



# **PROGRAMMING MANUAL**

Digital Storage Oscilloscope

**MODEL: 2550 Series (2552, 2553, 2554, 2555, 2556, 2557,  
2558, 2559)**

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# Using Status Registers

A wide range of status registers allows the oscilloscope's internal processing status to be determined quickly at any time. These registers and the instrument's status reporting system are designed to comply with IEEE 488.2 recommendations. Following an overview, starting this page, each of the registers and their roles are described.

Related functions are grouped together in common status registers. Some, such as the Status Byte Register (STB) or the Standard Event Status Register (ESR), are required by the IEEE 488.2 Standard. Other registers are device-specific, and include the Command Error Register (CMR) and Execution Error Register (EXR). Those commands associated with IEEE 488.2 mandatory status registers are preceded by an asterisk <\*>.

## About these Commands & Queries

This section lists and describes the remote control commands and queries recognized by the instrument. All commands and queries can be executed in either local or remote state.

The description for each command or query, with syntax and other information, begins on a new page. The name (header) is given in both long and short form at the top of the page, and the subject is indicated as a command or query or both. Queries perform actions such as obtaining information, and are recognized by the question mark (?) following the header.

followed by a presentation of the formal syntax, with the header given in Upper-and-Lower Case characters and the short form derived from it in ALL UPPER-CASE characters. Where applicable, the syntax of the query is given with the format of its response.

sd

## Command Notation

The following notation is used in the commands:

- < > Angular brackets enclose words that are used as placeholders, of which there are two types: the header path and the data parameter of a command.
- := A colon followed by an equals sign separates a placeholder from the description of the type and range of values that may be used in a command instead of the placeholder.
- { } Braces enclose a list of choices, one of which one must be made.
- [ ] Square brackets enclose optional items.
- ... An ellipsis indicates that the items both to its left and right may be repeated a number of times.

As an example, consider the syntax notation for the command to set the vertical input sensitivity:

```
<channel>:VOLT_DIV <v_gain>  
<channel> := {C1, C2, C3, C4}  
<v_gain>:= 2 mV to 5 V
```

The first line shows the formal appearance of the command, with <channel> denoting the placeholder for the header path and <v\_gain> the placeholder for the data parameter specifying the desired vertical gain value. The second line indicates that one of four channels must be chosen for the header path. And the third explains that the actual vertical gain can be set to any value between 2 mV and 5 V.

# Table of Commands & Queries

<i>Short Form</i>	<i>Long Form</i>	<i>Subsystem</i>	<i>What the Command/Query Does</i>
ALST?	ALL_STATUS?	STATUS	Reads and clears the contents of all status registers.
ARM	ARM_ACQUISITION	ACQUISITION	Changes acquisition state from “stopped” to “single”.
ATTN	ATTENUATION	ACQUISITION	Selects the vertical attenuation factor of the probe
ACAL	AUTO_CALIBRATE	MISCELLANEOUS	Enables or disables automatic calibration.
ASET	AUTO_SETUP	ACQUISITION	Adjusts vertical, time and trigger parameters
AUTTS	AUTO_TYPESET	ACQUISITION	Selects the display type automatic setup.
AVGA	AVERAGE_ACQUIRE	ACQUISITION	Selects the average time of average acquisition
BWL	BANDWIDTH_LIMIT	ACQUISITION	Enables/disables the bandwidth-limiting low pass filter.
BUZZ	BUZZER	MISCELLANEOUS	Controls the built-in piezo-electric buzzer.
*CAL?	*CAL?	MISCELLANEOUS	Performs complete internal calibration of instrument.
CHDR	COMM_HEADER	COMMUNICATION	Controls formatting of query responses.
*CLS	*CLS	STATUS	Clears all status data registers.

CRST?	CURSOR_SET?	CURSOR	Allows positioning of one of eight cursors.
CRVA?	CURSOR_VALUE?	CURSOR	Returns trace values measured by specified cursors.
CRAU	CURSOR_AUTO	CURSOR	Changes the cursor mode to auto mode.
CSVS	CSV_SAVE	SAVE/RECALL	Saves specified waveform data of CSV format to USB device.
COUN	COUNTER	FUNCTION	Enables or disables the cymometer to display on the screen.
CYMT	CYMOMETER	FUNCTION	Returns the current cymometer value which is displaying on the screen.
DATE	DATE	MISCELLANEOUS	Changes the date/time of the internal real-time clock.
DDR?	DDR?	STATUS	Clears the Device Dependent Register (DDR).
DEF	DEFINE?	FUNCTION	Specifies math expression for function evaluation.
DELF	DELETE_FILE	MASS STORAGE	Deletes files from mass storage.
DIR	DIRECTORY	MASS STORAGE	Creates and deletes file directories.
DTJN	DOT_JOIN	DISPLAY	Controls the interpolation lines between data points.
*ESE	*ESE	STATUS	Sets the Standard Event Status Enable register (ESE).
*ESR?	*ESR?	STATUS	Reads, clears the Event Status Register (ESR).
			Reads, clears the

FILTS	FILT_SET	FUNCTION	Selects the type of filter and sets the limit value of filter.
FFTW	FFT_WINDOW	FUNCTION	Selects the window of FFT.
FFTZ	FFT_ZOOM	FUNCTION	Selects the zoom in/out times of FFT trace.
FFTS	FFT_SCALE	FUNCTION	Selects the vertical scale of FFT trace.
FFTF	FFT_FULLSCREEN	FUNCTION	Enables or disables to display the FFT trace screen.
GRDS	GRID_DISPLAY	DISPLAY	Selects the type of grid.
GCSV	GET_CSV	WAVEFORMTRANS	Specifies waveform data of format to controller.
HMAG	HOR_MAGNIFY	DISPLAY	Horizontally expands selected expansion trace.
HPOS	HOR_POSITION	DISPLAY	Horizontally positions intensified zone's center.
HCSU	HARDCOPY_SETUP	HARD COPY	Configures the hard-copy driver.
*IDN?	*IDN?	MISCELLANEOUS	For identification purposes.
INTS	INTENSITY	DISPLAY	Sets the grid or trace/intensity level.
ILVD	INTERLEAVED	ACQUISITION	Enables/disables random interleaved sampling (RIS).
INR?	INR?	STATUS	Reads, clears INTERNAL state change Register (INR).
INVS	INVERT_SET	DISPLAY	Invert the trace or the math waveform of specified source.
LOCK	LOCK	MISCELLANEOUS	Lock keyboard
			Enables or disables

			measure.
OFST	OFFSET	ACQUISITION	Allows output channel vertical offset adjustment.
*OPC	*OPC	STATUS	Sets the OPC bit in the Event Status Register (ESR).
*OPT?	*OPT?	MISCELLANEOUS	Identifies oscilloscope options.
PACL	PARAMETER_CLR	CURSOR	Clears all current parameters in Custom Pass/Fail.
PACU	PARAMETER_CUSTOM	CURSOR	Controls parameters with customizable qualifiers.
PAVA?	PARAMETER_VALUE?	CURSOR	Returns current parameter mask test values.
PDET	PEAK_DETECT	ACQUISITION	Switches the peak detector ON and OFF.
PERS	PERSIST	DISPLAY	Enables or disables the persistence display mode.
PESU	PERSIST_SETUP	DISPLAY	Selects display persistence duration.
PNSU	PANEL_SETUP	SAVE/RECALL	Complements the *SAV/*RST command.
PFDS	PF_DISPLAY	FUNCTION	Enables or disables to display the test and the message options of pass/fail.
PFST	PF_SET	FUNCTION	Sets the X mask and the mask.
PFSL	PF_SAVELOAD	SAVE/RECALL	Saves or recalls the created mask setting.
PFCT	PF_CONTROL	FUNCTION	Selects the "operate", "output" and the "stop output" which are the options of pass/fail.
			Creates the mask of



RCPN	RECALL_PANEL	SAVE/RECALL	Recalls a front-panel s from mass storage.
*RST	*RST	SAVE/RECALL	The *RST command initiates a device reset
REFS	REF_SET	FUNCTION	Sets the reference waveform and its opti
*SAV	*SAV	SAVE/RECALL	Stores current state in volatile internal memo
SCDP	SCREEN_DUMP	HARD COPY	Causes a screen dump controller.
SCSV	SCREEN_SAVE	DISPLAY	Controls the automatio screen saver.
*SRE	*SRE	STATUS	Sets the Service Requ Enable register (SRE)
*STB?	*STB?	STATUS	Reads the contents of IEEE 488.
STOP	STOP	ACQUISITION	Immediately stops sig acquisition.
STO	STORE	WAVEFORMTRANS	Stores a trace in inter memory or mass stora
STPN	STORE_PANEL	SAVE/RECALL	Stores front-panel setu mass storage.
STST	STORE_SETUP	WAVEFORMTRANS	Controls the way in w traces are stored.
SAST	SAMPLE_STATUS	ACQUISITION	Return the acquisition status of the scope
SARA	SAMPLE_RATE	ACQUISITION	Return the sample rate the scope
SANU	SAMPLE_NUM	ACQUISITION	Return the number of sampled points availab from last acquisition a the trigger position
SKEW	SKEW	ACQUISITION	Sets the skew of speci trace.
SET50	SETTO%50	FUNCTION	Sets the trigger level o trigger source to the

			command.
TRCP	TRIG_COUPLING	ACQUISITION	Sets the coupling mode for the specified trigger source.
TRDL	TRIG_DELAY	ACQUISITION	Sets the time at which the trigger is to occur.
TRLV	TRIG_LEVEL	ACQUISITION	Adjusts the trigger level for the specified trigger source.
TRMD	TRIG_MODE	ACQUISITION	the trigger mode.
TRSE	TRIG_SELECT	ACQUISITION	Selects the condition that will trigger acquisition.
TRSL	TRIG_SLOPE	ACQUISITION	Sets the trigger slope for the specified trigger source.
UNIT	UNIT	ACQUISITION	Sets the unit of specified trace.
VPOS	VERT_POSITION	DISPLAY	Adjusts the vertical position of the FFT trace.
VDIV	VOLT_DIV	ACQUISITION	Sets the vertical sensitivity.
VTCL	VERTICAL	ACQUISITION	Controls the vertical position of the slope trigger line.
WF	WAVEFORM	WAVEFORMTRANS	Gets the waveform from the instrument.
WFSU	WAVEFORM_SETUP	WAVEFORMTRANS	Specifies amount of waveform data to go to controller.
WAIT	WAIT	ACQUISITION	Prevents new analysis until current has been completed.
XYDS	XY_DISPLAY	DISPLAY	Enables or disables to display the XY format.

# Commands & Queries

*STATUS*

ALL\_STATUS?, ALST?  
**Query**

## **DESCRIPTION**

The ALL\_STATUS? Query reads and clears the contents of all status registers: STB, ESR, INR, DDR, CMR, EXR and URR except for the MAV bit (bit 6) of the STB register. For an interpretation of the contents of each register, refer to the appropriate status register.

The ALL\_STATUS? Query is useful in a complete overview of the state of the instrument.

## **QUERY SYNTAX**

ALI\_Status?

## **RESPONSE FORMAT**

ALI\_Status  
STB,<value>,ESR,<value>,INR,<value>,DDR,<value>  
e>,<value>,CMR,<value>,EXR,<value>,URR,<value>

<value> : = 0 to 65535

## **EXAMPLE**

The following instruction reads the contents of all the status registers:

Command message:  
ALST?

## *ACQUISITION*

ARM\_ACQUISITION, ARM  
**Command**

### **DESCRIPTION**

The ARM\_ACQUISITION command enables the signal acquisition process by changing the acquisition state (trigger mode) from “stopped” to “single”.

### **COMMAND SYNTAX**

ARM acquisition

### **EXAMPLE**

The following command enables signal acquisition:

Command message:  
ARM

### **RELATED COMMANDS**

STOP, \*TRG, TRIG\_MODE, WAIT

## *ACQUISITION*

## ATTENUATION, ATTN Command /Query

### **DESCRIPTION**

The ATTENUATION command selects the vertical attenuation factor of the probe. Values of 1, 5, 10, 50, 100, 500, and 1000 may be specified.

The ATTENUATION? Query returns the attenuation factor of the specified channel.

### **COMMAND SYNTAX**

<channel>: ATTeNuation <attenuation>  
<channel> := {C1, C2, C3, C4}  
<attenuation> := {1, 5, 10, 50, 100, 500, 1000}

### **QUERY SYNTAX**

<channel>: ATTeNuation?

### **RESPONSE FORMAT**

<channel>: ATTeNuation <attenuation>

### **EXAMPLE**

The following command sets to 100 the attenuation factor of Channel 1:

Command message:  
C1:ATTN 100

## MISCELLANEOUS

## AUTO\_CALIBRATE, ACAL Command /Query

### DESCRIPTION

The AUTO\_CALIBRATE command is used to enable or disable the quick calibration of the instrument.

The quick calibration may be disabled by issuing the command ACAL OFF. Whenever it is convenient, \*CAL? Query may be issued to fully calibrate the oscilloscope.

The response to the AUTO\_CALIBRATE? Query indicates whether quick -calibration is enabled.

The command is only used in the CFL series instrument.

### COMMAND SYNTAX

Auto\_CALibrate <state>  
<state> := {ON, OFF}

### QUERY SYNTAX

Auto\_CALibrate?

### RESPONSE FORMAT

Auto\_CALibrate <state>

### EXAMPLE

The following instruction disables quick-calibration

Command message:  
ACAL OFF

### RELATED COMMANDS

\*CAL?

