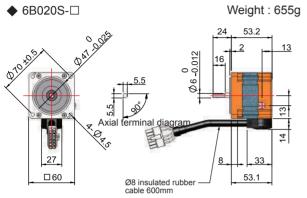
Dimensions - Motor/Gearhead

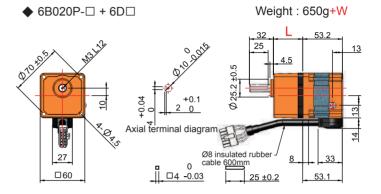
Round shaft type

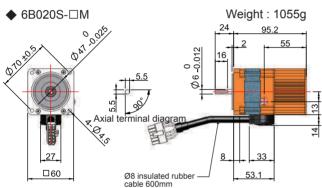
Pinion shaft type

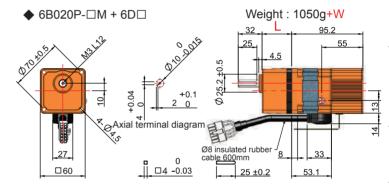
Unit: mm

20W/□60mm

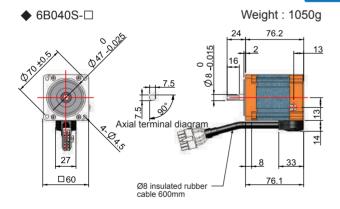


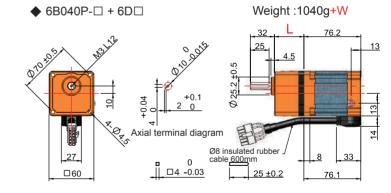




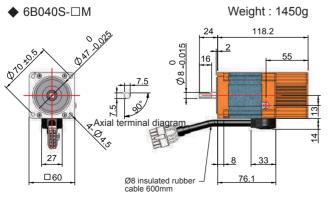


40W/□60mm





6B040P-□M + 6D□



(+0.1 Axial terminal diagram Ø8 insulated rubber □4 -0.03

* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

★ 6B pinion shaft type 6D3-6D360, Gearhead length L and weight W specification as following:

	Model	6D3~6D20	6D25~6D100	6D120~6D360
arhead	Length L (mm)	39.5	39.5	43.5
	Weight W (g)	300	325	365



BS series

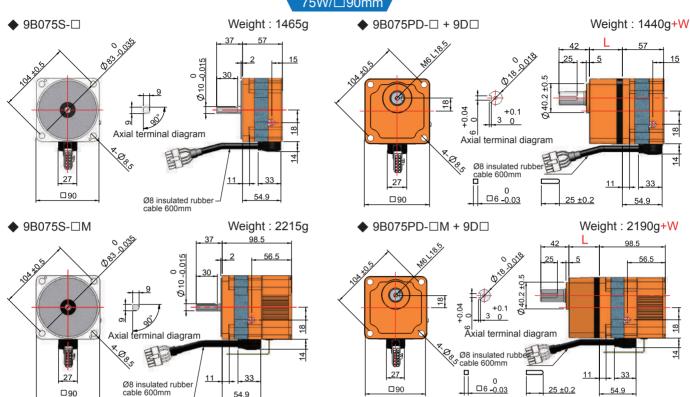
Round shaft type

■ Dimensions - Motor/Gearhead

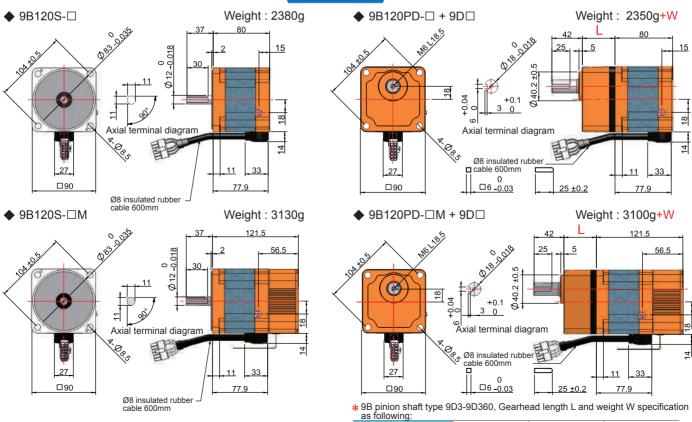
Pinion shaft type

Unit: mm

75W/□90mm



120W/□90mm



* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

	Model	9D3~9D20	9D25~9D100	9D120~9D360
Gearhead	Length L (mm)	45.5	58.5	64.5
	Weight W (g)	860	1125	1265

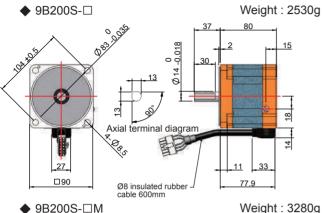
Unit: mm

Dimensions - Motor/Gearhead

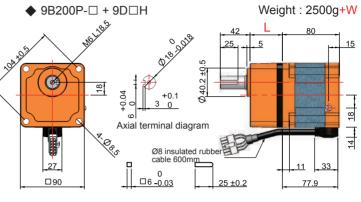
Round shaft type

Pinion shaft type

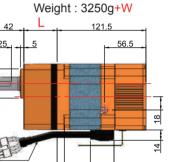
200W/□90mm



Weight: 3280g



9B200P-□M + 9D□H



Weight: 660g

Weight: 670g

Weight: 680g

* 9B pinion shaft type 9D3H-9D360H, Gearhead length L and weight W specification as following:

് ര| Axial terminal diagram

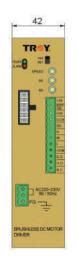
Ø8 insulated rubbe 0 □6 <u>-0.03</u>

	Model	9D3H~9D20H	9D25H~9D100H	9D120H~9D360H
Gearhead	Length L (mm)	45.5	58.5	64.5
	Weight W (g)	860	1125	1265

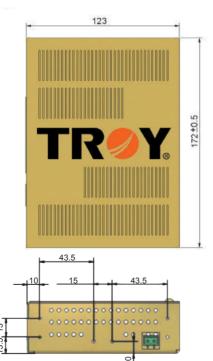
Dimensions - Driver

Axial terminal diagram

Ø8 insulated rubbe cable 600mm



704.20,52

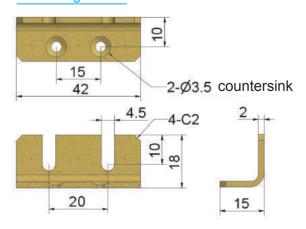


Mounting sheet

Model: DB020-□ / DB040-□

DB120-□ / DB200-□ Dimensions are common

DB075-□

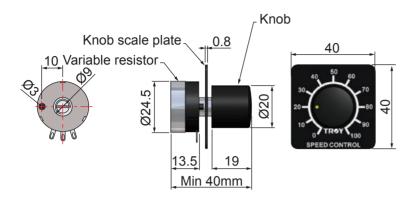


* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.



BS series

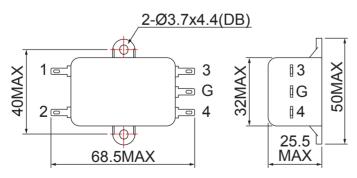
■ Dimensions - Variable resistor



■ Dimensions - Regenerative resistance dimensions (Only 150 / 200W attached)

Two insulated wires, 16AWG long 300mm 7.5 175 20 150 20 190

■ Dimensions - Power supply noise filter



* Figure above dimensions tolerance values are not label on general maching tolerances, the control mode refer to P.12, others have marked tolerance values according to the drawing labeled based.

Weight: 260g

Weight: 50g

Weight: 30g

Unit: mm



-For fast response speed, high operation frequency demand

System wiring diagrams
Specifications and characteristics of Motor/Driver
Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD²)
Motor allowable radial load/axial load
Speed - Torque characteristic diagrams
Driver panel functions and wiring instructions

46 Motor electromagnetic brake wiring instructions

47 Dimensions - Motor/Gearhead

49 Dimensions - Driver

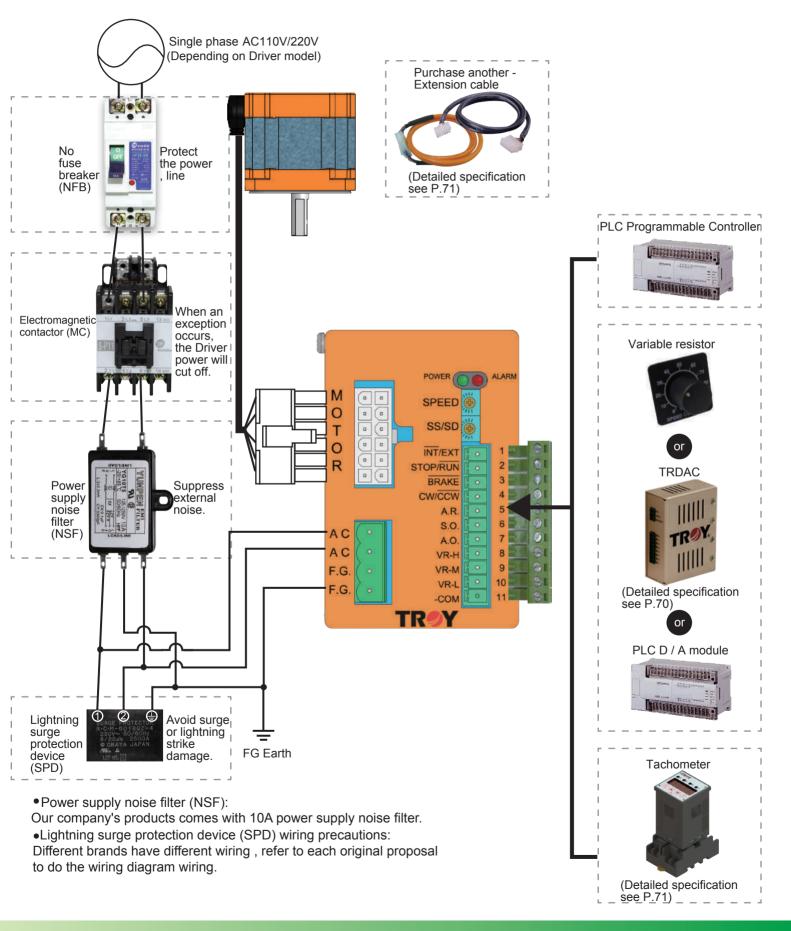
Page

49 Dimensions - Variable resistor/Power supply noise filter



DC brushless Motor- SBS series

■ System wiring diagrams



6B040P-2N

■ Specifications and characteristics of Motor/Driver

				000401-214			X
Motor	output pov	wer	20W	40W	60W	90W	
	shaft Motor (shaft Motor (M:	M: E/M brake type) E/M brake type)	6B020S-□N(M) (Note 1) 6B020P-□N(M)	6B040S-□N(M) 6B040P-□N(M)	9B060S-□N(M) 9B060PD-□N(M)	9B090S-□N(M) 9B090PD-□N(M)	Characteristics Product index Product names of Motor
Motor specification -1 Type			∠ RoHS	⊕ IP54	RoHS)	_S Pr
certificates -2 Type			(€ 	юнs) e IP54	(€ @	RoHS (Note 2)	oduct
Driver SBD020-□N SBD040-□N SBD060-□N SBD090-□N						index	
Driver s	specification	certificates		C€ Ro	oHS (e)		Produ
<u></u> -1 Ty	pe Single Phase	Max. Current (A)	2.4	2.4	2.5	2.9	ct nar
AC11 50/60 -2 Tyl AC22 50/60	10~115V) HZ	Rated Current (A)	0.59	0.99	1.48	1.93	nes F
er -2 Ty	pe Single Phase	Max. Current (A)	1.7	1.7	1.7	1.7	roduc
의 AC22 50/60	20~230V) HZ	Rated Current (A)	0.33	0.56	0.82	1.05	Product weight
Starting	Torque (Nm)		0.15	0.25	0.45	0.65	ght
Rated To	orque (Nm)		0.10	0.20	0.30	0.50	G
Allowabl	Allowable load inertia GD ² (Kgcm ²)		14.01	23.23	39.42	54.23	Gearhead
se O	Input line v	O ()	DC	24	DC	224	ead
Series h	Consumpti	ion power(W)	6.			.5	-
ily E/M bra iles have E E/M Brake	Maintenan Attraction t		0.3		0.5		Installation
e E/M	Release tir	` '	30 8		33 95		llatior
	ontrol range(r/	, ,	0.	250~		<u> </u>	
ореса с		To load	-1%Max.	at 2000r/min, no load~rat			Certificates
Speed va	ariation rate	To voltage		Voltage variation ±15%, a			ates
opeca is		To Temperature		0-+40°C at 2000r/min, no	•		Mod
Slow sta	rt/Slow down	time set up	·	tor from 0~2000r/min whe			Model naming
Speed co	ontrol method		 Control from external variable resistor (resistance 20ΚΩ) Control from external DC voltage (DC0~5V/1 mA above) Gontrol from internal variable resistor (also work with external variable resistor for 2 sections speed switch control) Work with D/A speed setter TRDAC (Option) 				
Signal in	put/output me	thode	●Photo coupler input inte	erface	(Ораоп)		S
Olgilai III	put/output me	uious	Transistor Open Collect	<u> </u>			B S
			●Within speed control ra	inge, Motor sets Flat Torq	stor, Relay type I/O modu ue output	le	S B S
Function			 Instant brake stop, Slov When brake stop all el 	w up/Slow down lectric types of holding rol	۵		
			Can parallel operation	counc types of floraling for			U B S
			Overload protection: stOver heat protection: s	arts when Motor activate tarts when Driver internal		C	D B S
Protectio	Protection function Over voltage protection: (1) starts when up down, coiling or over inertial load (2) When Driver voltage of the AC power input over about 35%, starts operation Low voltage protection: Driver input AC power voltage is lower than about 20%, starts operation Offline protection: When Motor cable disconnected, starts operation				Accessories		
Insulation	n impedance		Applies DC500V high resi	istance meter test, power, F	F.G grounding, I/O terminal i	resistance value is over 100MΩ	
Insulation	n high voltage		Power and F.G connect connectors pass with 3k	to ground, terminals pass	s with 1.8KV/60Hz high vo 1 minute, no abnormal cor	Itage, power and I/O ndition	Motor selection
Ambient	temperature/l	Humidity range	0~+40°C, under 85% re	lative humidity (avoid dus	t and erosion, combustion	gas)	ion ——

Note1 : -□, Please fill power voltage in □. □indicates single phaseAC110~115V , ②: indicates single phase AC220~230V * 1 Nm=10.19716 Kgcm Note2: 9B060PD-2N \ 9B090PD-2N have passed IP54 certificate.



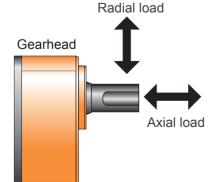
SBS series

■ Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD²)

Gear	ratio	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30
Speed range	High speed	666	555	400	333	266	222	200	160	133	111	100	80	66
(r/min)	Low speed	83.4	69.5	50	41.7	33.4	27.8	25	20	16.7	13.9	12.5	10	8.4
Allowable torque (Nm)	6B020P-□N(M) + 6D□	0.27	0.32	0.45	0.54	0.68	0.81	0.9	1.1	1.4	1.6	1.8	2.2	2.6
Allowable iner	tia load GD² (kgcm²)	6.30	9.08	17.5	25.2	39.4	56.7	70.1	109	158	227	280	438	625
Allowable torque (Nm)	6B040P-□N(M) + 6D□	0.54	0.65	0.9	1.1	1.4	1.6	1.8	2.3	2.7	3.2	3.6	4.3	5.2
Allowable inert	tia load GD ² (kgcm ²)	10.5	15.1	29.0	41.8	65.3	94.1	116	181	261	376	465	62	25
Allowable torque (Nm)	9B060PD-□N(M) + 9D□	0.81	0.97	1.4	1.6	2	2.4	2.7	3.4	4.1	4.9	5.4	6.5	7.7
Allowable inert	tia load GD² (kgcm²)	63.1	90.8	175	252	394	568	701	1095	1577	2271	2803	4380	6307
Allowable torque (Nm)	9B090PD-□N(M) + 9D□	1.4	1.6	2.3	2.7	3.4	4.1	4.5	5.6	6.8	8.1	9	10.8	12.9
Allowable inert	tia load GD ² (kgcm ²)	86.8	125	241	347	542	781	964	1506	2169	3124	3856	6026	8677
Gear	r ratio	36	50	60	75	90	100	120	150	180	200	250	300	360
Speed range	High speed	55	40	33	26	22	20	16	13	11	10	8	6	5
(r/min)	Low speed	7	5	4.2	3.4	2.8	2.5	2.1	1.7	1.4	1.3	1	0.9	0.7
Allowable torque (Nm)	6B020P-□N(M) + 6D□	3.1	4.3	5.2		6.5					6.5			
Allowable inert	ia load GD ² (kgcm ²)			62	25						625			
Allowable torque (Nm)	6B040P-□N(M) + 6D□	6.2			6.5						6.5			
Allowable inert	tia load GD ² (kgcm ²)			62	25						625			
Allowable torque (Nm)	9B060PD-□N(M) + 9D□	9.3	12.9	15.5	19.4	23.2	25.8	29.2	36.5			40		
Allowable inert	tia load GD² (kgcm²)	9082			110	00					11000			
Allowable torque (Nm)	9B090PD-□N(M) + 9D□	15.5	21.5	25.8	32.3	38.7	40				40			
	tia load GD² (kgcm²)			11/	000						11000			

- * Motor 6B020P- \square (M)...etc, please fill in \square with line power voltage. $\boxed{1}$: stand for single phase AC110~115V, $\boxed{2}$: stand for single phase AC220~230V.
- * Gearhead 6D □ /9D □ /9D □ H, please fill gear ratio in □.
- * In above table stands for after installation of Gearhead, the axis rotation direction is reversed with Motor axis direction; without marking stands for the same direction as Motor axis rotation.
- *1Nm = 10.197Kgcm.
- *The Gearheads of all series have RoHS @ certificate.
- *Also available orthogonal Gearhead: hollow shaft type $9VD\square(H)$, the solid single shaft type $9VD\square A(H)$, the solid biaxial shaft type $9VD\square B(H)$, and size please refer to P.10.

■ Motor allowable radial load/axial load



- 1 Radial load (hanging load): loading is vertical to Gearhead axis power output
- ② Axial load (thrust load): loading is in the direction of Gearhead axis power output

◆ Round shaft type

Model	Permissible overhun	Permissible thrust load	
Model	10mm from output shaft front 20mm from output shaft front		(Unit: Kg f)
6B020S-□N(M)	8	9	Permissible axial loading, not more than 1/2 of motor weight. But please try to avoid applying
6B040S-□N(M)	8	9	force in the horizontal direction (axial) of motor shaft, when
9B060S-□N(M)	13	15	exceeds that will reduce motor service life. If axial loading is needed, we
9B090S-□N(M)	16	17	recommend applying indirect transmission, such as: couplings, belts, chains, etc

◆ Pinion shaft type (Gearhead attached)

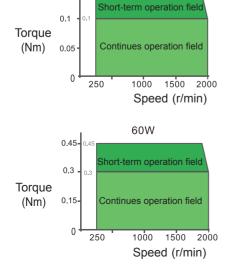
		Permissible overhur	Permissible thrust load	
Model	Gear ratio	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)
6B020P-□N(M)	3, 3.6, 5	10	15	
+ 6D□ 6B040P-□N(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	15	20	4
+ 6D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	20	30	
9B060PD-□N(M)	3, 3.6, 5	30	40	
+ 9D□ 9B090PD-□N(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	40	50	15
+ 9D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	50	65	

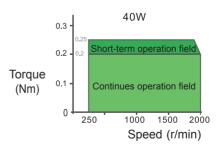
* Motor 6B020S-□N(M)... etc, please fill power voltage in □. □ : indicate single phase AC110V~115V, □ : indicate single phaseAC220~230V

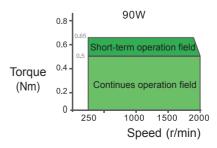
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■ Speed - Torque characteristic diagrams

20W







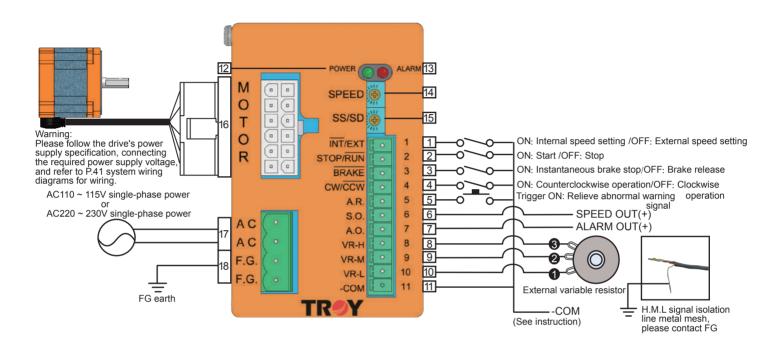
^{*} Gearhead 6D□/9D□, please fill Gearhead in □.