## *ACQUISITION*

## AUTO\_SETUP, ASET Command

### **DESCRIPTION**

The AUTO\_SETUP command attempts to identify the waveform type and automatically adjusts control to produce a usable display of the input signal.

### **COMMAND SYNTAX**

AUTO\_SETUP

### **EXAMPLE**

The following command instructs the oscilloscope to perform an auto-setup:

Command message:  
ASET

### **RELATED COMMANDS**

AUTTS

## *ACQUISITION*

## AUTO\_TYPESET, AUTTS

**Command /Query**

### **DESCRIPTION**

The AUTO\_TYPESET command selects the specified type of automatically adjusting which is used to display.

### **COMMAND SYNTAX**

AUTO\_TYPESET <type>

<type> : = {SP,MP,RS,DRP,RC}

SP means only one period to be displayed, MP means multiple periods to be displayed, RS means the waveform is triggered on the rise side, DRP means the waveform is triggered on the drop side, and RC means to go back to the state before auto set.

### **QUERY SYNTAX**

AUTO\_TYPESET?

### **RESPONSE FORMAT**

AUTO\_TYPESET <type>

### **EXAMPLE**

The following command sets the type of automatic adjustment to multiple periods:

Command message:  
AUTTS MP

### **RELATED COMMANDS**

ASET



## *ACQUISITION*

AVERAGE\_ACQUIRE, AVGA  
**Command /Query**

### **DESCRIPTION**

The AVERAGE\_ACQUIRE command selects the average times of average acquisition.

The response to the AVERAGE\_ACQUIRE query indicates the times of average acquisition.

### **COMMAND SYNTAX**

AVERAGE\_ACQUIRE <time>

<time> : = {4, 16, 32, 64,128,256}

### **QUERY SYNTAX**

AVERAGE\_ACQUIRE?

### **RESPONSE FORMAT**

AVERAGE\_ACQUIRE <time>

### **EXAMPLE**

The following turns the average times of average acquisition 16:

Command message:  
AVGA 16

## ACQUISITION

## BANDWIDTH\_LIMIT, BWL Command /Query

### DESCRIPTION

BANDWIDTH\_LIMIT enables or disables the bandwidth-limiting low-pass filter. If the bandwidth filters are on, it will limit the bandwidth to reduce display noise. When you turn Bandwidth Limit ON, the Bandwidth Limit value is set to 20 MHz. It also filters the signal to reduce noise and other unwanted high frequency components.

The response to the BANDWIDTH\_LIMIT? Query indicates whether the bandwidth filters are on or off.

### COMMAND SYNTAX

```
BandWidth_Limit <channel>, <mode>  
[, <channel>, <mode> [, <channel>, <mode>  
[, <channel>, <mode>]]]
```

<channel> := {C1, C2, C3, C4}

<mode> := {ON, OFF}

### QUERY SYNTAX

```
BandWidth_Limit?
```

### RESPONSE FORMAT

```
BandWidth_Limit <channel>, <mode> [, <channel>  
<mode> [, <channel>, <mode> [, <channel>  
<mode>]]]
```

### EXAMPLE

The following turns on the bandwidth filter for all channels, when Global\_BWL is on (as it is by default).

The following turns the bandwidth filter on for Channel 1 only:

## MISCELLANEOUS

## BUZZER, BUZZ Command /Query

### DESCRIPTION

The BUZZER command enables or disables sound switch.

The response to the BUZZER? query indicates whether the sound switch is enabled.

### COMMAND SYNTAX

BUZZer <state>  
<state> := {ON, OFF}

### QUERY SYNTAX

BUZZER?

### RESPONSE FORMAT

BUZZER <state>

### EXAMPLE

Sending the following code will let the oscilloscope turn on the sound switch.

Command message:  
BUZZ ON

## MISCELLANEOUS

**\*CAL?**  
**Query**

### DESCRIPTION

The \*CAL? query cause the oscilloscope to perform an internal self-calibration and generates a response

### QUERY SYNTAX

\*CAL?

### RESPONSE FORMAT

\*CAL <diagnostics>  
<diagnostics> : = 0  
0 = Calibration successful

### EXAMPLE

The following instruction forces a self-calibration:

Command message:

\*CAL?

Response message:

\*CAL 0

### RELATED COMMANDS

AUTO\_CALIBRATE

## COMMUNICATION

## COMM\_HEADER, CHDR Command/ Query

### DESCRIPTION

The COMM\_HEADER command controls the way the oscilloscope formats responses to queries. There are three response formats: LONG, in which responses start with the long form of the header word; SHORT, where responses start with the short form of the header word; and OFF, for which headers are omitted from the response and units in numbers are suppressed.

Unless you request otherwise, the SHORT response format is used.

This command does not affect the interpretation of messages sent to the oscilloscope. Headers can be sent in their long or short form regardless of the COMM\_HEADER setting.

Querying the vertical sensitivity of Channel 1 may result in one of the following responses:

COMM_HEADER	RESPONSE
LONG	C1:VOLT_DIV 200E-3 V
SHORT	C1:VDIV 200E-3 V
OFF	200E-3

### COMMAND SYNTAX

Comm\_HeaDeR <mode>  
<mode> : = {SHORT, LONG, OFF}

### QUERY SYNTAX

Comm\_HeaDeR?

### RESPONSE FORMAT

Comm\_HeaDeR <mode>

### EXAMPLE

The following code sets the response header format

## *STATUS*

**\*CLS  
Command**

### **DESCRIPTION**

The \*CLS command clears all the status data registers.

### **COMMAND SYNTAX**

\*CLS

### **EXAMPLE**

The following command causes all the status data registers to be cleared:

Command message:

\*CLS

### **RELATED COMMANDS**

ALL\_STATUS, CMR, DDR, \*ESR, EXR, \*STB, URR

## *STATUS*

CMR?  
Query

### **DESCRIPTION**

The CMR? Query reads and clears the contents of the Command error Register (CMR) --- see table on next page---which specifies the last syntax error type detected by the instrument.

### **QUERY SYNTAX**

CMR?

### **RESPONSE FORMAT**

CMR <value>  
<value> : = 0 to 14

### **EXAMPLE**

The following instruction reads the contents of the CMR register:

Command message:  
CMR?

Response message:  
CMR 0

### **RELATED COMMANDS**

ALL\_STATUS? ,\*CLS

## ADDITIONAL INFORMATION

### Command Error Status Register Structure (CMR)

Command Error Status Register Structure (CMR)	
Value	Description
1	Unrecognized command/query header
2	Invalid character
3	Invalid separator
4	Missing parameter
5	Unrecognized keyword
6	String error
7	Parameter cannot allowed
8	Command String Too Long
9	Query cannot allowed
10	Missing Query mask
11	Invalid parameter
12	Parameter syntax error
13	Filename too long



## *MISCELLANEOUS*

## COMM\_NET, CONET Command /Query

### **DESCRIPTION**

The COMM\_NET command changes the IP address of the oscilloscope's internal network interface.

The COMM\_NET? query returns the IP address of the oscilloscope's internal network interface.

### **COMMAND SYNTAX**

COMM\_NET <ip\_add0>, <ip\_add1>,  
<ip\_add2>, <ip\_add3>

< ip\_add >:= 0 to 255

### **QUERY SYNTAX**

COMM\_NET?

### **RESPONSE FORMAT**

COMM\_NET <ip\_add0>, <ip\_add1>,  
<ip\_add2>, <ip\_add3>

### **EXAMPLE**

This instruction will change the IP address to 10.11.0.230:

Command message:  
CONET 10,11,0,230

## ACQUISITION

## COUPLING, CPL Command /Query

### DESCRIPTION

The COUPLING command selects the coupling mode of the specified input channel.

The COUPLING? query returns the coupling mode of the specified channel.

### COMMAND SYNTAX

<channel>: CouPLing <coupling>  
<channel> := {C1, C2, C3, C4}  
<coupling> := {A1M, A50, D1M, D50, GN  
The A of the <coupling> is alternating current.  
The D of the <coupling> is direct current.1M  
and 50 is the impedance of input. Some series  
(CML) couldn't have the set of input  
impedance.

### QUERY SYNTAX

<channel>: CouPLing?

### RESPONSE FORMAT

<channel>: CouPLing <coupling>

### EXAMPLE

The following command sets the coupling of Channel 2 to 50  $\Omega$ DC:

Command message:  
C2: CPL D50

## *CURSOR*

## CURSOR\_MEASURE, CRMS Command /Query

### DESCRIPTION

The CURSOR\_MEASURE command specifies the type of cursor or parameter measurement to be displayed

The CURSOR\_MEASURE? query indicates which cursors or parameter measurements are currently displayed.

Notation	
HREL	Selected tract-cursor mode
VREL	Selected manual-cursor mode and set to voltage type
AUTO	Selected auto mode
OFF	Cursors and parameters off

### COMMAND SYNTAX

CuRsor\_MeaSure <mode>  
<mode>={ OFF,HREL,VREL,AUTO}

### QUERY SYNTAX

CuRsor\_MeaSure?

### RESPONSE FORMAT

CuRsor\_MeaSure <mode>

### EXAMPLE

The following command determines cursor function is turned off:

Command message:  
CRMS OFF

## CURSOR

## CURSOR\_SET, CURSOR\_SET? Command /Query

### DESCRIPTION

The CURSOR\_SET command allows the user to position any one of the eight independent cursors at a given screen location. The positions of the cursors can be modified and queried even if the required cursor is not currently displayed on the screen. When setting a cursor position, a trace must be specified, relative to which the cursor will be positioned.

The CURSOR\_SET? Query indicates the current position of the cursor(s). The values returned depend on the grid type selected.

Notation	
HREF	The time value of curA under Track cursor mode
HDIF	The time value of curB under Track cursor mode
VREF	The volt-value of curA under manual cursor mode
VDIF	The volt -value of curB under manual cursor mode
TREF	The time value of curA under manual cursor mode
TDIF	The time value of curB under manual cursor mode

### COMMANDSYNTAX

<trace>:CuRsror\_SeT<cursor>,<position>[,<cursor>,<position>,<cursor> ,<position>]

< trace > := {C1, C2, C3, C4}

<cursor>

={HREF,HDIF,VREF,VDIF,TREF,TDIF}

<position> : = 0.1 to 11.9(or 17.9) DI  
(horizontal) of track; the range of

## RESPONSE FORMAT

<cursor> :={ HREF, HDIF, VREF, VDIF, TDIF, TRIF, TDIF }

## EXAMPLE

<trace>:CuRsor\_SeT <cursor>, <position> [, <cursor>, <position>, <cursor>, <position>]

The following command positions the VREF and VDIF cursors at +3 DIV and -1 DIV respectively, using C1 as a reference:

Command message:

C1: CRST VREF, 3DIV, VDIF, -1DIV

## RELATED COMMANDS

CURSOR\_MEASURE, CURSOR\_VALUE, PARAMETER\_VALUE

## CURSOR

## CURSOR\_VALUE?, CRVA?

Query

### DESCRIPTION

The CURSOR\_VALUE? Query returns the values measured by the specified cursors for given trace. (The PARAMETER\_VALUE? query is used to obtain measured waveform parameter values.)

Notation	
HREL	the cursor value under track cursor mode
VREL	the delta volt-value under manual cursor mode

### QUERY SYNTAX

```
<trace>: CuRsor_Value? [<mode>,...<mode>]
<trace> := { C1, C2, C3, C4 }
<mode> := { HREL, VREL }
```

### RESPONSE FORMAT

```
<trace> : CuRsor_Value HREL,
<B->T - A->T>,<B->V - A->V>,<A->T>,
<B->T>,
<(B->V - A->V)/(B->T - A->T)>
<trace> : CuRsor_Value VREL,<delta_vert>
```

### EXAMPLE

The following query reads the delta volt value under manual cursor mode (VREL) of Channel 2:

Command message:  
C2:CRVA? VREL

Response message:  
C2:CuRsor\_Value VREL 1.00V

### RELATED COMMANDS

CURSOR\_SET, PARAMETER\_VALUE

*CURSOR*

CURSOR\_AUTO, CRAU

**Command**

**DESCRIPTION**

The CURSOR\_AUTO command changes the cursor mode to auto mode

**COMMAND SYNTAX**

CRAU

**EXAMPLE**

The following code changes the cursor mode to auto mode

Command message:

CRAU

## *SAVE/RECALL*

CSV\_SAVE, CSVS  
**Command /Query**

### **DESCRIPTION**

The CSV\_SAVE command selects the specified option of storing CSV format waveform.

The CSV\_SAVE? query returns the option of storing waveform data of CSV format.

### **COMMAND SYNTAX**

CSV\_SAVE DD,<DD>,SAVE,<state>

The option DD is the data depth which is saved as parameter.  
The option SAVE is that if the waveform data is stored with parameter.

<DD>: ={MAX, DIS} the meaning of MAX is saved as the maximum data depth. The meaning of DIS is saved as the data depth which is displayed on the screen

<save>: = {OFF, ON}

### **QUERY SYNTAX**

CSV\_SAVE?

### **RESPONSE FORMAT**

CSV\_SAVE DD, <DD>, SAVE, <state>

### **EXAMPLE**

The following command sets the save data depth to the maximum and "para" save to off

Command message:

CSV\_SAVE DD,MAX,SAVE,OFF



## *FUNCTION*

COUNTER, COUN  
**Command /Query**

### **DESCRIPTION**

The COUNTER command enables or disables the cymometer display on the screen of instrument.