SBS series

■ Driver panel functions and wiring instructions



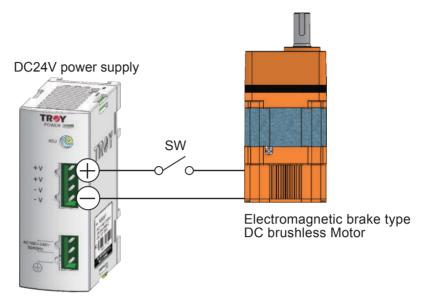


Number	Panel marked	Function	Explanation			
1	INT/EXT	Speed setting mode switch to select the input	Internal / external speed setting mode switching selection			
2	STOP/RUN	Stop/Start signal input	Stop / start signal switching input			
3	BRAKE	Instantaneous brake stop signal input	Executive instantaneous brake stop / brake release signal switch input			
4	CW/CCW	The direction of rotation switch to select the input	Clockwise/counterclockwise operation switch selection			
5	A.R.	Warning signs release abnormal input	AR trigger input contacts (continuous "L" state 10ms) to release the error warning signal			
6	S.O.	Speed signal output	When Motor speed is detected using, digital signal output 12 Pulse / rev			
7	A.O.	Abnormal warning signal output	Overload, overheating, over voltage, low voltage, disconnection of any of a protective function is activated, Motor stops naturally, and outputs an abnormality warning signal			
8	VR-H					
9	VR-M	External speed setting input	An external connection terminal variable resistor or external DC voltage (0 \sim 5V) Speed control range: 250 \sim 2000r / min			
10	VR-L					
11	-COM	Control signal grounding	GND contact input and output a control signal common ground wire, and the external DC power			
12	POWER	Power Indicator	Input power LED (green) lights			
13	ALARM	Abnormal indicator	Overload, overheating, over voltage, low voltage, disconnection of any of a protective function is activated LED (red) lights			
14	SPEED	Internal speed setting key	20 ~ 90W speed control range: 250 ~ 2000r / min			
15	SS/SD	Slow start, stop time setting key	Slow start 0.5 ~ 8 sec; slow stop 0.5 ~ 7sec			
16	MOTOR	Motor wiring connector	Motor and Driver connection			
17	AC	Power, voltage input terminal	AC power voltage input connection			
18	FG	Power ground terminal	Power ground connection			

U

В S

■ Motor electromagnetic brake wiring instructions



◆Operation instruction

Motor start/Motor stop with external electromagnetic brake operating procedures: Motor start: Must energize external electromagnetic brake before the Motor starts

Step: External electromagnetic brake power ON Attracting waiting time (This is the time of the external electromagnetic brake actuation, the purpose: to keep the force is released) Motor Driver starting signal ON Motor starts running The Motor is stopped before the operation do not yet fully external electromagnetic brake power. Motor Stop: Step: Motor Driver stop signal ON Wait 0.2sec (reference value, this is the operation of the Motor to a complete stop time) External electromagnetic brake power is turned OFF Waiting for the release time (This is the external electromagnetic brake actuation time, purpose: To generate holding force)

Motor stopped (a holding force)

Precautions

- 1. This series of external electromagnetic brake using the brake power is part of the hold-type.
- 2.External electromagnetic brake is designed to allow the Motor stops when the holding force has to be used as a safety brake, electromagnetic brake, do not use this as a Motor positioning or emergency brake applications.
- 3.Always to pull the Motor before starting the external electromagnetic brake energized (means no brakes); Motor stopped before the operation do not yet fully external electromagnetic brake power (expressed brakes).
- 4.External electromagnetic brake suction time and release time value refer to the product specification. 5. Motor brakes to stop for about 0.2sec (test conditions in the Motor no-load speed 3000r / min, the electromagnetic brake is energized, the brake actuator signal ON time of the Driver, this time as a reference base, but the actual length of time will stop according to the inertia load or frictional load ... different load patterns and has fluctuated.
- 6.We recommend to do the actual measuring device operating time at the time of commissioning.

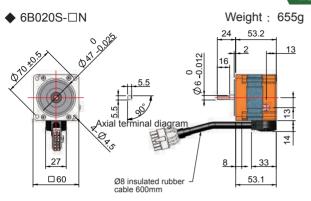


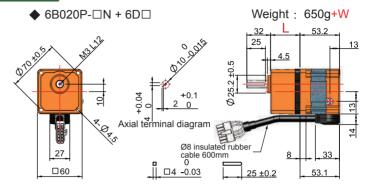
SBS series

■ Dimensions - Motor/Gearhead

Round shaft type Gear shaft type

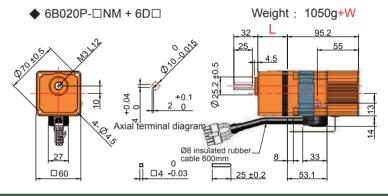
20W/□60mm



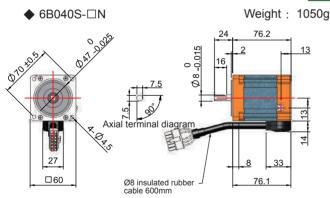


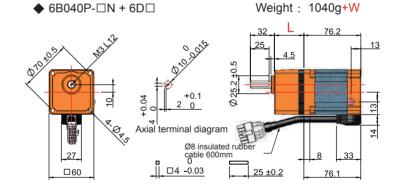
Unit: mm

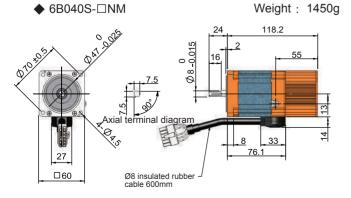
6B020S-□NM Weight: 1055g 970405 0 -0.012 □60 Ø8 insulated rubber cable 600mm 53.1



40W/□60mm

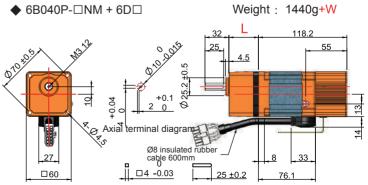






* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

6B040P-□NM + 6D□



* 6B pinion shaft type 6D3-6D360, Gearhead length L and weight W specification as following:

	Model	6D3~6D20	6D25~6D100	6D120~6D360
Gearhead	Length L (mm)	39.5	39.5	43.5
	Weight W (g)	300	325	365

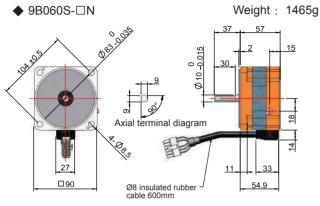
Round shaft type

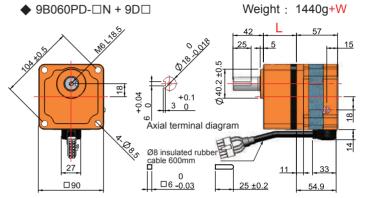
Dimensions - Motor/Gearhead

Gear shaft type

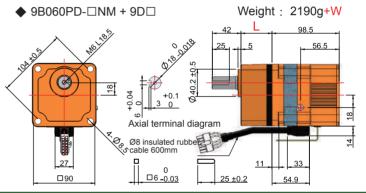
Unit: mm

60W/□90mm

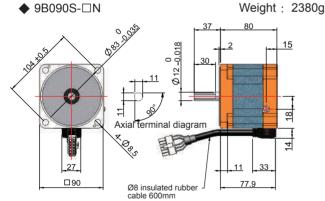


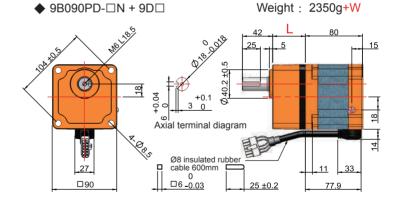


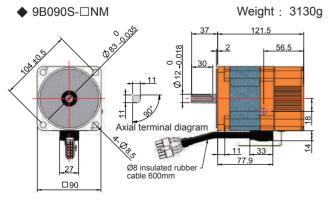
◆ 9B060S-□NM Weight: 2215g 704.20.52 terminal diagran Ø8 insulated rubber cable 600mm

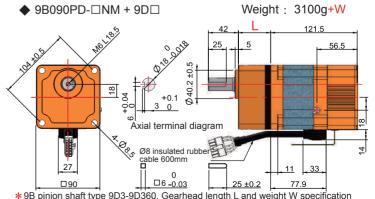


90W/□90mm









* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

* 9B pinion shaft type 9D3-9D360, Gearhead length L and weight W specification as following:

| Model | 9D3~9D20 | 9D25~9D100 | 9D120~9D360 | nead Length L (mm 45.5 58.5 64.5 Weight W (g) 860 1125 1265



SBS series

■ Dimensions - Driver

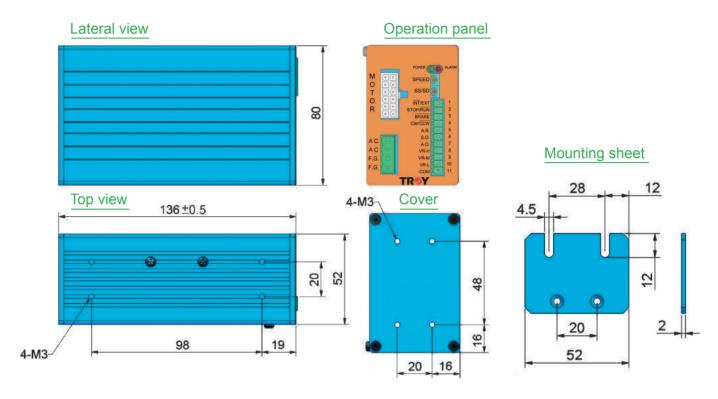
Unit: mm

Model : SBD020- \square N/SBD040- \square N

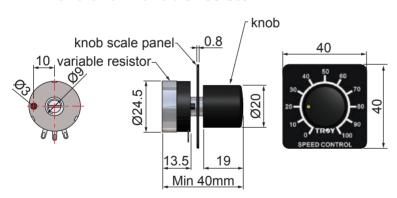
SBD060-□N/SBD090-□N

Dimensions are common

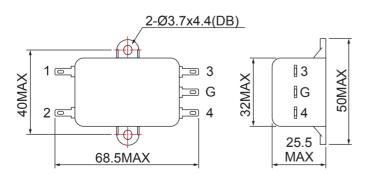
Weight: 530g



Dimensions - Variable resistor



■ Dimensions - Power supply noise filter



* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

Weight: 30g

Weight: 50g



UBS series

-The situation of simple operation and easy control

Page 51 System wiring diagrams

52 Specifications and characteristics of Motor/Driver

53 Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD2)

53 Motor allowable radial load/axial load

Speed - Torque characteristic diagrams

55 Driver panel functions and wiring instructions

56 Motor electromagnetic brake wiring instructions

57 Dimensions - Motor/Gearhead

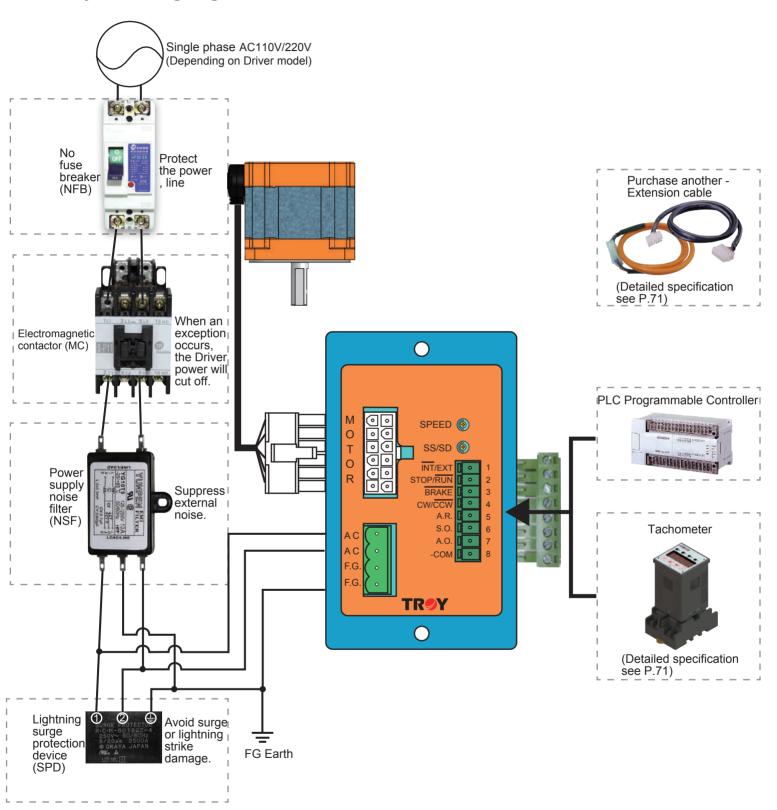
59 Dimensions - Driver

59 Dimensions - Power supply noise filter



DC brushless Motor- UBS series

■ System wiring diagrams



- Power supply noise filter (NSF):
- Our company's products comes with 10A power supply noise filter.
- •Lightning surge protection device (SPD) wiring precautions: Different brands have different wiring, refer to each original proposal to do the wiring diagram wiring.



■ Specifications and characteristics of Motor/Driver

Motor output power			20W	40W	60W	90W	
Round shaft Motor (M: E/M brake type) Pinion shaft Motor (M: E/M brake type)			6B020S-□N(M) (Note 1) 6B020P-□N(M)	6B040S-□N(M) 6B040P-□N(M)	9B060S-□N(M) 9B060PD-□N(M)	9B090S-□N(M) 9B090PD-□N(M)	
Mot	tor specification	-1 Type	Ç RoHS RoHS	e IP54	RoH] 	
cer	tificates	-2 Type	(€ ((() R	он ѕ ⊕ IP54	(((()	RoHS (Note 2)	
Driv	/er		UBD020-□N	UBD040-□N	UBD060-□N	UBD090-□N	
Driv	er specification	certificates		CE Ro	oHS) (e)		
Inp	-1 Type Single Phase	Max. Current (A)	2.4	2.4	2.5	2.9	
ut pov	AC110~115V 50/60 HZ	Rated Current (A)	0.59	0.99	1.48	1.93	
	-2 Type Single Phase AC220~230V	Max. Current (A)	1.7	1.7	1.7	1.7	
tage	AC220~230V 50/60 HZ	Rated Current (A)	0.33	0.56	0.82	1.05	
Star	ting Torque (Nm)		0.15	0.25	0.45	0.65	
	ed Torque (Nm)		0.10	0.20	0.30	0.50	
Allo	wable load inertia		14.01	23.23	39.42	54.23	
	Se S	voltage(V)	DC		DC24		
E/M	G Consump	tion power(W)	6.5 0.3		7.5 0.5		
E/M Brake	Series have EM Release t		30		33		
e	Release t			87 95			
Spe	ed control range(` '	250~2000				
		To load	-1%Max. at 2000r/min, no load~rated load.				
Spe	ed variation rate	To voltage	±2% Voltage variation ±15%, at 2000r/min, no load.				
		To Temperature	±2% 0-+40°C at 2000r/min, no load.				
Slov	w start/Slow dowr	time set up	Slow start 0.5~8sec, Motor from 0~2000r/min when no load Slow stop 0.5~7sec, Motor from 2000~0r/min when no load				
Spe	ed control metho	d	Controlled by front panel knob for speed Controlled by back panel knob for speed				
			Photo coupler input interest.				
Sigr	nal input/output m	ethods	Transistor Open Collect				
			,	•	om the front panel "RUN /		
Fun	ection		· ·		vithin the speed control ra op (SLOW START / SLOV	•	
			When brake to stop all	• •	op (SEOW STAIRT / SEOV	. 201111	
			When protective function	is activated, Motor will c	oast to a stop drive ALAR	M contact signal output	
				it starts operation	ated torque of Motor runni		
Protection function			 Overlheat Protection: When Driver is internal heat sink temperature exceeds 80 ° C, starts operation Overvoltage Protection: (1)Up and down, winding or exceeds the allowable load inertia during operation, 				
			_	(2)When Driver voltage	of the AC power input mo	ore than about 35%,	
			_		voltage is lower than abou	ut 20%, starts operation	
L	detien in the			: When Motor cable disc	, ,		
ınsı	ulation impedance				<u> </u>	resistance value is over 100M	
Insu	ılation high voltag	е	Power and F.G connect to connectors pass with 3K	to ground, terminals pass V/60Hz high voltage for 1	with 1.8KV/60Hz high vo 1 minute, no abnormal cor	Itage, power and I/O	
A k	nient temperature	Humidity range	0~+40°C under 85% rel	ative humidity (avoid dus	t and erosion, combustion	1 (125)	

Note1 : -□, Please fill power voltage in □. ⊡indicates single phaseAC110~115V , ②: indicates single phase AC220~230V * 1 Nm=10.19716 Kgcm_Note2 : 9B060PD-2N \ 9B090PD-2N have passed IP54 certificate.

വന വര്യ Accessories | Motor selection



UBS series

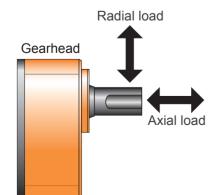
■ Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD²)

Gea	r ratio	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30
0	High speed	666	555	400	333	266	222	200	160	133	111	100	80	66
Speed range (r/min)	Low speed	83.4	69.5	50	41.7	33.4	27.8	25	20	16.7	13.9	12.5	10	8.4
Allowable torque (Nm)	6B020P-□N(M) + 6D□	0.27	0.32	0.45	0.54	0.68	0.81	0.9	1.1	1.4	1.6	1.8	2.2	2.6
Allowable iner	tia load GD² (kgcm²)	6.30	9.08	17.5	25.2	39.4	56.7	70.1	109	158	227	280	438	625
Allowable torque (Nm)	6B040P-□N(M) + 6D□	0.54	0.65	0.9	1.1	1.4	1.6	1.8	2.3	2.7	3.2	3.6	4.3	5.2
Allowable iner	tia load GD² (kgcm²)	10.5	15.1	29.0	41.8	65.3	94.1	116	181	261	376	465	6	25
Allowable torque (Nm)	9B060PD-□N(M) + 9D□	0.81	0.97	1.4	1.6	2	2.4	2.7	3.4	4.1	4.9	5.4	6.5	7.7
Allowable iner	tia load GD ² (kgcm ²)	63.1	90.8	175	252	394	568	701	1095	1577	2271	2803	4380	6307
	9B090PD-□N(M) + 9D□	1.4	1.6	2.3	2.7	3.4	4.1	4.5	5.6	6.8	8.1	9	10.8	12.9
Allowable iner	tia load GD ² (kgcm ²)	86.8	125	241	347	542	781	964	1506	2169	3124	3856	6026	8677
Gea	r ratio	36	50	60	75	90	100	120	150	180	200	250	300	360
Speed range	High speed	55	40	33	26	22	20	16	13	11	10	8	6	5
(r/min)	Low speed	7	5	4.2	3.4	2.8	2.5	2.1	1.7	1.4	1.3	1	0.9	0.7
Allowable torque (Nm)	6B020P-□N(M) + 6D□	3.1	4.3	5.2		6.5			-		6.5			-
Allowable iner	tia load GD ² (kgcm ²)			62	25						625			
Allowable torque (Nm)	6B040P-□N(M) + 6D□	6.2			6.5						6.5			
Allowable iner	tia load GD² (kgcm²)			62	25						625			
Allowable torque (Nm)	9B060PD-□N(M) + 9D□	9.3	12.9	15.5	19.4	23.2	25.8	29.2	36.5			40		
Allowable iner	tia load GD ² (kgcm ²)	9082			110	000					11000			
Allowable torque (Nm)	9B090PD-□N(M) + 9D□	15.5	21.5	25.8	32.3	38.7	40				40			
Allowable iner	rtia load GD² (kgcm²)			110	000						11000			
	00000	_ (2.4)		e								1011		

- *Motor 6B020P-□(M)...etc, please fill in □ with line power voltage. 1 : stand for single phase AC110~115V, 2 : stand for single phase AC220~230V.
- *Gearhead 6D \(\textstyle \)/9D \(\textstyle \)/9D \(\textstyle \)/H, please fill gear ratio in \(\textstyle \).

 In above table stands for after installation of Gearhead, the axis rotation direction is reversed with Motor axis direction; without marking stands for the same direction as Motor axis rotation.
- * 1Nm = 10.197Kgcm.
- *The Gearheads of all series have RoHS @ certificate.
- * Also available orthogonal Gearhead: hollow shaft type $9VD\square(H)$, the solid single shaft type $9VD\square A(H)$, the solid biaxial shaft type $9VD\square B(H)$, and size please refer to P.10.