The response to the COUNTER? query indicates whether the cymometer is displayed on the screen of instrument.

### **COMMAND SYNTAX**

COUNTER <state>  
< state > := {ON, OFF}

### **QUERY SYNTAX**

COUNTER?

### **RESPONSE FORMAT**

COUNTER < state >

### **EXAMPLE**

The following command enables the cymometer display

Command message:  
COUN ON

*FUNCTION*

CYMOMETER, CYMT  
**Query**

**DESCRIPTION**

The response to the CYMOMETER? query is the value of the counter which displays on the screen of the instrument. When the signal frequency is less than 10Hz, it returns 10Hz.

**QUERY SYNTAX**

CYMOMETER?

**RESPONSE FORMAT**

CYMT <option>

**EXAMPLE**

The following instruction returns the value of the counter which displays on the screen of the instrument.

Response message:  
CYMT 10Hz

## MISCELLANEOUS

## DATE

### Command /Query

### DESCRIPTION

The DATE command changes the date/time of the oscilloscope's internal real-time clock.

The command is only used in the CFL series instrument.

### COMMAND SYNTAX

DATE <day>, <month>, <year>, <hour>, <minute>, <second>

<day> : = 1 to 31

<month> : = {JAN, FEB, MAR, APR, MAY, JUN, JUL, AUG, SEP, OCT, NOV, DEC}

<year> : = 1990 to 2089

<hour> : = 0 to 23

<minute> : = 0 to 59

<second> : = 0 to 59

### QUERY SYNTAX

DATE?

### RESPONSE FORMAT

DATE <day>, <month>, <year>, <hour>, <minute>, <second>

### EXAMPLE

This instruction will change the date to NOV. 1, 2009 and the time to 14:38:16:

Command message:

DATE 1, NOV, 2009,14,38,16

*STATUS*

DDR?  
Query

**DESCRIPTION**

The DDR? Query reads and clears the contents of the Device Dependent or device specific error Register (DDR). In the case of a hardware failure, the DDR register specifies the origin of the failure.

**QUERY SYNTAX**

DDR?

**RESPONSE FORMAT**

DDR <value>  
<value> : = 0 to 65535

**EXAMPLE**

The following instruction reads the contents of the DDR register:

Command message:  
DDR?

Response message:  
DDR 0

**RELATED COMMANDS**

ALL\_STATUS? , \*CLS

## *FUNCTION*

DEFINE, DEF  
Command /Query

### **DESCRIPTION**

The DEFINE command specifies the mathematical expression to be evaluated by a function.

### **COMMAND SYNTAX**

DEFine EQN,'<equation>'  
<equation> the mathematical expression

Function Equations	
<source1> + <source2>	Addition
<source1> - <source2>	Subtraction
<source1>*<source2>	Multiplication
<source1>/<source2>	Ratio
FFT(source x)	FFT

### **QUERY SYNTAX**

DEFine?

### **RESPONSE FORMAT**

DEFine EQN,'<equation>'

### **EXAMPLE**

Command message:  
DEFine EQN,'C1\*C2'

## *MASS STORAGE*

## DELETE\_FILE, DELF **Command**

### **DESCRIPTION**

The DELETE\_FILE command deletes files from the currently selected directory on mass storage.

### **COMMAND SYNTAX**

DELEte\_File DISK, <device>, FILE, '*<filename>*'  
<device>: = {UDSK}  
<filename>: = a file of specified directory and the specified file should be up to eight characters

### **EXAMPLE**

The following command deletes a front-panel setup from the directory named SETUP in USB memory device:

Command message:  
DELF DISK, UDSK, FILE, '/ SETUP /001.SETUP

### **RELATED COMMANDS DIRECTORY**

## *MASS STORAGE*

## DIRECTORY, DIR Command /Query

### DESCRIPTION

The DIRECTORY command is used to manage the creation and deletion of file directories on mass storage devices. It also allows selection of the current working directory and listing of files in the directory.

The query response consists of a double-quoted string containing a DOS-like listing of the directory.

### COMMAND SYNTAX

Directory DISK, <device>, ACTION, <action>  
'<directory>'

### QUERY SYNTAX

Directory? DISK, <device> [, '<directory>']  
<device>: = {UDSK}  
<action>: = {CREATE, DELETE}  
< directory >: = A legal DOS path or filename  
(This can include the '/' character to define the  
root directory.)

### RESPONSE FORMAT

DIRectory DISK, <device> "<directory>"

### EXAMPLE

The following asks for a listing of the directory on  
a USB memory device:

Command message:  
DIR? DISK, UDSK

Response message:  
DIRectory DISK, UDSK,"A:

*DISPLAY*

DOT\_JOIN, DTJN  
**Command /Query**

**DESCRIPTION**

The DOT\_JOIN command controls the interpolation lines between data points.

**COMMAND SYNTAX**

DoT\_JoiN <state>  
<state> := {ON, OFF}

**QUERY SYNTAX**

DoT\_JoiN?

**RESPONSE FORMAT**

DoT\_JoiN <state>

**EXAMPLE**

The following instruction turns off the interpolation lines:

Command message:  
DTJN OFF



## *STATUS*

**\*ESE  
Command /Query**

### **DESCRIPTION**

The \*ESE command sets the Standard Event Status Enable register (ESE). This command allows one or more events in the ESR register to be reflected in the ESB summary message bit (bit 5) of the STB register.

### **COMMAND SYNTAX**

\*ESE <value>  
<value> : = 0 to 255

### **QUERY SYNTAX**

\*ESE?

### **RESPONSE FORMAT**

\*ESE <value>

### **EXAMPLE**

The following instruction allows the ESB bit to be set if a user request (URQ bit 6, i.e. decimal 64) and/or a device dependent error (DDE bit 3, i.e. decimal 8) occurs. Summing these values yields the ESE register mask of 64+8=72.

Command message:  
\*ESE 72

### **RELATED COMMANDS**

\*ESR

*STATUS*

**\*ESR?**  
**Query**

**DESCRIPTION**

The \*ESR? query reads and clears the contents of the Event Status Register (ESR). The response represents the sum of the binary values of the register bits 0 to 7.

**QUERY SYNTAX**

\*ESR?

**RESPONSE FORMAT**

\*ESR <value>  
<value> : = 0 to 255

**EXAMPLE**

The following instruction reads and clears the contents of the ESR register:

Command message:

\*ESR?

Response message:

\*ESR 0

**RELATED COMMANDS**

ALL\_STATUS, \*CLS, \*ESE

## ADDITIONAL INFORMATION

<b>Standard Event Status Register (ESR)</b>					
Bit	Bit Value	Bit Name		Description	Note
15~8			0	reserved by IEEE 488.2	
7	128	PON	1	Power off-to-ON transition as occurred	(1)
6	64	URQ	1	User Request has been issued	(2)
5	32	CME	1	Command parser Error has been detected	(3)
4	16	EXE	1	Execution Error detected	(4)
3	8	DDE	1	Device specific Error occurred	(5)
2	4	QYE	1	Query Error occurred	(6)
1	2	RQC	1	Instrument never requests bus control	(7)
0	1	OPC	1	Instrument never requests bus control	(8)

## Notes

- (1) The Power On (PON) bit is always turned on (1) when the unit is powered up.
- (2) The User Request (URQ) bit is set true (1) when a soft key is pressed. An associated register URR identifies which key was selected. For further details refer to the URR? query.
- (3) The CoMmand parser Error bit (CME) is set true (1) whenever a command syntax error is detected. The CME bit has an associated CoMmand parser Register (CMR) which specifies the error code. Refer to the query CMR? for further details.
- (4) The EXecution Error bit (EXE) is set true (1) when a command cannot be executed due to some device condition (e.g. oscilloscope in local state) or a semantic error. The EXE bit has an associated Execution Error Register (EXR) which specifies the error code. Refer to query EXR? for further details.
- (5) The Device specific Error (DDE) is set true (1) whenever a hardware failure has occurred power-up, or execution time, such as a channel overload condition, a trigger or a timebase circuit defect. The origin of the failure may be localized via the DDR? or the self test \*TST? query.
- (6) The Query Error bit (QYE) is set true (1) whenever (a) an attempt is made to read data from the Output Queue when no output is either present or pending, (b) data in the Output Queue has been lost, (c) both output and input buffers are full (deadlock state), (d) an attempt is made by the controller to read before having sent an <END>, (e) a command is received before the response to the previous query was read (output buffer flushed).
- (7) The ReQuest Control bit (RQC) is always false (0), as the oscilloscope has no GPIB controlling capability.
- (8) The OPeration Complete bit (OPC) is set true (1) whenever \*OPC has been received, since all commands and queries are strictly executed in sequential order. The oscilloscope starts processing a command only when the previous command has been entirely executed.

*STATUS*

\*EXR?  
Query

**DESCRIPTION**

The EXR? query reads and clears the content of the Execution error Register (EXR). The EXR register specifies the type of the last error detected during execution.

**QUERY SYNTAX**

EXR?

**RESPONSE FORMAT**

EXR <value>  
<value> : = to

**EXAMPLE**

The following instruction reads the contents of the EXR register:

Command message:  
EXR?

Response message (if no fault):  
EXR 0

**RELATED COMMANDS**

ALL\_STATUS, \*CLS

## ADDITIONAL INFORMATION

### Execution Error Status Register Structure (EXR)

Value	Description
21	Permission error. The command cannot be executed in local mode.
22	Environment error. The instrument is not configured to correctly process command. For instance, the oscilloscope cannot be set to RIS at a slow timebase.
23	Option error. The command applies to an option which has not been installed.
25	Parameter error. Too many parameters specified.
26	Non-implemented command.
32	Waveform descriptor error. An invalid waveform descriptor has been detected.
36	Panel setup error. An invalid panel setup data block has been detected.
50	No mass storage present when user attempted to access it.
53	Mass storage was write protected when user attempted to create, or a file, to delete file, or to format the device.
58	Mass storage file not found.
59	Requested directory not found.
61	Mass storage filename not DOS compatible, or illegal filename.
62	Cannot write on mass storage because filename already exists.

## *MASS STORAGE*

## FILENAME, FLNM Command /Query

### **DESCRIPTION**

The FILENAME command is used to change the default filename given to any traces, setups and hard copies when they are being stored to a mass storage device.

### **COMMAND SYNTAX**

FiLeNaMe TYPE, <type>, FILE, '<filename>'  
<type>:={ C1,C2,C3, C4, SETUP,TA, TB, TC, TD, HCOPIY }  
<filename> : = an alphanumeric string of up to characters forming a legal DOS filename.

Note: the file's extension can be specified automatically by the oscilloscope.

### **QUERY SYNTAX**

FiLeNaMe? TYPE, <type>  
<type> :={ ALL, C1, C2, C3, C4, SETUP, TA, TB, TC, TD, HCOPIY }

### **RESPONSE FORMAT**

FiLeNaMe TYPE, <type>, FILE, "<filename>"  
[,TYPE, <type>, FILE, "<filename>"...]

### **EXAMPLE**

The following command designates channel 1 waveform files to be "TESTWF.DAV":

Command message:  
FLNM TYPE, C1, FILE, 'TESTWF'

### **RELATED COMMANDS**

DIRECTORY, DELETE\_FILE

## *ACQUISITION*

FORCE\_TRIGGER, FRTR

**Command**

### **DESCRIPTION**

Causes the instrument to make one acquisition

### **COMMAND SYNTAX**

FoRce\_TRigger

### **EXAMPLE**

Either of the following pairs of instruction make one acquisition:

Command message1:

TRMD SINGLE;ARM;FRTR

Command message2:

TRMD STOP;ARM;FRTR



## *MASS STORAGE*

## FORMAT\_VDISK, FVDISK

**Query**

### **DESCRIPTION**

The FORMAT\_VDISK? query reads the capability of the USB memory device.

### **QUERY SYNTAX**

Format\_VDISK?

### **RESPONSE FORMAT**

Format\_VDISK <capability>  
<capability>:= the capability of the USB memory device.

### **EXAMPLE**

The following query reads the capability of the USB device.

Command message:  
Format\_VDISK?

Response message:  
Format\_VDISK 963 MB

## *FUNCTION*

## **FILTER, FILTER?** **Command /Query**

### **DESCRIPTION**

The FILTER command enables or disables filter of the specified trace.

The response to the FILTER? query indicates whether the filter of specified trace is enabled

### **COMMAND SYNTAX**

<channel>:FILTER <state>  
<channel> : = {C1,C2,C3,C4}  
<state> : = {ON,OFF}

### **QUERY SYNTAX**

<channel>:FILTER?

### **RESPONSE FORMAT**

<channel>:FILTER <state>

### **EXAMPLE**

The following command enables the filter of channel 1:

Command message:  
C1:FILT ON

### **RELATED COMMANDS**

FILTS

## *FUNCTION*

FILT\_SET, FILTS  
Command /Query

## **DESCRIPTION**

The FILT\_SET command selects the specified type of filter, and sets the limit value of filter.

The response to the FILT\_SET? query indicates current parameter of the filter

## **COMMAND SYNTAX**

<channel>: FILT\_SET TYPE,<type>,  
                  <limit>,<limit\_value>  
<channel> : = {C1,C2,C3,C4}  
<type> : = {LP,HP,BP,BR}

LP is lowpass, HP is highpass, BP is bandpass, BR is bandreject

<limit> : = {UPPLIMIT,LOWLIMIT}  
if seted the <limit>,the <type> must be related

## **QUERY SYNTAX**

<channel>: FILT\_SET?