■ Motor allowable radial load/axial load



- Radial load (hanging load): loading is vertical to Gearhead axis power output
- Axial load (thrust load): loading is in the direction of Gearhead axis power output

◆ Round shaft type

Model	Permissible overhur	ng load (Unit: Kg f)	Permissible thrust load (Unit: Kg f)	
	10mm from output shaft front	20mm from output shaft front		
6B020S-□N(M)	8	9	Permissible axial loading, not more than 1/2 of motor weight. But please try to avoid applying	
6B040S-□N(M)	8	9	force in the horizontal direction (axial) of motor shaft, when	
9B060S-□N(M)	13	15	exceeds that will reduce motor service life. If axial loading is needed, we	
9B090S-□N(M)	16	17	recommend applying indirect transmission, such as: couplings, belts, chains, etc	

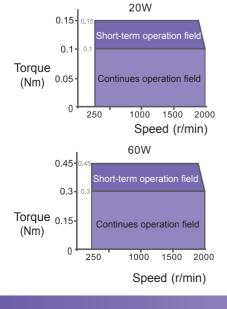
◆ Pinion shaft type (Gearhead attached)

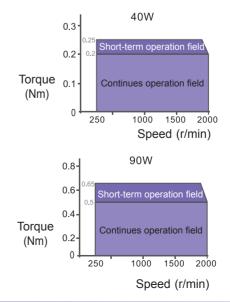
		Permissible overhu	ng load (Unit: Kg f)	Permissible thrust load	
Model	Gear ratio	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)	
6B020P-□N(M)	3, 3.6, 5	10	15		
+ 6D□ 6B040P-□N(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	15	20	4	
+ 6D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	20	30		
9B060PD-□N(M)	3, 3.6, 5	30	40		
+ 9D□ 9B090PD-□N(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	40	50	15	
+ 9D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	50	65		

* Motor 6B020S-□N(M)... etc, please fill power voltage in □. □ : indicate single phase AC110V~115V, □ : indicate single phaseAC220~230V

* Gearhead 6D□/9D□, please fill Gearhead in □.

■ Speed - Torque characteristic diagrams

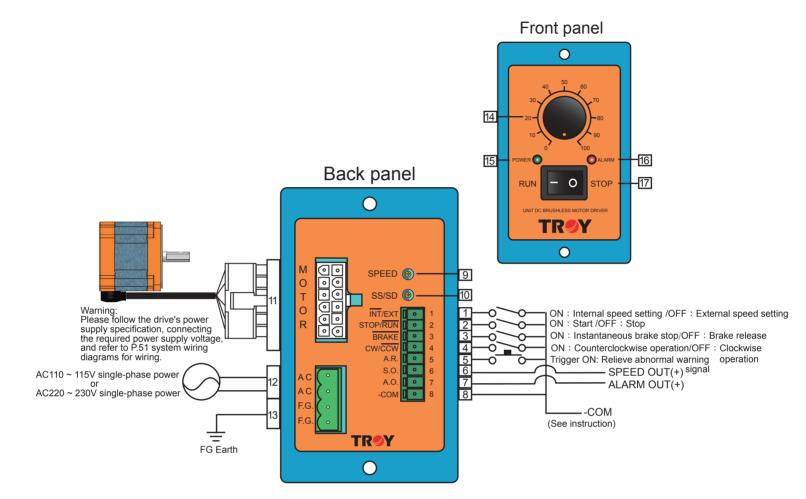






UBS series

■ Driver panel functions and wiring instructions



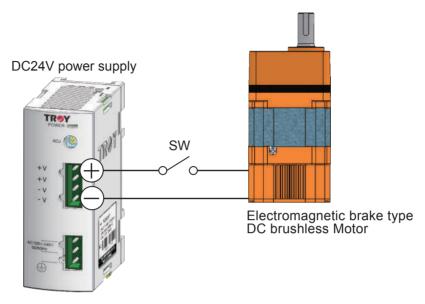
Number	Panel marked	Function	Explanation
1	ĪNT/EXT	Speed setting mode switch to select the input	Internal / external speed setting mode switching selection
2	STOP/RUN	Stop/Start signal input	Stop / start signal switching input
3	BRAKE	Instantaneous brake stop signal input	Executive instantaneous brake stop / brake release signal switch input
4	CW/CCW	The direction of rotation switch to select the input	Clockwise/counterclockwise operation switch selection
5	A.R.	Warning signs release abnormal input	AR trigger input contacts (continuous "L" state 10ms) to release the error warning signal
6	S.O.	Speed signal output	When Motor speed is detected using, digital signal output 12 Pulse / rev
7	A.O.	Abnormal warning signal output	Overload, overheating, over voltage, low voltage, disconnection of any of a protective function is activated, Motor stops naturally, and outputs an abnormality warning signal
8	-COM	Controlling signal grounding	GND contact inputs and outputs a control signal common ground wire, and the external DC power
9	SPEED	Speed setting button	20~90W speed control range:250~2000r/min
10	SS/SD	Slow start, stop time setting button	Slow start 0.5~8sec; slow stop 0.5~7sec
11	MOTOR	Motor wiring connector	Motor and Driver connection
12	AC	Power voltage input terminal	AC power voltage input connection
13	FG	Power ground terminal	Power ground connection
14	Scale button	Speed setting button	Rotating the knob clockwise to adjust the Motor speed from slow to fast speed range: 250 ~ 2000r/ min
15	POWER	Power indicator	Input Power LED (green) lights
16	ALARM	Unusual indicator	Overload, overheating, over-voltage, low voltage, disconnection of any of a protective function is activated LED (red) lights
17	RUN/STOP	Start / stop switch	Start / stop switch

В

Μ S

D

■ Motor electromagnetic brake wiring instructions



Operation instruction

Motor start/Motor stop with external electromagnetic brake operating procedures: Motor start: Must energize external electromagnetic brake before the Motor starts

Step :	External electromagnetic brake power ON
	Attracting waiting time (This is the time of the external electromagnetic brake actuation, the purpose: to keep the force is released)
	Motor Driver starting signal ON
	Motor starts running
Motor Stop :	The Motor is stopped before the operation do not yet fully external electromagnetic brake power.
Step :	Motor Driver stop signal ON
	Wait 0.2sec (reference value, this is the operation of the Motor to a complete stop time)
	External electromagnetic brake power is turned OFF
	Waiting for the release time (This is the external electromagnetic brake actuation time, purpose: To generate holding force)
	Motor stopped (a holding force)

1. This series of external electromagnetic brake using the brake power is part of the hold-type. 2.External electromagnetic brake is designed to allow the Motor stops when the holding force

has to be used as a safety brake, electromagnetic brake, do not use this as a Motor positioning or emergency brake applications.

3. Always to pull the Motor before starting the external electromagnetic brake energized (means no brakes); Motor stopped before the operation do not yet fully external electromagnetic brake

power (expressed brakes)

4.External electromagnetic brake suction time and release time value refer to the product specification. 5.Motor brakes to stop for about 0.2sec (test conditions in the Motor no-load speed 3000r / min, the electromagnetic brake is energized, the brake actuator signal ON time of the Driver, this time as a reference base, but the actual length of time will stop according to the inertia load or frictional load ... different load patterns and has fluctuated.

6.We recommend to do the actual measuring device operating time at the time of commissioning.



UBS series

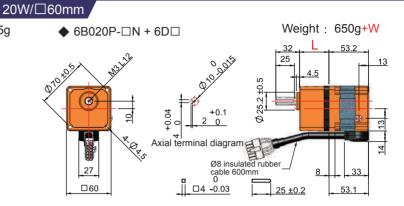
Dimensions - Motor/Gearhead

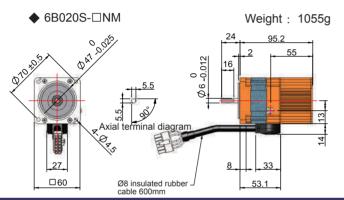
Unit: mm

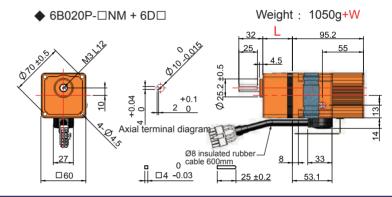
Round shaft type

Gear shaft type

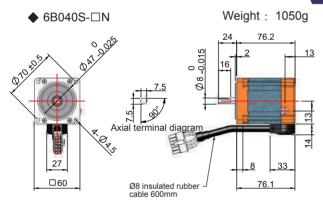
◆ 6B020S-□N Weight: 655g Axial terminal diagram Ø8 insulated rubber cable 600mm

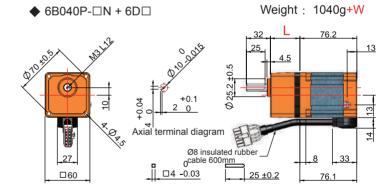




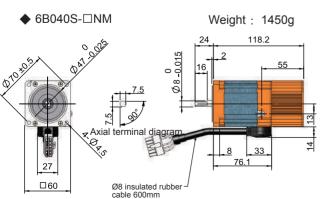


40W/□60mm





6B040P-□NM + 6D□



Weight: 1440g+W

* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

*6B pinion shaft type 6D3-6D360, Gearhead length L and weight W specification as following:

	Model	6D3~6D20	6D25~6D100	6D120~6D360
Gearhead	Length L (mm)	39.5	39.5	43.5
	Weight W (g)	300	325	365

Unit: mm

Weight: 2350g+W

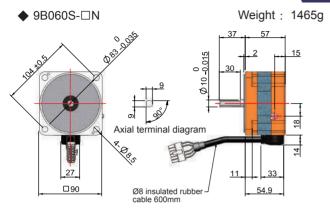
Weight: 3100g+W

■ Dimensions - Motor/Gearhead

Round shaft type

Gear shaft type

60W/□90mm



Weight: 1440g+W ♦ 9B060PD-□N + 9D□ NOA KOE (A) لى ا Axial terminal diagram Ø8 insulated rubber able 600mm □6 <u>-0.03</u>

◆ 9B060S-□NM Weight: 2215g 704.20.52 Axial terminal diagram

Ø8 insulated rubber cable 600mm

9B060PD-□NM + 9D□ Weight: 2190g+W 98.5 Axial terminal diagram Ø8 insulated rubbe 0 □6 **-**0.03 □90

90W/□90mm

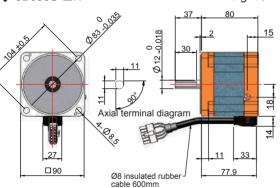
◆ 9B090PD-□N + 9D□

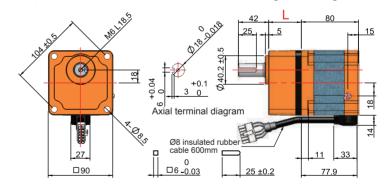
◆ 9B090PD-□NM + 9D□

♦ 9B090S-□N

Weight: 2380g

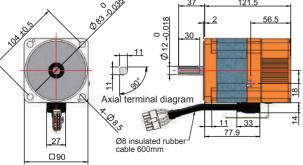
54.9





◆ 9B090S-□NM





* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

ره Axial terminal diagram Ø8 insulated rubber □6 <u>-0.03</u> □90 25 ±0.2 77.9

* 9B pinion shaft type 9D3-9D360, Gearhead length L and weight W specification as following: Model 9D3~9D20 9D25~9D100 9D120~9D360 ead Length L (mm 45.5 58.5 64.5 Weight W (g) 860 1125 1265



UBS series

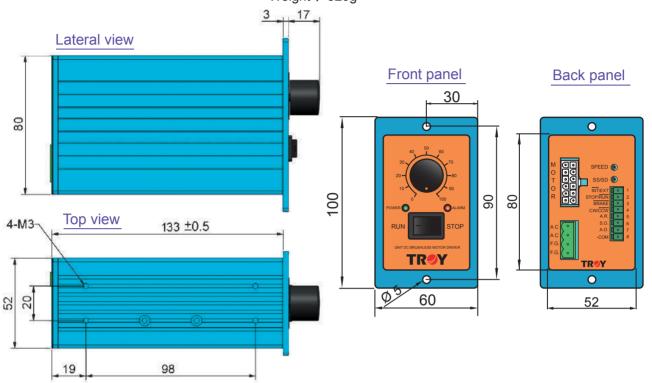
■ Dimensions - Driver

Model : UBD020-□N/UBD040-□N Dimensions are common Unit : mm

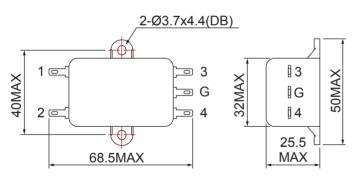
UBD060-□N/UBD090-□N

Weight: 50g

Weight: 520g



■ Dimensions - Power supply noise filter



* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.



DBS series

-The situation needs DC power control

Specifications and characteristics of Motor/Driver

Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD²)

Motor allowable radial load/axial load

Speed - Torque characteristic diagrams

Driver panel functions and wiring instructions

Motor electromagnetic brake wiring instructions

67 Dimensions - Motor/Gearhead

69 Dimensions - Driver

69 Dimensions - Variable resistor



DC Brushless Motor-DBS series

■ Specifications and characteristics of Motor/Driver

Motor	output po	wer	20W	40W	60W	100W			
Round shaft Motor (M: E/M brake type)			· , , , , , , , , , , , , , , , , , , ,		9B060S-D(M)	9B100S-D(M)			
Pinion s	shaft Motor	(M: E/M brake type)	6B020P-D(M)	6B040P-D(M)	9B060PD-D(M) 9B060PH-D	9B100PD-D(M) 9B100PH-D			
Motor sp	ecification c	ertificate	RoHS						
Driver			DBD020-D	DBD020-D DBD040-D DBD100-D DBD100-E					
Driver sp	pecification c	ertificate		C	€				
Input		Current Min.(A)	2	4	6	10			
Power Do Voltage	C23~26V	Rated current(A)	1.48	3.65	4.37	6.73			
Starting ⁻	Torque (Nm)	•	0.08	0.16	0.25	0.4			
Rated To	orque (Nm)		0.07	0.14	0.2	0.33			
Allowab	le load inertia	a GD²(Kgcm²)	4.78	9.55	11.3	20.8			
_	« Input pow	er voltage(V)	DC	224	DC	24			
series have E/M brake brake E/M Brake	Consumpt	tion power(W)	6	.5	7.	.5			
ries have ake E/M Brake	Maintenar	` /		.3	0.				
e E/M	Attraction	` ,		0		<u>3</u>			
	Release to	,	C	250~		5			
Орсси		To load	-2%Max. In 3000r / min, no-load ~rated load						
Speed v	/ariation rate		±2% Power voltage variation DC24V ± 10%, while in 3000r / min with no load						
орооц .		To Temperature							
Slow sta	art/Slow dowr	n time set up	When slow start $0.5 \sim 10$ sec, Motor from the $0 \sim 3000$ r / min, while no load When slow stop $0.5 \sim 5$ sec, Motor from the $3000 \sim 0$ r / min, while no load						
Speed o	control metho	od	•Controlled by an external variable resistor (resistance • By an external DC voltage control (DC0 ~ 5 · Controlling by internal variable resistor value 20ΚΩ) (2-speed also with an external variable resistor for switching control) •By an external DC voltage control (DC0 ~ 5 · /1mA or more control) •Can be used with D / A speed setter TRAC (optional)						
Signal in	nput/output n	nethod	Photo coupler(PHOTO COUPLER) Open collector transistor circuit(OPEN COLLECTOR) output interface						
Function	1		Contactless control (ZERO POINT), direct PLC or transistor type, relay-style I / O modules Within speed control range, Motor constant torque output (FLAT TORQUE) Instantaneous brake stop, slow start/slow stop (SLOW START/SLOW DOWN) When brake stop all electrical type cage effect						
Protection function			Protection function will be the following two kinds of situation: Motor will naturally stop, Driver ALARM contact signal output Overload Protection: Exceeding the rated torque of Motor running more than 7 seconds, it operates Low voltaage Protection: Driver input AC power voltage less than about 20%, it operates Offline Protection: When Motor cable disconnected, it operates disconnect power supply of internal controller, POWER light goes out Over voltage protection: When Driver input DC power voltage exceeds about 25%, it operates Reverse power protection: DC power voltage polarity is reversed, it operates						
Insulatio		Motor		egger test, the impedance					
impedan		Driver	vvnen using DC500V mi above 100MO Between coil and casing	egger test between power g, through to AC 1.8KV / 6	Input terminal and cabine	ned 1sec			
Insulatio		Motor	no abnormal condition	rminal and cabinet, through					
•		Driver	no abnormal condition			<u> </u>			
Ambient	temperature	Humidity range	iviotor u ~ + 50 ° C, Driv	rei 0 ~ + 40 ° C, 85% RH	or less (to avoid dust and	corrosive, flammable gas)			

TROY 111111111111

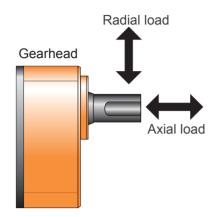
■ Gearhead specifications & allowable speed range/allowable torque/allowable inertia load (GD²)

Gear	ratio	3	3.6	5	6	7.5	9	10	12.5	15	18	20	25	30
Speed range	High speed	1000	883	600	500	400	333	300	240	200	166	150	120	100
(r/min)	Low speed	83.4	69.5	50	41.7	33.4	27.8	25	20	16.7	13.9	12.5	10	8.4
Allowable torque (Nm)	6B020P-D(M) + 6D□	0.18	0.21	0.29	0.35	0.44	0.53	0.59	0.73	0.88	1.1	1.2	1.4	1.7
Allowable iner	tia load GD² (kgcm²)	2.25	3.24	6.25	9.00	14.1	20.3	25.0	39.1	56.3	81.0	100	156	225
Allowable torque (Nm)	6B040P-D(M) + 6D□	0.35	0.42	0.59	0.7	0.88	1.1	1.2	1.5	1.8	2.1	2.3	2.8	3.4
Allowable iner	tia load GD ² (kgcm ²)	4.50	6.48	12.5	18.0	28.1	40.5	50.0	78.1	113	162	200	313	450
Allowable orque (Nm)	9B060PD-D(M) + 9D□	0.54	0.65	0.9	1.1	1.4	1.6	1.8	2.3	2.7	3.2	3.6	4.3	5.2
Allowable inert	tia load GD ² (kgcm ²)	18.0	25.9	50.0	72.1	113	162	200	313	450	649	801	1251	1802
Allowable torque (Nm)	9B060PH-D + 9D□H	0.54	0.65	0.9	1.1	1.4	1.6	1.8	2.3	2.7	3.2	3.6	4.3	5.2
Allowable inerti	ia load GD ² (kgcm ²)	181	260	501	722	1128	1624	2006	3134	4512	6498	8022	12534	18050
Allowable torque (Nm)	9B100PD-D(M) + 9D□	0.89	1.1	1.5	1.8	2.2	2.7	3.0	3.7	4.5	5.3	5.9	7.1	8.5
Allowable inerti	ia load GD² (kgcm²)	33.3	48.0	92.5	133	208	300	370	578	832	1199	1480	2312	3330
Allowable torque (Nm)	9B100PH-D + 9D□H	2.2	2.6	3.6	4.3	5.4	6.5	7.2	9	10.8	13	14.4	17.2	20.6
Allowable inerti	ia load GD² (kgcm²)	181	260	501	722	1128	1624	2006	3134	4512	6498	8022	12534	18050
Gear	ratio	36	50	60	75	90	100	120	150	180	200	250	300	360
Speed range	High speed	83	60	50	40	33	30	25	20	16	15	12	10	8
(r/min)	Low speed	7	5	4.2	3.4	2.8	2.5	2.1	1.7	1.4	1.3	1	0.9	0.7
Allowable torque (Nm)	6B020P-D(M) + 6D□	2	2.8	3.4	4.2	5	5.6	6.3			6	. 5		
Allowable inert	tia load GD ² (kgcm ²)	324			625						625			
Allowable torque (Nm)	6B040P-D(M) + 6D□	4	5.6		6	.5					6.5			
Allowable inert	tia load GD ² (kgcm ²)			62	25						625			
Allowable torque (Nm)	9B060PD-D(M) + 9D□	6.2	8.6	10.3	12.9	15.5	17.2	19.4	24.3	29.2	32.4		40	
Allowable inert	tia load GD ² (kgcm ²)	2594	5004	7206		11000					11000			
	9B060PH-D + 9D□H	6.2	8.6	10.3	12.9	15.5	17.2	19.4	24.3	29.2	32.4		40	
Allowable inert	tia load GD ² (kgcm ²)	25991			45000			45000						
Allowable torque (Nm)	9B100PD-D(M) + 9D□	10.2	14.2	17	21.3	25.5	28.4	32.1			40			
Allowable inerti	ia load GD ² (kgcm ²)	4795	9249		110	000					11000			
Allowable torque (Nm)	9B100PH-D + 9D□H	24.8	34.4	41.3		50		50						
Allowable inert	tia load GD² (kgcm²)	25991			45000			45000						

- *Gearhead 6D □/9D □/9D □H, please fill gear ratio in □.
- *■ In above table stands for after installation of Gearhead, the axis rotation is reversed with Motor axis direction; without marking stands for the same direction as Motor axis rotation.
- *1 Nm=10.19716 Kgcm
- *In addition to Gearhead 9D□H120~360 without RoHS ⊕ certificate, other series of Gearhead have RoHS ⊕ certificate
- * Also available orthogonal Gearhead: hollow shaft type 9VD (H), the solid single shaft type 9VD (A), the solid biaxial shaft type 9VD□B(H), and size please refer to P.10.