## **RESPONSE FORMAT**

<limit\_value >

<channel>:FILTER TYPE,<type>,<limit>,

## **EXAMPLE**

The following command changes the type of filter to bandpass, and sets the upplimit to 200 KHz and the lowlimit to 100 KHz:

Command message:  
C1:FILTS TYPE,BP,  
UPPLIMIT,200KHz,LOWLIMIT,100KHz

## *FUNCTION*

FFT\_WINDOW, FFTW  
**Command /Query**

### **DESCRIPTION**

The FFT\_WINDOW command selects the window of FFT(Fast Fourier Transform algorithm).

The response to the FFT\_WINDOW? query indicates current window of FFT

### **COMMAND SYNTAX**

FFT\_WINDOW <window>  
< window > := {RECT,BLAC,HANN,HAMM  
RECT is short for rectangle.  
BLAC is short for Blackman.  
HANN is short for hanning.  
HAMM is short for hamming,

### **QUERY SYNTAX**

FFT\_WINDOW?

### **RESPONSE FORMAT**

FFT\_WINDOW,<window>

### **EXAMPLE**

The following command sets the FFT window to hamming:

Command message:  
FFTW HAMM

## *FUNCTION*

FFT\_ZOOM, FFTZ  
**Command /Query**

### **DESCRIPTION**

The FFT\_ZOOM command selects the specific zoom of FFT.

The response to the FFT\_ZOOM? query indicates current zoom in/out times of FFT

### **COMMAND SYNTAX**

FFT\_ZOOM <zoom>  
< zoom > : = {1,2,5,10}

### **QUERY SYNTAX**

FFT\_ZOOM?

### **RESPONSE FORMAT**

FFT\_ZOOM,<zoom>

### **EXAMPLE**

The following command sets the zoom factor of FFT to 1X:

Command message:  
FFTZ 1

## *FUNCTION*

FFT\_SCALE, FFTS  
**Command /Query**

## **DESCRIPTION**

The FFT\_SCALE command selects the specified scale of FFT(Fast Fourier Transform algorithm).

The response to the FFT\_SCALE? query indicates current vertical scale of FFT waveform.

## **COMMAND SYNTAX**

FFT\_SCALE <scale>  
< scale > : = {VRMS,DBVRMS}

## **QUERY SYNTAX**

FFT\_SCALE?

## **RESPONSE FORMAT**

FFT\_SCALE,< scale >

## **EXAMPLE**

The following command turns the vertical scale of FFT to dBVRms:

Command message:  
FFTS DBVRMS

## *FUNCTION*

FFT\_FULLSCREEN, FFTF  
**Command /Query**

## **DESCRIPTION**

The FFT\_FULLSCREEN command enables or disables to display the FFT waveform full screen.

The response to the FFT\_FULLSCREEN? query indicates whether the FFT waveform is full screen displayed.

## **COMMAND SYNTAX**

FFT\_FULLSCREEN <state>  
< state > : = {ON,OFF}

## **QUERY SYNTAX**

FFT\_FULLSCREEN?

## **RESPONSE FORMAT**

FFT\_FULLSCREEN < state >

## **EXAMPLE**

The following command enables to display the FFT waveform full screen:

Command message:  
FFTF ON

*DISPLAY*

GRID\_DISPLAY, GRDS  
**Command /Query**

**DESCRIPTION**

The GRID\_DISPLAY command selects the type of the grid which is used to display.

The response to the GRID\_DISPLAY? query indicates current type of the grid

**COMMAND SYNTAX**

GRID\_DISPLAY <type>  
< type > := {FULL,HALF,OFF}

**QUERY SYNTAX**

GRID\_DISPLAY?

**RESPONSE FORMAT**

GRID\_DISPLAY < type >

**EXAMPLE**

The following command changes the type of grid to full grid:

Command message:  
GRID\_DISPLAY FULL



## *WAVEFORMTRANS*

## GET\_CSV, GCSV Query

### **DESCRIPTION**

indicates current waveform of CSV format.

The response to the GET\_CSV? query

The GET\_CSV? query have two options to set. They are the same as the options of CSVS.

### **QUERY SYNTAX**

GET\_CSV? DD,<DD>,SAVE,<state>

The option DD is the data depth of the CSV format waveform. The option SAVE is that if the waveform data have parameters.

<DD>: = {MAX, DIS} the meaning of MAX is that the CSV waveform's depth is maximum. The meaning of DIS is that CSV waveform's depth is the data which is displayed on the screen.

<save>: = {OFF,ON}

### **RESPONSE FORMAT**

the waveform data of CSV format

### **EXAMPLE**

The following command transfers the waveform data of CSV format to the controller. It has the maximum depth of waveform data with parameters information

Command message:

GET\_CSV? DD,MAX,SAVE,ON

## *DISPLAY*

## HOR\_MAGNIFY, HMAG

**Command /Query**

### **DESCRIPTION**

The HOR\_MAGNIFY command horizontally expands the selected expansion trace by a specified factor. Magnification factors must be within the range of permissible values and will be rounded off to the closest legal value.

If the specified factor is too large for any of the expanded traces (depending on their current source), it is reduced to an acceptable value and only then applied to the traces. The VAB bit (bit 2) in the STB register is set when a factor outside the legal range is specified.

The HOR\_MAGNIFY query returns the current magnification factor for the specified expansion function.

### **COMMAND SYNTAX**

<exp\_trace>: Hor\_MAGnify <factor>  
<exp\_trace>: = {TA, TB, TC, TD}  
<factor> : = 1 to 50,000,000 The range of  
<factor> it is related to the current timebase  
and the range of the timebase

### **QUERY SYNTAX**

<exp\_trace> : Hor\_MAGnify?

### **RESPONSE FORMAT**

<exp\_trace>: Hor\_MAGnify <factor>

### **EXAMPLE**

The following instruction horizontally magnifies Trace A (TA) by a factor of 5:

## *DISPLAY*

## HOR\_POSITION, HPOS

**Command /Query**

### **DESCRIPTION**

The HOR\_POSITION command horizontally positions the geometric center of the intensified zone on the source trace. Allowed positions range from division -9 to 9. If this would cause the horizontal position of any expanded trace to go outside the left or right screen boundaries, the difference of positions is adapted and then applied

to the traces.

The VAB bit (bit 2) in the STB register is set if value outside the legal range is specified.

The HOR\_POSITION query returns the position of the geometric center of the intensified zone of the source trace.

### **COMMAND SYNTAX**

<exp\_trace>: Hor\_POSITION <hor\_position>

<exp\_trace>: = {TA, TB, TC, TD}

<hor\_position>: = -9 to 9 DIV(The range of the value is related to the size of the screen). the range of the <hor\_position> is related to the magnification factors of command HMAG. When the range after magnifying beyond the screen could display, it will be adjusted to the proper value.

### **QUERY SYNTAX**

<exp\_trace>: Hor\_POSITION?

### **RESPONSE FORMAT**

<exp\_trace>: Hor\_POSITION <hor\_position>

### **EXAMPLE**

The following instruction positions the center of

## *HARD COPY*

### **DESCRIPTION**

### **COMMAND SYNTAX**

### **QUERY SYNTAX**

### **RESPONSE FORMAT**

### **EXAMPLE**

### **RELATED COMMANDS**

## HARDCOPY\_SETUP, HCSU Command /Query

The HARDCOPY\_SETUP command configures the instrument's hard-copy driver.

HCSU PSIZE, <page\_size>, ISIZE, <image\_size>, FORMAT, <format>, BCKG, <bckg>, PRTKEY, <printkey>

<page\_size> := { DEFAULT }  
<printkey> := { SAVE, PRINT }  
<format> := { PORTRAIT, LANDSCAPE }  
<bckg> := { BLACK, WHITE }  
<image\_size> := { DEFAULT, A4, LETTER }.

HCSU?

HCSU PSIZE, <page\_size>, ISIZE, <image\_size>, FORMAT, <format>, BCKG <bckg>, PRTKEY, <printkey>

The following example selects PORTRAIT format, sets the size of the image to "6\*8CM

Command message:  
HCSU ISIZE, 6\*8CM, FORMAT  
PORTRAIT

SCDP

## MISCELLANEOUS

**\*IDN?  
Query**

### DESCRIPTION

The \*IDN? query is used for identification purposes`. The response consists of four different fields providing information on the manufacturer, the scope model, the serial number and the firmware revision level.

### QUERY SYNTAX

\*IDN?

### RESPONSE FORMAT

\*IDN SIGLENT, <model>, <serial\_number>  
<firmware\_level>  
<model> := A eleven characters model identifier  
<serial\_number> := A 14-digit decimal code  
<firmware\_level> := similar to k.xx.yy.zz

### EXAMPLE

This example issues an identification request to the scope:

Command message:

\*IDN?

Response message:

\*IDN

B&K Precision, 2553,SN#,  
3.01.01.22

## *DISPLAY*

## INTENSITY, INTS

**Command /Query**

### **DESCRIPTION**

The INTENSITY command sets the intensity level of the grid or the trace.

The intensity level is expressed as percentage (PCT). A level of 100 PCT corresponds to the maximum intensity while a level of 0 PCT sets the intensity to its minimum value. (The minimum value of the trace is 30 PCT)

The response to the INTENSITY? Query indicates the grid and trace intensity levels.

### **COMMAND SYNTAX**

INTensity GRID, <value>, TRACE, <value>  
<value> : = 0(or 30) to 100 [PCT]

Note 1: Parameters are grouped in pairs. The first of the pair names the variable to be modified, whilst the second gives the new value to be assigned. Pairs may be given in any order and be restricted to those variables to be changed.

Note 2: The suffix PCT is optional.

### **QUERY SYNTAX**

INTensity?

### **RESPONSE FORMAT**

INTensity TRACE, <value>, GRID, <value>

### **EXAMPLE**

The following instruction enables remote

## *ACQUISITION*

## INTERLEAVED, ILVD

**Command /Query**

### **DESCRIPTION**

The INTERLEAVED command enables or disables random interleaved sampling (RIS) for timebase settings where both single shot and RIS mode are available.

The response to the INTERLEAVED? Query indicates whether the oscilloscope is in RIS mode.

### **COMMAND SYNTAX**

InterLeaVeD <mode>  
<mode> := {ON, OFF}

### **QUERY SYNTAX**

InterLeaVeD?

### **RESPONSE FORMAT**

InterLeaVeD <mode>

### **EXAMPLE**

The following instructs the oscilloscope to use RIS mode:

Command message:  
ILVD ON

### **RELATED COMMANDS**

TIME\_DIV, TRIG\_MODE

## STATUS

INR?  
Query

### DESCRIPTION

The INR? query reads and clears the contents of the INternal state change Register(INR). The INR register (table below) records the completion of various internal operations and state transitions.

Note : This command only supports 0 bit and 1 bit.

Internal State Register Structure (INR)			
Bit	Bit Value	Description	
15...14		0	Reserved for future use
13	8192	1	Trigger is ready
12	4096	1	Pass/Fail test detected desired outcome
11	2048	1	Waveform processing has terminated in Trace D
10	1024	1	Waveform processing has terminated in Trace C
9	512	1	Waveform processing has terminated in Trace B
8	256	1	Waveform processing has terminated in Trace A
7	128	1	A memory card, floppy or hard disk exchange has been detected
6	64	1	Memory card, floppy or hard disk has become full in "AutoStore Fill" mode
5	32	0	Reserved for LeCroy use
4	16	1	A segment of a sequence waveform has been acquired
3	8	1	A time-out has occurred in a data block transfer
2	4	1	A return to the local state is detected
1	2	1	A screen dump has terminated
0	1	1	A new signal has been acquired



Response message1:  
INR 8913

If we send INR? query while the instrument didn't trigger, the INR register:

Command message2:  
INR?

Response message2:  
INR 8912

If we send INR? query after have sent a INR? query and the mode of the instrument is STOP  
The INR register:

Command message3:  
INR?

Response message3:  
INR 0

If we send INR? query while there is no and then make the instrument triggered. Finally we send another INR? query  
the INR register:

Command message4:  
INR?

Response message4:  
INR 1

*DISPLAY*

**INVERTSET, INVS**  
**Command /Query**

## **DESCRIPTION**

The INVERTSET command inverts the specified traces or the waveform of math.

The response to the INVERTSET? query indicates whether the specified waveform invert.

## **COMMAND SYNTAX**

<trace>:INVERTSET < state >  
< trace > := {C1,C2,C3,C4,MATH}  
< state >:= {ON,OFF}

## **QUERY SYNTAX**

<trace>:INVERTSET?

## **RESPONSE FORMAT**

<trace>:INVERTSET < state >

## **EXAMPLE**

The following instruction inverts the trace of channel 1:

Command message:  
C1:INVS ON

## MISCELLANEOUS

## LOCK, LOCK Command /Query

### DESCRIPTION

The LOCK command enables or disables the panel keyboard of the instrument.

When any command or query is executed in either local or remote state, the functions of the panel keys except "FORCE" are not available. When the panel keyboard of the instrument is locked, press "FORCE" key can enable the panel keyboard function.

The LOCK? query returns the status of the panel keyboard of the instrument.

### COMMAND SYNTAX

LOCK < status >  
<status>:= {ON,OFF}

### QUERY SYNTAX

LOCK?

### RESPONSE FORMAT

LOCK < status >

### EXAMPLE

The following instruction enables the functions of the panel keys:

Command message:  
LOCK ON

*DISPLAY*

**MENU, MENU**  
**Command /Query**

**DESCRIPTION**

The MENU command enables or disables to display the menu.

The response to the MENU? query indicates whether the menu is displayed.

**COMMAND SYNTAX**

MENU < status >  
<status>:= {ON,OFF}

**QUERY SYNTAX**

MENU?

**RESPONSE FORMAT**

MENU < status >

**EXAMPLE**

The following instruction enables the display of the menu:

Command message:  
MENU ON

## *ACQUISITION*

## MATH\_VERT\_POS, MTVP Command /Query

### **DESCRIPTION**

The MATH\_VERT\_POS command controls the vertical position of the math waveform with specified source.

The FFT waveform isn't included. But we have another command which called VPOS to control its vertical position.

The response to the MATH\_VERT\_POS? query indicates the value of the vertical position of the math waveform.

### **COMMAND SYNTAX**

MATH\_VERT\_POS <position>  
<position>:= the position is related to the position of the screen center. For example, if we set the position of MTVP to 25. The math waveform will be displayed 1 grid up to the vertical center of the screen. Namely one grid is 25.

### **QUERY SYNTAX**

MATH\_VERT\_POS?

### **RESPONSE FORMAT**

MATH\_VERT\_POS < position >

### **EXAMPLE**

The following instruction changes the vertical position of the math waveform to 1 grid up to the screen vertical centre:

Command message:  
MTVP 25

## *ACQUISITION*

MATH\_VERT\_DIV, MTVD  
**Command /Query**

### **DESCRIPTION**

The MATH\_VERT\_DIV command controls the vertical sensitivity of the math waveform of specified source. We can only set the value of existing

The FFT waveform isn't included.

The response to the MATH\_VERT\_DIV? query indicates the specified scale of math waveform of specified source.

### **COMMAND SYNTAX**

MATH\_VERT\_DIV < scale >  
< scale >:= 1PV/div ~ 100V/div.

### **QUERY SYNTAX**

MATH\_VERT\_DIV?

### **RESPONSE FORMAT**

MATH\_VERT\_DIV < scale >

### **EXAMPLE**

The following instruction changes the vertical sensitivity of the math waveform of specified source to 1V/div:

Command message:  
MTVD 1V

## *FUNCTION*

MEASURE\_DELY, MEAD  
**Command /Query**

## **DESCRIPTION**

The MEASURE\_DELY command selects the type of delay measure.

The response to the MEASURE\_DELY? query indicates the type of delay measure.

## **COMMAND SYNTAX**

MEASURE\_DELY  
SOURCE,<mode>,TYPE,<type>  
<mode>:= {C1-C2, C1-C3, C1-C4, C2-C3, C2-C4, C3-C4}  
<type>:=  
{PHA,FRR,FRF,FFR,FFF,LRR,LRF,LFR, LFF},

The PHA is phase, the others are the same as the specified type of the instrument's delay measure

## **QUERY SYNTAX**

MEASURE\_DELY?

## **RESPONSE FORMAT**

MEASURE\_DELY  
SOURCE,<mode>,TYPE,<type>

## **EXAMPLE**

The following instruction sets the type of delay measure to phase between C1 and C2.

Command message:  
MEAD SOURCE,C1-C2,TYPE,PHA

## *ACQUISITION*

## OFFSET, OFST Command /Query

### **DESCRIPTION**

The OFFSET command allows adjustment of the vertical offset of the specified input channel. The maximum ranges depend on the fixed sensitivity setting.

If an out-of-range value is entered, the oscilloscope is set to the closest possible value and the VAB bit (bit 2) in the STB register is set.

The OFFSET? query returns the offset value of the specified channel.

### **COMMAND SYNTAX**

<channel>: OFfSeT <offset>  
<channel> := {C1, C2, C3,C4}  
<offset> := See specifications.

### **QUERY SYNTAX**

<channel>: OFfSeT?

### **RESPONSE FORMAT**

<channel>: OFfSeT <offset>

### **EXAMPLE**

The following command sets the offset of Channel 2 to -3 V:

Command message:  
C2: OFST -3V



## *STATUS*

\*OPC

**Command /Query**

### **DESCRIPTION**

The \*OPC (OPeration Complete) command sets to true the OPC bit (bit 0) in the standard Event Status Register (ESR). This command has no other effect on the operation of the oscilloscope because the instrument starts parsing a command or query only after it has completely processed the previous command or query.

The \*OPC? query always responds with the ASCII character "1" because the oscilloscope only responds to the query when the previous command has been entirely executed.

### **COMMAND SYNTAX**

\*OPC

### **QUERY SYNTAX**

\*OPC?

### **RESPONSE FORMAT**

\*OPC 1

## MISCELLANEOUS

**\*OPT  
Query**

### **DESCRIPTION**

The \*OPT? query identifies oscilloscope options installed software or hardware that is additional to the standard instrument configuration. The response consists of a series of response fields listing all the installed options.

### **QUERY SYNTAX**

\*OPT?

### **RESPONSE FORMAT**

\*OPT <option>

NOTE: If no option is present, the character 0 will be returned.

EXAMPLE : The following instruction queries the installed options:

\*OPT?

Return: \*OPT RS232,NET,USBTMC

## *CURSOR*

### **DESCRIPTION**

test counter and starts it again at 0.

### **COMMAND SYNTAX**

### **RELATED COMMANDS**

## PARAMETER\_CLR, PACL Command

The PARAMETER\_CLR command clears the P/F

PArameter\_CLr

PARAMETER\_VALUE PFDD

## *CURSOR*

## PARAMETER\_CUSTOM, PACU Command /Query

### DESCRIPTION

The PARAMETER\_CUSTOM command controls the parameters that have customizable qualifiers.

Note: The measured value of a parameter setup with PACU may be read using PAVA?

### COMMAND SYNTAX

Parameter\_CUstom <line>,  
<parameter>,<qualifier><line> : = 1 to 5  
<parameter> : = { PKPK, MAX, MIN, AMPL,  
TOP, BASE, CMEAN, MEAN, RMS, CRMS,  
OVSN, FPRE, OVSP, RPRE, PER, FREQ,  
PWID, NWID, RISE, FALL, WID, DUTY,  
NDUTY }  
<qualifier> : = Measurement qualifier specific  
to each(source option)

### QUERY SYNTAX

Parameter\_CUstom? <line>

### RESPONSE FORMAT

Parameter\_Custom <line>, <parameter>,  
<qualifier>

### EXAMPLE

Command Example            PACU 2, PKPK, C  
Query/Response Examples   PACU? 2 return  
PACU 2, PKPK, C1  
PAVA? CUST2 returns:  
C2: PAVA CUST2, 160.00mV

### RELATED

COMMANDS PARAMETER CLR,

*CURSOR*

PARAMETER\_VALUE?, PAVA?

**Query**

**DESCRIPTION**

The PARAMETER\_VALUE query returns the measurement values.

Parameters Available on All Models			
ALL	all parameters	NDUTY	negative duty cycle
AMPL	amplitude	NWID	negative width
BASE	base	OVSN	negative overshoot
CMEAN	mean for cyclic waveform	OVSP	positive overshoot
CRMS	root mean square for cyclic part of waveform	PKPK	peak-to-peak
DUTY	duty cycle	PER	period
FALL	falltime	RPRE	(Vmin-Vbase)/ Vamp before the waveform rising transition
FREQ	frequency	PWID	positive width
FPRE	(Vmin-Vbase)/ Vamp before the waveform falling transition	RMS	root mean square
MAX	maximum	RISE	risetime
MIN	minimum	TOP	top
MEAN	mean	WID	width

**QUERY SYNTAX**

<trace>: PArAmeter\_VAlue? [<parameter>, ...  
<parameter>]  
<trace>: = { C1, C2, C3, C4}  
<parameter> : = See table of parameter names  
on previous table.

## **RELATED COMMANDS**

CURSOR\_MEASURE, CURSOR\_SET,  
PARAMETER\_CUSTOM

## *ACQUISITION*

## PEAK\_DETECT, PDET Command /Query

### **DESCRIPTION**

The PEAK\_DETECT command switches ON or OFF the peak detector built into the acquisition system.

The PEAK\_DETECT? query returns the current status of the peak detector.

### **COMMAND SYNTAX**

Peak\_DETEct <state>  
<state> : = {ON, OFF}

### **QUERY SYNTAX**

Peak\_DETEct?

### **RESPONSE FORMAT**

PDET <state>

### **EXAMPLE**

The following instruction turns on the peak detector:

Command message:  
PDET ON

*DISPLAY*

**PERSIST, PERS**  
**Command /Query**

**DESCRIPTION**

The PERSIST command enables or disables the persistence display mode.

**COMMAND SYNTAX**

PERSist <mode>  
<mode> := {ON, OFF}

**QUERY SYNTAX**

PERSist?

**RESPONSE FORMAT**

PERSist <mode>

**EXAMPLE**

The following code turns the persistence display ON:

Command message:  
PERS ON

**RELATED COMMANDS**

PERSIST\_SETUP



*DISPLAY*

PERSIST\_SETUP, PESU  
**Command /Query**

**DESCRIPTION**

The PERSIST\_SETUP command selects the persistence duration of the display, in seconds, in persistence mode.

The PERSIST\_SETUP? query indicates the current status of the persistence.

**COMMAND SYNTAX**

PErsist\_SetUp <time>  
<time>: ={1, 2, 5, Infinite}

**QUERY SYNTAX**

PErsist\_SetUp?

**RESPONSE FORMAT**

PErsist\_SetUp <time>

**EXAMPLE**

The following instruction sets the variable persistence at 5 Seconds:

Command message:  
PESU 5

**RELATED COMMANDS**

PERSIST

## *SAVE/RECALL SETUP*

## PANEL\_SETUP, PNSU

**Command /Query**

### **DESCRIPTION**

The PANEL\_SETUP command complements the \*SAV or \*RST commands.

PANEL\_SETUP allows you to archive panel setups in encoded form on external storage media. Only setup data read by the PNSU? query can be recalled into the oscilloscope.

### **COMMAND SYNTAX**

PaNeL\_SetUp <setup>

<setup> : = A setup previously read by PNSU?

### **QUERY SYNTAX**

PaNeL\_SetUp?

### **RESPONSE FORMAT**

PaNeL\_SetUp <setup>

### **EXAMPLE**

The following instruction saves the scilloscope's current panel setup in the file PANEL.SET:

Command message:  
PNSU?

### **RELATED COMMANDS**

\*RCL, \*SAV

## *FUNCTION*

PF\_DISPLAY, PFDS  
**Command /Query**

### **DESCRIPTION**

The PF\_DISPLAY command enables or disables to turn the test and display the message in the pass/fail option.

The response to the PF\_DISPLAY? query indicates whether the test is enabled and the message of pass/fail is displayed

### **COMMAND SYNTAX**

PF\_DISPLAY TEST,<state>,DISPLAY,<state>  
<state> := {ON, OFF}

### **QUERY SYNTAX**

PF\_DISPLAY TEST?

### **RESPONSE FORMAT**

PF\_DISPLAY TEST <state>,DISPLAY,<state>

### **EXAMPLE**

The following instruction enables to turn on the test and display the message of pass/fail:

Command message:  
PFDS TEST,ON,DISPLAY,ON

## *FUNCTION*

PF\_SET, PFST  
Command /Query

### **DESCRIPTION**

The PF\_SET command sets the X mask and the Y mask of the mask setting in the pass/fail option.

The response to the PF\_SET? query indicates the value of the X mask and the Y mask.

### **COMMAND SYNTAX**

PF\_SET XMASK, <div>, YMASK, <div>  
<div> := 0.04div~4.0div

### **QUERY SYNTAX**

PF\_SET?

### **RESPONSE FORMAT**

PF\_SET XMASK, <div>, YMASK, <div>

### **EXAMPLE**

The following instruction sets the X mask to 0.4div and the Y mask to 0.5div of the mask setting in the pass/fail option:

Command message:  
PFST XMASK,0.4,YMASK,0.5

### **RELATED COMMANDS**

PFSL PFST

*SAVE/RECALL*

PF\_SAVELOAD, PFSL  
**Command**

**DESCRIPTION**

The PF\_SAVELOAD command saves or recalls the created mask setting.

**COMMAND SYNTAX**

PF\_SAVELOAD LOCATION,  
<location>,ACTION, <action>  
The <location> means to save the created mask setting to the internal memories or the external memories.

<location> := {IN,EX}  
IN means to save the mask setting to the internal memories while EX means the external memories.  
<action> := {SAVE,LOAD}  
SAVE means to save the mask setting while LOAD means recall the stored mask setting.

**EXAMPLE**

The following instruction saves the mask setting to the internal memories:

Command message:  
PFSL LOCATION,IN,ACTION,SAVE

**RELATED COMMANDS**

PFCM

## *FUNCTION*

PF\_CONTROL, PFCT  
Command / Query

### **DESCRIPTION**

The PF\_CONTROL command controls the pass/fail controlling options: “operate”, “output” and the “stop on output”.

See instrument’s Operator Manual for these options

The response to the PF\_CONTROL? query indicates the controlling options of the pass/fail

### **COMMAND SYNTAX**

PF\_CONTROL  
TRACE,<trace>,CONTROL,<control>,OUTPUT,<output>,OUTPUTSTOP,<state>  
<trace> := {C1,C2,C3,C4}  
<control> := {START,STOP}  
<output> := {FAIL,PASS}  
<state> := {ON,OFF}

### **QUERY SYNTAX**

PF\_CONTROL?