■ Motor allowable radial load/axial load



- Radial load (hanging load): loading is vertical to Gearhead axis power output
- 2 Axial load (thrust load): loading is in the direction of Gearhead axis power output

Round shaft type

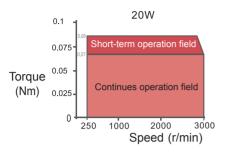
Model	Permissible overhui	Permissible thrust load		
Wodel	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)	
6B020S-D(M)	8	9	Permissible axial loading, not more than 1/2 of Motor weight. But please try to avoid applying	
6B040S-D(M)	8	9	force in the horizontal direction (axial) of motor shaft, when exceeds that will reduce Motor	
9B060S-D(M)	16	17	service life. If axial loading is needed, we recommend applying indirect	
9B100S-D(M)	16	17	transmission, such as: couplings, belts, chains, etc	

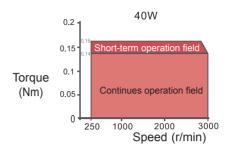
◆ Pinion shaft type (Gearhead attached)

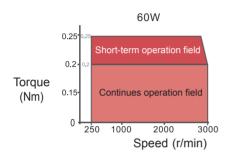
Madal	Gear ratio	Permissible overhur	ng load (Unit: Kg f)	Permissible thrust load	
Model	0.00.00	10mm from output shaft front	20mm from output shaft front	(Unit: Kg f)	
6B020P-D(M)	3, 3.6, 5	10	15		
+ 6D□ 6B040P-D(M)	6, 7.5, 9, 10, 12.5, 15,18, 20	15	20	4	
+ 6D□	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	20	30		
9B060PD-D(M)+9D□	3, 3.6, 5	30	40		
9B060PH-D+9D□H 9B100PD-D(M)+9D□	6, 7.5, 9, 10, 12.5, 15,18, 20	40	50	15	
9B100PH-D+9D□H	25, 30, 36, 50, 60, 75,90,100,120, 150, 180,200, 250, 300, 360	50	65		

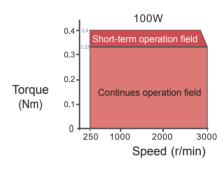
^{*}Gearhead 6D□/9D□/9D□H, please fill gear ratio in□

■ Speed - Torque characteristic diagrams



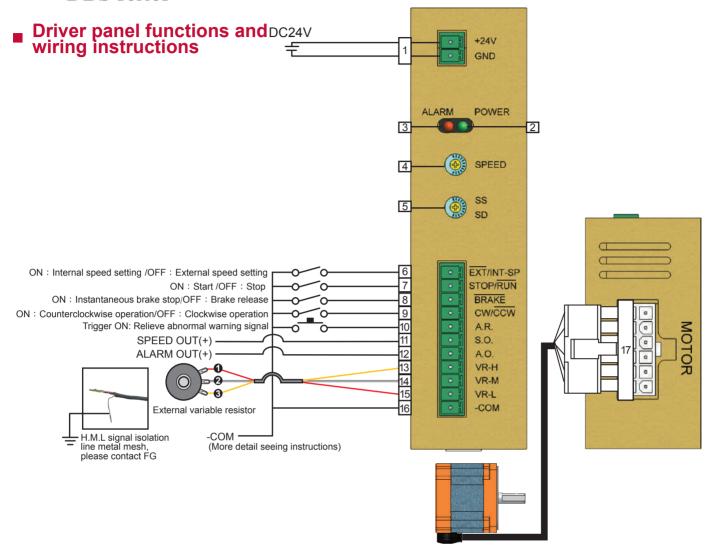






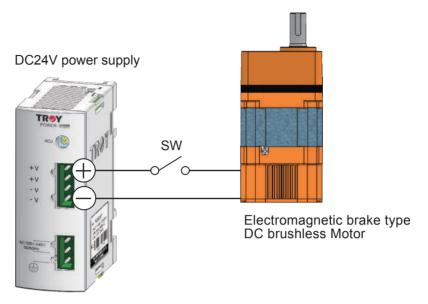


DBS series



Number	Panel marked	Function	Explanation
1	+24V \ GND	DC power voltage input terminal	DC power voltage input connection
2	POWER	Power indicator	LED (green) lights when input power
3	ALARM	Unusual indicator	Overload, low voltage, disconnection any protective function is activated LED (red) lights
4	SPEED	Internal speed setting button	20 ~ 100W speed control range: 250 ~ 3000r/min
5	SS/SD	Slow start, stop time setting button	Slow start 0.5 ~ 10 sec; slow stop 0.5 ~ 5 sec
6	EXT/INT-SP	Speed setting switch to select the input mode	External/internal speed setting mode switch selection
7	STOP/RUN	Stop/start signal input	Stop/start signal switch input
8	BRAKE	Instantaneous brake stop signal input	Executive instantaneous brake stop / brake release signal switch input
9	CW/CCW	The direction of rotation switch to select input	CW/CCW operation switch selection
10	A.R.	Abnormal warning signal release input	A.R. trigger input contacts (Length "L" state 10ms) to release the error of warning signal
11	S.O.	Speed signal output	Using while monitoring Motor speed, digital signal output 12Pulse/rev
12	A.O.	Abnormal warning signal output	Overload, low voltage, disconnection any protective function is activated, Motor stops naturally, and outputs an abnormality warning signal.
13	VR-H		
14	VR-M	Motor wiring connector	An external connection terminal variable resistor or external DC voltage (0 \sim 5V) control of speed control range: 250 \sim 3000r / min
15	VR-L		
16	-COM	Control signal grounding	GND contact inputs and outputs a control signal common ground wire, and the external DC power contact
17	MOTOR	Motor wiring connector	Motor and Driver connection

■ Electromagnetic brake wiring instructions



Operation instruction

Motor start/Motor stop with external electromagnetic brake operating procedures: Motor start: Must energize external electromagnetic brake before the Motor starts

Step: External electromagnetic brake power ON

Attracting waiting time (This is the time of the external electromagnetic brake actuation, the purpose: to keep the force is released)

Motor Driver starting signal ON

Motor starts running

The Motor is stopped before the operation do not yet fully external electromagnetic brake power. Motor Stop: Step:

Motor Driver stop signal ON

Wait 0.2sec (reference value, this is the operation of the Motor to a complete stop time)

External electromagnetic brake power is turned OFF

Waiting for the release time (This is the external electromagnetic brake actuation time, purpose: To generate holding force)

Motor stopped (a holding force)

Precautions

1. This series of external electromagnetic brake using the brake power is part of the hold-type.

2. External electromagnetic brake is designed to allow the Motor stops when the holding force has to be used as a safety brake, electromagnetic brake, do not use this as a Motor positioning or emergency brake applications.

3. Always to pull the Motor before starting the external electromagnetic brake energized (means no brakes); Motor stopped before the operation do not yet fully external electromagnetic brake power (expressed brakes).

4.External electromagnetic brake suction time and release time value refer to the product specification. 5. Motor brakes to stop for about 0.2sec (test conditions in the Motor no-load speed 3000r / min, the electromagnetic brake is energized, the brake actuator signal ON time of the Driver, this time as a reference base, but the actual length of time will stop according to the inertia load or frictional load ... different load patterns and has fluctuated.

6.We recommend to do the actual measuring device operating time at the time of commissioning.



DBS series

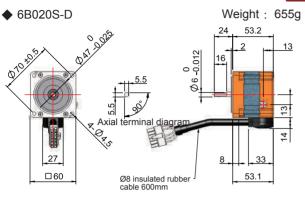
■ Dimensions - Motor/Gearhead

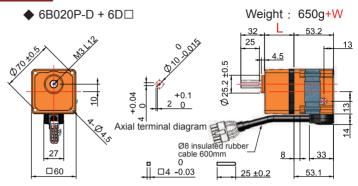
Round shaft type

Gear shaft type

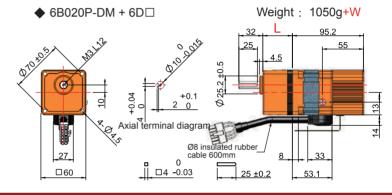
Unit: mm

20W/□60mm

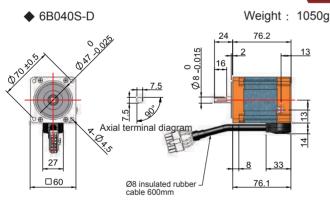


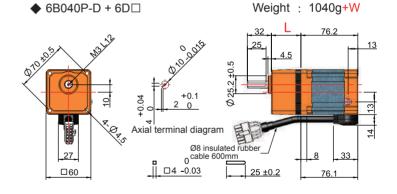


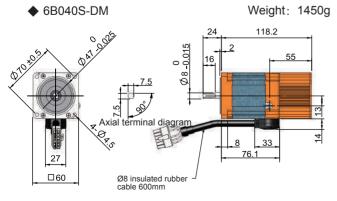
◆ 6B020S-DM Weight: 1055g 970405 0 -0.012 □60 Ø8 insulated rubber cable 600mm 53.1



40W/□60mm

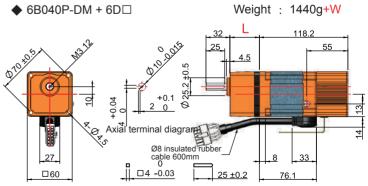






*Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

6B040P-DM + 6D□



★ 6B pinion shaft type 6D3-6D360, Gearhead length L and weight W specification as following:

	Model	6D3~6D20	6D25~6D100	6D120~6D360
	Length L (mm)	39.5	39.5	43.5
	Weight W (g)	300	325	365

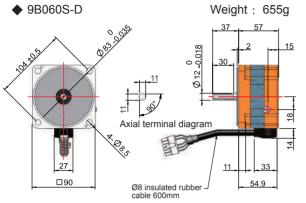
■ Dimensions - Motor/Gearhead

Round shaft type

Gear shaft type

Unit: mm

60W/□90mm



◆ 9B060PD-D + 9D□ Weight: 1500g+W Axial terminal diagram 0 □6 -0.03 □90 25 ±0.2

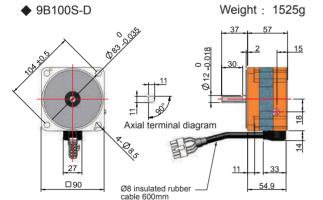
9B060S-DM Weight: 2275g 19A x05

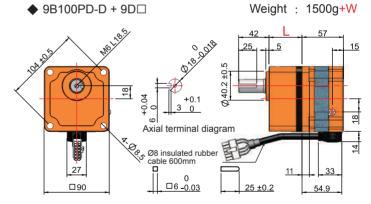
Ø8 insulated rubber cable 600mm

54.9

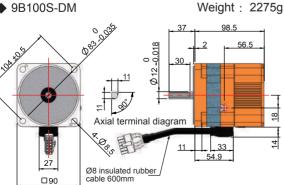
Weight: 2250g+W 9B060PD-DM + 9D□ Axial terminal diagram Ø8 insulated rubber 0 □6 -0.03 □90