### **RESPONSE FORMAT**

PF\_CONTROL  
TRACE,<trace>,CONTROL,<control>,  
OUTPUT,<output>,OUTPUTSTOP,<state>

### **EXAMPLE**

The following instruction sets source to channel 1, “operate” to “start”, “output” to “pass” and “stop on output” to “off”:

Command message:

*FUNCTION*

PF\_CREATEM, PFCM  
**Command**

**DESCRIPTION**

The PF\_CREATEM command creates the mask of the pass/fail.

**COMMAND SYNTAX**

PF\_CREATEM

**EXAMPLE**

The following instruction creates the mask of the pass/fail.:

Command message:  
PFCM

**RELATED COMMANDS**

PFSL PFST

## *FUNCTION*

PF\_DATADIS, PFDD

**Query**

### **DESCRIPTION**

The PF\_DATADIS? query returns the number of the fail ,pass and total number that the screen is showing.

### **QUERY SYNTAX**

PF\_ DATADIS?

### **RESPONSE FORMAT**

PF\_ DATADIS  
FAIL,<num>,PASS,<num>,total,<num>

### **EXAMPLE**

The following instruction returns the number of the message display of the pass/fail:

Command message:  
PFDD FAIL,0,PASS,0,TOTAL,0

### **RELATED COMMANDS**

PACL



## *SAVE/RECALL SETUP*

**\*RCL  
Command**

### **DESCRIPTION**

The \*RCL command sets the state of the instrument, using one of the ten non-volatile panel setups, by recalling the complete front-panel setup of the instrument. Panel setup 0 corresponds to the default panel setup.

The \*RCL command produces the opposite effect of the \*SAV command.

If the desired panel setup is not acceptable, the EXecution error status Register (EXR) is set and the EXE bit of the standard Event Status Register (ESR) is set.

### **COMMAND SYNTAX**

\*RCL <panel\_setup>  
<panel\_setup>:= 0 to 20

### **EXAMPLE**

The following recalls the instrument setup previously stored in panel setup 3:

Command message:  
\*RCL 3

### **RELATED COMMANDS**

PANEL\_SETUP, \*SAV, EXR

## WAVEFORM TRANSFER

## RECALL, REC Command

### DESCRIPTION

The RECALL command recalls a waveform file from the current directory on mass storage into any or all of the internal memories M1 to M10(or M20 in the CFL series).

### COMMAND SYNTAX

<memory>: RECall DISK, <device>, FILE, '<filename>'  
<memory> := {M1~M10}(or M1~M20 in the CFL series)  
<device> := {UDSK}  
<filename>: = A waveform file under a legal DOS path . A filename-string of up to eight characters, with the extension ".DAV". (This can include the '/' character to define the root directory.)

### EXAMPLE

The following recalls a waveform file called "C1WF.DAV" from the memory card into Memory M1:

Command message:

M1: REC DISK, UDSK FILE, 'C1WF.DAV'

### RELATED COMMANDS

STORE, INR?

## *SAVE/RECALL SETUP*

## RECALL\_PANEL, RCPN Command

### **DESCRIPTION**

The RECALL\_PANEL command recalls a front-panel setup from the current directory on mass storage.

### **COMMAND SYNTAX**

ReCall\_PaNel DISK, <device>, FILE,  
'<filename>'  
<device> := {UDSK}  
<filename>: = A waveform file under a legal DOS path . A filename-string of up to eight characters, with the extension ".SET". (This can include the '/' character to define the root directory.)

### **EXAMPLE**

The following recalls the front-panel setup from file SEAN.SET in a USB memory device:

Command message:  
RCPN DISK, UDSK, FILE, 'SEAN.SET'

### **RELATED COMMANDS**

PANEL\_SETUP, \*SAV, STORE\_PANEL,  
\*RCL

## *SAVE/RECALL SETUP*

**\*RST**  
**Command**

### **DESCRIPTION**

The \*RST command initiates a device reset.  
The \*RST sets recalls the default setup.

### **COMMAND SYNTAX**

\*RST

### **EXAMPLE**

This example resets the oscilloscope:

Command message:

\*RST

### **RELATED COMMANDS**

\*CAL, \*RCL

## *FUNCTION*

REF\_SET, REFS  
Command /Query

## **DESCRIPTION**

The REF\_SET command sets the reference waveform and its options.

The response to the REF\_SET? query indicates whether the specified reference waveform is turned on.

## **COMMAND SYNTAX**

REF\_SET TRACE,<trace>REF,<ref>,state,  
<state>,SAVE,DO  
<trace> :=  
{C1,C2,C3,C4,C1OFF,C2OFF,C3OFF,C4OFF}  
If the trace is closed, the specified trace will be  
CxOFF,(x is 1,2,3,4), the closed trace couldn't  
be saved or set  
<ref> := {RA,RB,RC,RD}  
The Rx(x is A,B,C,D) is that which one can be  
stored or displayed  
<state> := {ON,OFF}

The state enables or disables to display the specified reference waveform.

If the command syntax have the option that SAVE,DO, means that the specified trace will be saved to the specified reference waveform.

## **QUERY SYNTAX**

REF\_SET? REF,<ref>

## **RESPONSE FORMAT**

REF\_SET REF,<ref>,STATE,<state>

## **EXAMPLE**

The following instruction saves the channel 1 waveform to the REFA, and turns on REFA:

## *SAVE/RECALL SETUP*

**\*SAV  
Command**

### **DESCRIPTION**

The \*SAV command stores the current state of the instrument in internal memory. The \*SAV command stores the complete front-panel setup of the instrument at the time the command is issued.

### **COMMAND SYNTAX**

\*SAV <panel\_setup>  
<panel\_setup>: = 1 to 20

### **EXAMPLE**

The following saves the current instrument setup in Panel Setup 3:

Command message:  
\*SAV 3

### **RELATED COMMANDS**

PANEL\_SETUP, \*RCL

*HARD COPY*

SCREEN\_DUMP, SCDP  
**Command**

**DESCRIPTION**

The SCREEN\_DUMP command is used to obtain the screen information of image format.

**COMMAND SYNTAX**

Screen\_DumP

**EXAMPLE**

The following command transfers the screen information of image format to the controller.

Command message:  
SCDP

## *DISPLAY*

## SCREEN\_SAVE, SCSV Command /Query

### **DESCRIPTION**

The SCREEN\_SAVE command controls the automatic Screen Saver, which automatically shuts down the internal color monitor after a preset time.

The response to the SCREEN\_SAVE? query indicates whether the automatic screen saver feature is on or off.

Note: When the screen save is in effect, the oscilloscope is still fully functional.

### **COMMAND SYNTAX**

SCreen\_SaVe <enabled>  
<enabled> := {YES, NO}

### **QUERY SYNTAX**

SCreen\_SaVe?

### **RESPONSE FORMAT**

SCreen\_SaVe <enabled>

### **EXAMPLE**

The following enables the automatic screen sav

Command message:  
SCSV YES



## *STATUS*

**\*SRE**  
**Command /Query**

### **DESCRIPTION**

The \*SRE command sets the Service Request Enable register (SRE). This command allows the user to specify which summary message bit(s) in the STB register will generate a service request.

A summary message bit is enabled by writing '1' into the corresponding bit location. Conversely, writing a '0' into a given bit location prevents the associated event from generating a service request (SRQ). Clearing the SRE register disables SRQ interrupts.

The \*SRE? query returns a value that, when converted to a binary number, represents the bit settings of the SRE register.

Note: that bit 6 (MSS) cannot be set and its returned value is always zero.

### **COMMAND SYNTAX**

\*SRE <value>  
<value> : = 0 to 255

### **QUERY SYNTAX**

\*SRE?

### **RESPONSE FORMAT**

\*SRE <value>

### **EXAMPLE**

The following instruction allows an SRQ to be generated as soon as the MAV summary bit (bit 4, i.e. decimal 16) or the INB summary bit (bit

## *STATUS*

**\*STB?**  
**Query**

### **DESCRIPTION**

The \*STB? query reads the contents of the 488.1 defined status register (STB), and the Master Summary Status (MSS). The response represents the values of bits 0 to 5 and 7 of the Status Byte register and the MSS summary message.

The response to a \*STB? Query is identical to the response of a serial poll except that the MSS summary message appears in bit 6 in place of the RQS message.

### **QUERY SYNTAX**

\*STB?

### **RESPONSE FORMAT**

\*STB <value>  
<value> : = 0 to 255

### **EXAMPLE**

The following reads the status byte register:

Command message:  
\*STB?

Response message:  
\*STB 0

### **RELATED COMMANDS**

ALL\_STATUS, \*CLS, \*SRE

## ADDITIONAL INFORMATION

Status Byte Register (STB)				
Bit	Bit Value	Bit Name	Description	Note
7	128	DIO7	0 reserved for future use	
6	64	MSS/RQS MSS=1 RQS=1	at least 1 bit in STB masked by SRE is 1 service is requested	(1) (2)
5	32	ESB	1 an ESR enabled event has occurred	(3)
4	16	MAV	1 output queue is not empty	(4)
3	8	DIO3	0 reserved	
2	4	VAB	1 a command data value has been adapted	(5)
1	2	DIO1	0 reserved	
0	1	INB	1 an enabled INternal state change has occurred	(6)

### Notes

- (1) The Master Summary Status (MSS) indicates that the instrument requests service, whilst the Service Request status — when set — specifies that the oscilloscope issued a service request. Bit position 6 depends on the polling method:  
Bit 6 = MSS if an \*STB? Query is received  
= RQS if serial polling is conducted
- (2) Example: If SRE=10 and STB=10 then MSS=1. If SRE=010 and STB=100 then MSS=0.
- (3) The Event Status Bit (ESB) indicates whether or not one or more of the enabled IEEE 488.2 events have occurred since the last reading or clearing of the Standard Event Status Register (ESR). ESB is set if an enabled event becomes true (1).
- (4) The Message AVailable bit (MAV) indicates whether or not the Output queue is empty. The MAV summary bit is set true (1) whenever a data byte resides in the Output queue.
- (5) The Value Adapted Bit (VAB) is set true (1) whenever a data value in a command has been adapted to the nearest legal value. For instance, the VAB bit would be set if the timebase is redefined as 2  $\mu$ s/div since the adapted value is 2.5  $\mu$ s/div.
- (6) The INternal state Bit (INB) is set true (1) whenever certain enabled internal states are entered. For further information, refer to the INR query.

## *ACQUISITION*

## **STOP Command**

### **DESCRIPTION**

The STOP command immediately stops the acquisition of a signal. If the trigger mode is AUTO or NORM.

### **COMMAND SYNTAX**

STOP

### **EXAMPLE**

The following stops the acquisition process:

Command message:  
STOP

### **RELATED COMMANDS**

ARM\_ACQUISITION, TRIG\_MODE, WAIT

## WAVEFORM TRANSFER

## STORE, STO Command

### DESCRIPTION

The STORE command stores the contents of the specified trace into one of the internal memories M1 to M10(or M20 in the CFL series) or to the current directory in a USB memory device.

### COMMAND SYNTAX

STORe [<trace>, <dest>]

<trace>: = {TA, TB, TC, TD, C1, C2, C3, C4, ALL\_DISPLAYED}

<dest>: = {M1~M10(or M20 in the CFL series), UDSK}

Note: If the STORE command is sent without an argument, and the current trace isn't enabled, the current trace will be enabled and stored in the Store Setup. This setup can be modified using the STORE\_SETUP command.

### EXAMPLE

The following command stores the contents of Channel 1(C1) into Memory 1 (M1):

Command message:  
STO C1, M1

The following command stores all currently displayed waveforms onto the USB memory device:

Command message:  
STO ALL\_DISPLAYED, UDSK

## *SAVE/RECALL SETUP*

STORE\_PANEL, STPN

**Command**

### **DESCRIPTION**

The STORE\_PANEL command stores the complete front-panel setup of the instrument, at the time the command is issued, into a file on the specified-DOS path directory in a USB memory device.

### **COMMAND SYNTAX**

STore\_PaNel DISK, <device>, FILE, '  
<filename>'  
<device>: = {UDSK}  
< directory >: = A legal DOS path or filename.  
A filename -string of up to 8 characters, with the extension “.SET”. (This can include the '/' character to define the root directory.)

### **EXAMPLE**

The following code saves the current instrument setup to root directory of the USB memory device in a file called “SEAN.SET”:

Command message:

STore\_PaNel DISK,UDSK,FILE,'SEAN.SET'

The following code saves the current instrument setup to specified-directory of the USB memory device in a file called “SEAN.SET”:

Command message:

STore\_PaNel DISK,UDSK,FILE,'/AAA/SEAN

### **RELATED COMMANDS**

\*SAV, RECALL\_PANEL, \*RCL

## WAVEFORM TRANSFER

## STORE\_SETUP, STST Command /Query

### DESCRIPTION

The STORE\_SETUP command controls the way in which traces will be stored. A single trace or all displayed traces may be enabled for storage.

### COMMAND SYNTAX

STore\_SeTup [<trace>, <dest>]  
<trace> := {C1,C2,C3,C4,ALL\_DISPLAYED}  
<dest> := {M1~M10(or M20 in the CFL series),UDSK}

### QUERY SYNTAX

STore\_SeTup?