100W/□90mm



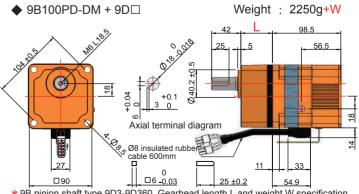


◆ 9B100S-DM



* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

◆ 9B100PD-DM + 9D□



* 9B pinion shaft type 9D3-9D360, Gearhead length L and weight W specification as following:

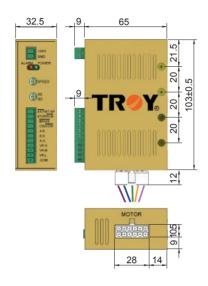
	Model	9D3~9D20	9D25~9D100	9D120~9D360	
Gearhead	Length L (mm)	45.5	58.5	64.5	
	Weight W (g)	860	1125	1265	



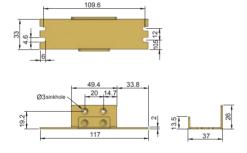
■ Dimensions - Driver

Model: DBD020-D / DBD040-D Dimensions

Weight: 210g are common

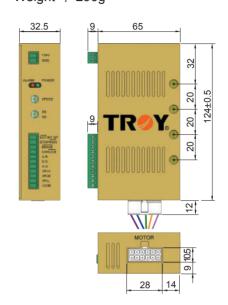


Mounting sheet

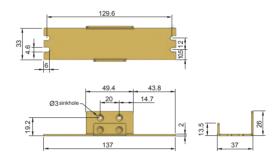


Model: DBD060-D / DBD100-D Dimensions Weight: 290g Dimensions

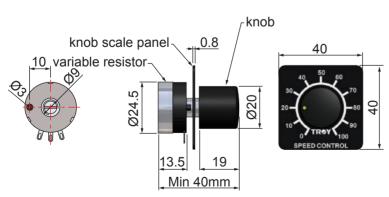
Unit: mm



Mounting sheet



■ Dimensions - Variable resistor



* Figure above dimensions tolerance values are not labeled a general machining tolerances, the control mode, refer to P.12, others have marked tolerance values according to the drawing labeled based.

■ Machanism: 【Opera	iting of larg	e index tab	le 】				Date dd/mn	n I yy
Company name:	Co	ntact persor	:		Departr	ment/Ti	tle:	
TEL:	FAX:		Application	:		Use a	rea:	
Power input: □Single -ph	nase AC:	V □Three	-phase AC:	V	□DC:	V	Frequency:	Hz
□Single stop t □Clock Stop:	llated speed e direction retime: Sec wise/counte	(Range: un \ stop \ ru cond/Sequen er clockwise Sequence \	rpm ~ rpr	n) Activation total (CW:	ated tim Sequ Seco	e: S uence / ond/Sec		ence,
□DBS \$	e shless motor Series	∵ □BMS Ser		ries [lMagnetic bra ⊐UBS Series	
[Mechanism reference]			se sketch you of mechanisr		ual trans	smissic	on	
Object W	LT							
Drive mechanism and	operating da	ıta]						
Object r	nass		W	=	kg			
Index ta	ble diamete	r	Dт	=	cm			
Width			Lт	=	cm			
Materia			ρ	=				
Position	ing angle	*(note)	θ	=	deg			
Position	ning time	*(note)	То	=	sec			
Stoppin	g accuracy			±	mm			
*(note)F	lease enter	the max spe	ed					
Recommendation produc	ts (Selecte	d specs) :						

After complete above information, please fax it to nearby regional business office, we will select

applicable product for you as soon as possible

■ Machanism: 【Lo	ead screw]			D	ate dd/mm	7 уу
Company name:		Contact person:	D	epartment/Tit	ile:	
TEL:	FAX:		Application:	Use ar	ea:	
Power input: □Sing	e -phase AC:	V	-phase AC:V	□DC: <u>V</u>	Frequency:	Hz
	Regulated spe Single direction stop time: Clockwise/cou Stop: Seco	eed (Range: on run \ stop \ ru Second/Sequen unter clockwise i	•	ited time: \$ Sequence Second/Se	/Minutes)	ence,
DC □E	orque brushless m DBS Series	otor: □BMS Ser	□Reversible □Sp ies □BS Series □ ohase □5 phase		J	
Mechanism refere	Object Level	W a	【Please sketch y part of mechani		nsmission	
(Drive mechanism Work+Table mas Screw angle Screw shaft diam Screw Length Screw pitch Material Screw efficiency Internal frictional	s	$W = _{_{_{_{_{_{_{_{_{_{_{_{_{_{_{_{_{_{_$	Positioning distar Positioning time Push / Pull force Stopping accurac	nce *(note) *(note)	F _A =k ±n	sec (g
pilot pressure nu	t		*(note)Please en	iter the max s	speed	

 $\label{lem:commendation} \textbf{Recommendation products} \ (\, \textbf{Selected specs} \,) \ :$

^{*} After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible

FAX: gle -phase AC: g	n operated (Ran n run \s Second/S nter cloc nd/Sequ ence/Min	Application: ☐Three -phase AC:\ cing continuously → ☐R nge: rpm ~ rpm) stop · run · stop → (Act Sequence; Run, stop to ckwise repeated → (CV nence · CCW:Secon	ated speed ivated time: tal Sequence V: Second/S d/Sequence \	Frequency: Second/Sequence /Minutes) Sequence >	
Ile -phase AC: IlSingle direction IRegulated spellsingle direction stop time: SIClockwise/cou Stop: Secon Stop: Sequelsinduction moto Torque C brushless mo	n operated (Ran n run \s Second/S nter cloc nd/Sequ ence/Min	Three -phase AC:\ ing continuously → □R ige: rpm ~ rpm) stop · run · stop → (Act Sequence; Run, stop to ckwise repeated → (CV ience · CCW:Secon nute)	ated speed ivated time: tal Sequence ∀: Second/S d/Sequence \	Frequency: Second/Sequence/Minutes) Sequence	
ISingle direction IRegulated specification is stop time: Stop: Second Stop: Sequection induction motor Torque C brushless mo	n operated (Ran n run \s Second/S nter cloc nd/Sequ ence/Min	ting continuously → □R lige: rpm ~ rpm) stop \ run \ stop → (Act Sequence; Run, stop to ckwise repeated → (CV lence \ CCW:Secon nute)	ated speed ivated time: tal Sequence V: Second/S d/Sequence \	Second/Seque /Minutes) Sequence \	
Regulated spe ISingle direction stop time: S IClockwise/cou Stop: Secon Stop: Seque induction moto Torque C brushless mo	ed (Ran n run \ s Second/S nter cloo nd/Sequ ence/Min	rge: rpm ~rpm) stop · run · stop → (Act Sequence; Run, stop to ckwise repeated → (CV sence · CCW:Secon nute)	ivated time: talSequence V:Second/S d/Sequence \	e /Minutes) equence >	ence
Torque C brushless mo		uction □Reversible □	Speed control	□Mognatia h	
			□SBS Series	_	
bject Belt Level	Motor	-		ssion	
and operating	data]				
$\alpha = $	deg cm cm	frictional coefficient of Positioning distance *(sliding surfaces note)	L =c To=s F _A =k	sec (g
	DBS Series epping motor: [ence] bject Belt LP1 W Level and operating Pulley W = DP1 = LP1 = P1 = DP2 =	DBS Series epping motor: □2 phase ence bject Motor Belt Motor Belt And operating data Pulley W =kg \[\alpha =kg \] \[\Delta =km \] \[\Delta 1 =km \] \[\Delta 1 =km \] \[\Delta 2 =km \] \[\Delta 2 =km \]	C brushless motor: □BMS Series □BS Series DBS Series epping motor: □2 phase □3 phase □5 phase ence] I Please sketch your part of mechanism] Digital part of mechanism] Pulley W =kg Belt pulley efficiency frictional coefficient of Positioning distance *(DP1 =cm Positioning time *(note p1 =cm Stopping accuracy	C brushless motor: □BMS Series □BS Series □SBS Series □BS Series □	C brushless motor: □BMS Series □BS Series □UBS Series □BS Series □BS Series □DBS Series □D

$\label{lem:Recommendation products} \mbox{ (Selected specs) } \mbox{ : }$

Material

*(note)Please enter the max speed

^{**} After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible

Company name: FAX:	peed time: Second/Sequence Sequence /Minutes) Second/Sequence \ uence \
Power input: □Single -phase AC:V □Three -phase AC:V □D Activated mode: □Single direction operating continuously → □Rated s □Regulated speed (Range: rpm ~ rpm) □Single direction run · stop · run · stop → (Activated stop time: Second/Sequence; Run, stop total S □Clockwise/counter clockwise repeated → (CW: S Stop: Second/Sequence · CCW: Second/Sequence · Stop: Sequence/Minute) Required motor: AC induction motor: □Induction □Reversible □Speed □Torque □C brushless motor: □BMS Series □BS Series □SB □DBS Series Stepping motor: □2 phase □3 phase □5 phase 【Drive mechanism and operating data】: Use the space below to draw	peed time: Second/Sequence Sequence /Minutes) Second/Sequence \ uence \
Activated mode: □Single direction operating continuously → □Rated s □Regulated speed (Range: rpm ~ rpm) □Single direction run · stop · run · stop → (Activated stop time: Second/Sequence; Run, stop total S □Clockwise/counter clockwise repeated → (CW: S Stop: Second/Sequence · CCW: Second/Sequence · Sequence/Minute) Required motor: AC induction motor: □Induction □Reversible □Speed □Torque □C brushless motor: □BMS Series □BS Series □SB □DBS Series Stepping motor: □2 phase □3 phase □5 phase 【Drive mechanism and operating data】: Use the space below to draw	peed time: Second/Sequence Sequence /Minutes) Second/Sequence \ uence \
□Regulated speed (Range: rpm ~ rpm) □Single direction run · stop · run · stop → (Activated stop time: Second/Sequence; Run, stop total S □Clockwise/counter clockwise repeated → (CW: S stop: Second/Sequence · CCW: Second/Sequence · Stop: Sequence/Minute) Required motor: AC induction motor: □Induction □Reversible □Speed □Torque □C brushless motor: □BMS Series □BS Series □SB □DBS Series Stepping motor: □2 phase □3 phase □5 phase 【Drive mechanism and operating data】: Use the space below to draw	time: Second/Sequence Sequence /Minutes) Second/Sequence \u00f3 uence \u00e7
□Torque □C brushless motor: □BMS Series □BS Series □SB □DBS Series Stepping motor: □2 phase □3 phase □5 phase □Drive mechanism and operating data]: Use the space below to draw	control □Magnetic brake
· · · · · · · · · · · · · · · · · · ·	S Series □UBS Series

Recommendation products (Selected specs):

^{*} After complete above information, please fax it to nearby regional business office, we will select applicable product for you as soon as possible





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