### RESPONSE FORMAT

STore\_SeTup <trace>, <dest>

### EXAMPLE

The following command selects Channel 1 to be stored.

Command message:  
STST C1, UDSK

### RELATED COMMANDS

STORE, INR

## *ACQUISITION*

SAMPLE\_STATUS, SAST  
**Query**

### **DESCRIPTION**

The SAST? query the acquisition status of the scope.

### **QUERY SYNTAX**

SAST?

### **RESPONSE FORMAT**

SAST < status >

### **EXAMPLE**

The following command reads the acquisition status of the scope.

Command message:  
SAST?

Response message:  
SAST trig'd



## *ACQUISITION*

SAMPLE\_RATE, SARA  
Query

### **DESCRIPTION**

The SARA? query returns the sample rate of the scope.

### **QUERY SYNTAX**

SARA?

### **RESPONSE FORMAT**

SARA <value>

### **EXAMPLE**

The following command reads the sample rate of the scope.

Command message:  
SARA?

Response message:  
SARA 500.0kSa

## *ACQUISITION*

SAMPLE\_NUM, SANU  
**Query**

### **DESCRIPTION**

The SANU? query returns the number of sampled points available from last acquisition and the trigger position.

### **QUERY SYNTAX**

SANU? <channel>

### **RESPONSE FORMAT**

SANU <value>

### **EXAMPLE**

The following command reads the number of sampled points available from last acquisition from the Channel 2.

Command message:  
SANU? C2

Response message:  
SANU 6000

## *ACQUISITION*

## **SKEW, SKEW Command**

### **DESCRIPTION**

The SKEW command sets the skew value of the specified trace.

The response to the SKEW? query indicates the skew value of the specified trace.

### **COMMAND SYNTAX**

<trace>:SKEW <skew>  
<trace> := {C1,C2,C3,C4 }  
<skew>:= it is a value about time.

### **QUERY SYNTAX**

<trace>:SKEW?

### **RESPONSE FORMAT**

<trace>:SKEW <skew>

### **EXAMPLE**

The following command sets channel 1 skew value to 3ns

Command message:  
C1:SKEW 3NS

## *FUNCTION*

SET50, SET50  
**Command**

## **DESCRIPTION**

The SET50 command sets the trigger level of the specified trigger source to the centre of the signal amplitude.

## **COMMAND SYNTAX**

SET50

## **EXAMPLE**

The following command sets the trigger level of the specified trigger source to the centre of the signal amplitude

Command message:  
SET50

## *ACQUISITION*

SINXX\_SAMPLE, SXSA  
**Command /Query**

### **DESCRIPTION**

The SINXX\_SAMPLE command sets the way of interpolation.

The response to the SINXX\_SAMPLE? query indicates the way of interpolation.

### **COMMAND SYNTAX**

SINXX\_SAMPLE, <state>  
<state> := {ON,OFF}  
ON means sine interpolation, and OFF means linear interpolation

### **QUERY SYNTAX**

SINXX\_SAMPLE?

### **RESPONSE FORMAT**

SINXX\_SAMPLE <state>

### **EXAMPLE**

The following instruction sets the way of the interpolation to sine interpolation:

Command message:  
SXSA ON

## ACQUISITION

## TIME\_DIV, TDIV Command /Query

### DESCRIPTION

The TIME\_DIV command modifies the timebase setting. The new timebase setting may be specified with suffixes: NS for nanoseconds, US for microseconds, MS for milliseconds, S for seconds, or KS for kiloseconds. An out-of-range value causes the VAB bit (bit 2) in the STB register to be set.

The TIME\_DIV? query returns the current timebase setting.

### COMMAND SYNTAX

Time\_DIV <value>  
<value>:={ 1NS(not every type has this value),2.5NS,5NS,10NS,25NS,50NS,100NS,250NS,500NS,1US,2.5US,5US,10US,25US,50US,100US,250US,500US,1MS,2.5MS,5MS,10MS,25MS,50MS,100MS,250MS,500MS,1S,2.5S,5S,10S,25S,50S}

### QUERY SYNTAX

Time\_DIV?

### RESPONSE FORMAT

Time\_DIV <value>

### EXAMPLE

The following sets the time base to 500  $\mu$ s /div:

Command message:  
TDIV 500US

### RELATED COMMANDS

TRIG\_DELAY, TRIG\_MODE

## *WAVEFORM TRANSFER*

## TEMPLATE, TMPL Query

### **DESCRIPTION**

The TEMPLATE? query produces a copy of the template that describes the various logical entities making up a complete waveform. In particular, the template describes in full detail the variables contained in the descriptor part of a waveform.

### **QUERY SYNTAX**

TeMPLate?

### **RESPONSE FORMAT**

TeMPLate "<template>"  
<template> := A variable length string detailing the structure of a waveform.

### **RELATED COMMANDS**

**WF**

## *DISPLAY*

## TRACE, TRA Command /Query

### **DESCRIPTION**

The TRACE command enables or disables the display of a trace. An environment error is set if an attempt is made to display more than four waveforms.

The TRACE? query indicates whether the specified trace is displayed or not.

### **COMMAND SYNTAX**

```
<trace>: TRAcE <mode>  
<trace> := {C1, C2, C3, C4, TA, TB, TC, TD}  
<mode> := {ON, OFF}
```

### **QUERY SYNTAX**

```
<trace>: TRAcE?
```

### **RESPONSE FORMAT**

```
<trace>: TRAcE <mode>
```

### **EXAMPLE**

The following command displays Channel 1 (C

Command message:

```
C1: TRA ON
```



## *ACQUISITION*

**\*TRG  
Command**

### **DESCRIPTION**

The \*TRG command executes an ARM command.

### **COMMAND SYNTAX**

\*TRG

### **EXAMPLE**

The following command enables signal acquisition:

Command message:

\*TRG

### **RELATED COMMANDS**

ARM\_ACQUISITION, STOP, WAIT

## *ACQUISITION*

TRIG\_COUPLING, TRCP  
**Command /Query**

### **DESCRIPTION**

The TRIG\_COUPLING command sets the coupling mode of the specified trigger source.

The TRIG\_COUPLING? query returns the trigger coupling of the selected source.

### **COMMAND SYNTAX**

<trig\_source>: TRig\_CouPling <trig\_coupling>  
<trig\_source>: = {C1, C2, C3, C4, EX, EX5, LINE}  
<trig\_coupling>: = {AC,DC,HFREJ,LFREJ}

### **QUERY SYNTAX**

<trig\_source>: TRig\_CouPling?

### **RESPONSE FORMAT**

<trig\_source>: TRig\_CouPling <trig\_coupling>

### **EXAMPLE**

The following command sets the coupling mode of the trigger source Channel 2 to AC:

Command message:  
C2: TRCP AC

### **RELATED COMMANDS**

TRIG\_COUPLING, TRIG\_DELAY,  
TRIG\_LEVEL, TRIG\_MODE, TRIG\_SELECT  
TRIG\_SLOPE

## *ACQUISITION*

TRIG\_DELAY, TRDL  
**Command /Query**

### **DESCRIPTION**

The TRIG\_DELAY command sets the time at which the trigger is to occur with respect to the first acquired data point.

This mode is called pre-trigger acquisition, as data are acquired before the trigger occurs. Negative trigger delays must be given in seconds. This mode is called post-trigger acquisition, as the data are acquired after the trigger has occurred.

If a value outside the range, the trigger time will be set to the nearest limit and the VAB bit (bit 1) will be set in the STB register. The response to the TRIG\_DELAY? query indicates the trigger time with respect to the first acquired data point.

### **COMMAND SYNTAX**

TRig\_DeLay <value>  
<value> : = the range of value is related to the timebase.

Note: The suffix S is optional and assumed.

### **QUERY SYNTAX**

TRig\_DeLay?

### **RESPONSE FORMAT**

TRig\_DeLay <value>

### **EXAMPLE**

The following command sets the trigger delay to -2ms (posttrigger):

## ACQUISITION

## TRIG\_LEVEL, TRLV

Command /Query

### DESCRIPTION

The TRIG\_LEVEL command adjusts the trigger level of the specified trigger source. An out-of-range value will be adjusted to the closest legal value and will cause the VAB bit (bit 2) in the STB register to be set.

The TRIG\_LEVEL? query returns the current trigger level.

### COMMAND SYNTAX

<trig\_source>: TRig\_LeVel <trig\_level>  
<trig\_source>: = {C1, C2, C3, C4, EX, EX5}  
<trig\_level>: = -6DIV\* volt/div to 6DIV \*  
volt/div

Note: The suffix V is optional and assumed.

### QUERY SYNTAX

<trig\_source>: TRig\_LeVel?

### RESPONSE FORMAT

<trig\_source>: TRig\_LeVel <trig\_level>

### EXAMPLE

The following code adjusts the trigger level of Channel 3 to 52.00mv:

Command message:  
C3:TRig\_LeVel 52.00mv

### RELATED COMMANDS

TRIG\_COUPLING, TRIG\_DELAY,  
TRIG\_MODE, TRIG\_SELECT, TRIG\_SLOPE

## ACQUISITION

TRIG\_MODE, TRMD  
Command /Query

### DESCRIPTION

The TRIG\_MODE command specifies the trigger mode.

The TRIG\_MODE? query returns the current trigger mode.

NOTE: STOP is a part of the option of this command, but is not a trigger mode of the instrument

### COMMAND SYNTAX

TRig\_MoDe <mode>  
<mode>: = {AUTO, NORM, SINGLE,STOP}

### QUERY SYNTAX

TRig\_MoDe?

### RESPONSE FORMAT

TRig\_MoDe <mode>

### EXAMPLE

The following selects the normal mode:

Command message:  
TRMD NORM

### RELATED COMMANDS

ARM\_ACQUISITION, STOP, TRIG\_SELECT,  
TRIG\_COUPLING, TRIG\_LEVEL, TRIG\_SLOP

## ACQUISITION

## TRIG\_SELECT, TRSE Command /Query

### DESCRIPTION

The TRIG\_SELECT command is used to set the trigger type and the type's option

HT which is an option of the TRIG\_SELECT command is related to the TRSL command. The TRSL command could set the <trig\_slope>. The HT's polarity will also be changed.

The TRIG\_SELECT? query returns the current trigger type.

### COMMAND SYNTAX

TRig\_SelEct <trig\_type>,SR,<source>,HT,  
<hold\_type>,<HV>,<hold\_value>

TRig\_SelEct<trig\_type>,SR,<source>,CHAR,  
<characteristicse>,POL,<polarity>,SYNC,<sync  
type>,LINE,  
<line>

TRig\_SelEct INTV,SR,<source>,VERT,<vertical

### OPTION

<trig\_type>:= {EDGE, GLIT,INTV,TV,}

GLIT means pulse trigger, INTV means slope trigger and TV means video trigger.

**Options:** SR HT HV POL CHAR SYNC  
LINE VERT

HT,<hold\_type>:is used to set pulse type.

<hold\_type> := {TI, PS, PL,PE, IS, IL,IE}

TI means holdoff, PS means that the pulse width is smaller than the set value. PL means that the pulse width is larger than the set value. PE means that the pulse width is equal with the set value. I

SR,< source > :is used to set the trigger's channel.If you want to set the other option. You must set it.

<source>: = {C1, C2, C3,C4,EX, EX5}

CHAR, <characteristicse>:is used to set the standard .if you want to set it, the <trig\_type> must be set to TV.

<characteristicse>:={NTSC, PALSEC}

SYNC,<sync\_type>:is used to set sync. If you Want to set it. You must set <trig\_type> to TV

<sync\_type> : = {AL,LN,OF,EF}

AL means all lines; LN means line num; OF means odd field; EF means even field

LINE,<line>:is used to set the line num. if you want to set it. The SYNC must be set to LINENUM

POL,<polarity>: is used to set polarity. If you want to set it. You must set <trig\_type> to TV

<polarity>: = {PO,NE}

PO means positive. NE means negative.

VERT,<vertical>:is used to set vertical. If you Want to set it. You must set <trig\_type> INTV

<vertical>: = {UP,DOWN,BOTH}

TRig\_SelEct?

TRig\_SelEct <mode>,the other options

## QUERY SYNTAX

## RESPONSE FORMAT

## EXAMPLE

The following sets the trigger type to video, the trigger source to C1,the standard to NTSC, the

## *ACQUISITION*

TRIG\_SLOPE, TRSL  
Command /Query

### **DESCRIPTION**

The TRIG\_SLOPE command sets the trigger slope of the specified trigger source.

The TRIG\_SLOPE? query returns the trigger slope of the selected source.

### **COMMAND SYNTAX**

<trig\_source>: TRig\_SLOpe <trig\_slope>  
<trig\_source>: = {C1, C2, C3, C4, EX,EX5,  
                  LINE}  
<trig\_slope>: = {NEG, POS,WINDOW }

### **QUERY SYNTAX**

<trig\_source> : TRig\_Slope?

### **RESPONSE FORMAT**

<trig\_source>: TRig\_SLOpe <trig\_slope>

### **EXAMPLE**

The following sets the trigger slope of Channel 2 to negative:

Command message:  
C2: TRSL NEG

### **RELATED COMMANDS**

TRIG\_COUPLING, TRIG\_DELAY,  
TRIG\_LEVEL, TRIG\_MODE, TRIG\_SELECT,  
TRIG\_SLOPE



## *ACQUISITION*

**UNIT, UNIT  
Command /Query**

### **DESCRIPTION**

The UNIT command sets the unit of the specified trace.

The UNIT query returns the unit of the specified trace.

### **COMMAND SYNTAX**

<channel>: UNIT <type>  
<channel>: = {C1, C2, C3, C4}  
<type>: = {V,A}

### **QUERY SYNTAX**

<channel> : UNIT?

### **RESPONSE FORMAT**

<channel>: UNIT <type>

### **EXAMPLE**

The following command sets the unit of the channel 1 to V:

Command message:  
C1: UNIT V

## *DISPLAY*

## VERT\_POSITION, VPOS Command /Query

### DESCRIPTION

The VERT\_POSITION command adjusts the vertical position of the specified FFT trace on the screen. It does not affect the original offset value obtained at acquisition time.

The VERT\_POSITION? query returns the current vertical position of the specified FFT trace.

### COMMAND SYNTAX

<trace>: Vert\_POSITION <display\_offset>  
<trace>: = {TA, TB, TC, TD}  
<display\_offset>: =-40 DIV to 40 DIV

Note: The suffix DIV is optional.

### QUERY SYNTAX

<trace>: Vert\_POSition?

### RESPONSE FORMAT

<trace>: Vert\_POSITION <display\_offset>

### EXAMPLE

The following shifts FFT Trace A (TA) upwards by +3 divisions relative to the position at the time of acquisition:

Command message:  
TA: VPOS 3DIV

## ACQUISITION

VOLT\_DIV, VDIV  
Command /Query

### DESCRIPTION

The VOLT\_DIV command sets the vertical sensitivity in Volts/div. The VAB bit (bit 2) in the STB register is set if an out-of-range value is entered.

The VOLT\_DIV query returns the vertical sensitivity of the specified channel.

### COMMAND SYNTAX

<channel>: Volt\_DIV <v\_gain>  
<channel>: = {C1, C2, C3, C4}  
<v\_gain>: = 2mV to 10V (or 5V in the CFL series)

Note: The suffix V is optional.

### QUERY SYNTAX

<channel> : Volt\_DIV?

### RESPONSE FORMAT

<channel>: Volt\_DIV <v\_gain>

### EXAMPLE

The following command sets the vertical sensitivity of channel 1 to 50 mV/div:

Command message:  
C1: VDIV 50MV

## *ACQUISITION*

## VERTICAL, VTCL Command /Query

### **DESCRIPTION**

The VERTICAL command controls the vertical position of the slope trigger line. It is related to the TRSE command. The VERT option of the TRSE command changes the controlling type of the slopes trigger line.

When the slope trigger lines are both controlled, the vertical position of the slope trigger line is the up one's position.

The VERTICAL query returns the vertical position of the slope trigger line.

### **COMMAND SYNTAX**

<channel>: VERTICAL <pos>  
<channel>: = {C1, C2, C3, C4}  
<pos>: = the position is related to the screen vertical center. For example, if we set the vertical position of the slope trigger line to 25, it will be displayed 1 grid up to the screen vertical center. Namely one grid is 25.

### **QUERY SYNTAX**

<channel> : VERTICAL?

### **RESPONSE FORMAT**

<channel>: VERTICAL <pos>

### **EXAMPLE**

The following command sets the vertical position of the slope trigger line to 25 that what is the distance from the up of centre about 1 grid :

Command message:

## WAVEFORM TRANSFER

## WAVEFORM, WF Query

### DESCRIPTION

A WAVEFORM? Query transfers a waveform from the oscilloscope to the controller.

A waveform consists of several distinct entities:

1. the descriptor (DESC)
2. the user text (TEXT)
3. the time (TIME) descriptor
4. the data (DAT1) block, and, optionally
5. a second block of data (DAT2)

The WAVEFORM? Query instructs the oscilloscope to transmit a waveform to the controller. The entities may be queried independently. If the “ALL” parameter is specified, all four or five entities are transmitted in one block in the order enumerated above.

Note: The format of the waveform data depends on the current settings specified by the last WAVEFORM\_SETUP command.

### QUERY SYNTAX

```
<trace>: WaveForm?  
<trace> := { C1,C2,C3,C4}
```

### RESPONSE FORMAT

### WAVEFORM, WF Query Response

Note:

Offset data factor is a 4 byte floating point number starting at address 0xA0.

Amplitude scale factor data is a 4 byte floating point number starting at address 0x9C.

Waveform descriptor block starts off from “WAVEDESC” in the return data. The size of the descriptor is  $0x16e - 0x15 + 1$ .

All waveform data are represented in two's complement binary. It must be converted to decimal and apply to the linear equation formula  $y = mx + b$ , where  $x$  is the data in decimal value,  $m$  is the amplitude scale factor, and  $b$  is the offset data factor.

For detailed description, see the end of the document.

## WAVEFORM TRANSFER

## WAVEFORM\_SETUP, WFSU Command /Query

### DESCRIPTION

The WAVEFORM\_SETUP command specifies the amount of data in a waveform to be transmitted to the controller. The command controls the settings of the parameters listed below.

Note: This command currently only support NP

Notation			
FP	first point	NP	number of points
SP	sparsing		

Sparsing (SP): The sparsing parameter defines the interval between data points. For example:  
SP = 0 sends all data points  
SP = 1 sends all data points  
SP = 4 sends every 4th data point

Number of points (NP): The number of points parameter indicates how many points should be transmitted. For example:  
NP = 0 sends all data points  
NP = 1 sends 1 data point  
NP = 50 sends a maximum of 50 data points  
NP = 1001 sends a maximum of 1001 data points

First point (FP): The first point parameter specifies the address of the first data point to be sent. For waveforms acquired in sequence mode this refers to the relative address in the given

## QUERY SYNTAX

WaveForm\_SetUp?

Note 1: After power-on, SP is set to 4, NP is set to 1000, and FP is set to 0.

Note 2: Parameters are grouped in pairs. The first of the pair names the variable to be modified, whilst the second gives the new value to be assigned. Pairs may be given in any order and may be restricted to those variables to be changed.

## RESPONSE FORMAT

WaveForm\_SetUp SP, <sparsing>, NP, <number>, FP, <point>

## EXAMPLE

The following command specifies that every 3rd data point (SP=3) starting at address 200 should be transferred:

Command message:  
WFSU SP, 3, FP, 200

## RELATED COMMANDS

WAVEFORM



## *ACQUISITION*

## WAIT, WAIT Command

### **DESCRIPTION**

The WAIT command prevents the instrument from analyzing new commands until the oscilloscope has completed the current acquisition.

The instrument will be waiting for trigger or the limit time over (if we set it) or the device time out when we sent this command

### **COMMAND SYNTAX**

WAIT <time>

Note : This command have two ways to use. One sets the limited time, another one doesn't set the limited time.

### **EXAMPLE**

If we move the trigger level of the source to the position where the trace isn't triggered. Then we send an ARM command to set the trigger mode to single. Finally we send the WAIT command. The instrument will be waiting for triggering until the time over (if we set it) or time out.

If we move the trigger level of the source, and the instrument is triggered. Then we send an ARM command to set the trigger mode to single. Finally we send the WAIT command. The WAIT command will be finished if we send a FRTR for triggering.

Command message:

WAIT

*DISPLAY*

XY\_DISPLAY, XYDS  
**Command /Query**

**DESCRIPTION**

The XY\_DISPLAY command enables or disables to display the XY format

The response to the XY\_DISPLAY? query indicates whether the XY format display is enabled.

**COMMAND SYNTAX**

XY\_DISPLAY <state>  
<state>: = {ON, OFF}

**QUERY SYNTAX**

XY\_DISPLAY?

**RESPONSE FORMAT**

XY\_DISPLAY <state>

**EXAMPLE**

The following command enables to display the XY format:

Command message:  
XYDS

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DSO: TEMPLATE

Explanation of the formats of waveforms and their descriptors on the DSO

A descriptor and/or a waveform consists of one or several logical data blocks whose formats are explained below.

Usually, complete waveforms are read: at the minimum they consist of the basic descriptor block WAVEDESC a data array block.

Some more complex waveforms, e.g. Extrema data or the results of a Fourier transform, may contain several data array blocks.

When there are more blocks, they are in the following sequence:

- the basic descriptor block WAVEDESC
- auxiliary data array block
- data array block

In the following explanation, every element of a block is described by a single line in the form

<byte position> <variable name>: <variable type> ; <comment>

where

<byte position> = position in bytes (decimal offset) of the variable, relative to the beginning of the block.

<variable name> = name of the variable.

<variable type> = string up to 16-character name terminated with a null byte

byte 08-bit signed data value

word 16-bit signed data value

long 32-bit signed data value

float 32-bit IEEE floating point value

with the format shown below

31 30 .. 23 22 ... 0 bit position

s exponent fraction

where

s = sign of the fraction

exponent = 8 bit exponent e

fraction = 23 bit fraction f

and the final value is

$(-1)^{**s} * 2^{**e} * 1.f$

double 64-bit IEEE floating point value

with the format shown below

63 62 .. 52 51 ... 0 bit position

s exponent fraction

where

s = sign of the fraction

exponent = 11 bit exponent e

fraction = 52 bit fraction f

and the final value is

$(-1)^{**s} * 2^{**e} * 1.f$

enum enumerated value in the range 0 to N represented as a 16-bit data value. The list of values follows immediately. The integer is preceded by an \_.

time\_stamp double precision floating point number, for the number of seconds and some bytes for minutes, hours, days, months and year.

double seconds (0 to 59)

byte minutes (0 to 59)

byte hours (0 to 23)

	byte	days	(1 to 31)
	byte	months	(1 to 12)
	word	year	(0 to 16000)
	word	unused	
data	There are 16 bytes in a time field. byte, word or float, depending on the read-out mode reflected by the WAVEDESC variable COMM_TYPE, modifiable via the remote command COMM_FORMAT.		
text	arbitrary length text string (maximum 160)		
unit_definition	a unit definition consists of a 48 character ASCII string terminated with a null byte for the unit name.		

=====

DESC: BLOCK

Explanation of the wave descriptor block WAVEDESC;

< 0>            DESCRIPTOR\_NAME: string ; the first 8 chars are always WAVEDESC

< 16>           TEMPLATE\_NAME: string

< 32>           COMM\_TYPE: enum            ; chosen by remote command COMM\_FORMAT  
                  \_0            byte  
                  \_1            word  
                  endenum

< 34>           COMM\_ORDER: enum  
                  \_0            HIFIRST  
                  \_1            LOFIRST  
                  endenum

The following variables of this basic wave descriptor block specify the block lengths of all blocks of which the entire waveform (as it is currently being read) is composed. If a block length is zero, this block is (currently) not present.

Blocks and arrays that are present will be found in the same order as their descriptions below.

BLOCKS :

< 36>           WAVE\_DESCRIPTOR: long        ; length in bytes of block WAVEDESC  
< 40>           USER\_TEXT: long            ; length in bytes of block USERTXT  
< 44>           RES\_DESC1: long            ;

ARRAYS :

< 48>           TRIGTIME\_ARRAY: long        ; length in bytes of TRIGTIME array

< 52>           RIS\_TIME\_ARRAY: long       ; length in bytes of RIS\_TIME array

< 56>           RES\_ARRAY1: long           ; an expansion entry is reserved

< 60>           WAVE\_ARRAY\_1: long           ; length in bytes of 1st simple  
   ; data array. In transmitted waveform,  
   ; represent the number of transmitted  
   ; bytes in accordance with the NP  
   ; parameter of the WFSU remote command  
   ; and the used format (see COMM\_TYPE).

< 64>           WAVE\_ARRAY\_2: long           ; length in bytes of 2nd simple  
   ; data array



< 68> RES\_ARRAY2: long  
 < 72> RES\_ARRAY3: long ; 2 expansion entries are reserved

The following variables identify the instrument

< 76> INSTRUMENT\_NAME: string  
 < 92> INSTRUMENT\_NUMBER: long  
 < 96> TRACE\_LABEL: string ; identifies the waveform.  
 <112> RESERVED1: word  
 <114> RESERVED2: word ; 2 expansion entries

The following variables describe the waveform and the time at which the waveform was generated.

<116> WAVE\_ARRAY\_COUNT: long ; number of data points in the data  
 ; array. If there are two data  
 ; arrays (FFT or Extrema), this number  
 ; applies to each array separately.  
 <120> PNTS\_PER\_SCREEN: long ; nominal number of data points  
 ; on the screen  
 <124> FIRST\_VALID\_PNT: long ; count of number of points to skip  
 ; before first good point  
 ; FIRST\_VALID\_POINT = 0  
 ; for normal waveforms.  
 <128> LAST\_VALID\_PNT: long ; index of last good data point  
 ; in record before padding (blanking)  
 ; was started.  
 ; LAST\_VALID\_POINT = WAVE\_ARRAY\_COUNT-1  
 ; except for aborted sequence  
 ; and rollmode acquisitions  
 <132> FIRST\_POINT: long ; for input and output, indicates  
 ; the offset relative to the  
 ; beginning of the trace buffer.  
 ; Value is the same as the FP parameter  
 ; of the WFSU remote command.  
 <136> SPARSING\_FACTOR: long ; for input and output, indicates  
 ; the sparsing into the transmitted  
 ; data block.  
 ; Value is the same as the SP parameter  
 ; of the WFSU remote command.  
 <140> SEGMENT\_INDEX: long ; for input and output, indicates the  
 ; index of the transmitted segment.  
 ; Value is the same as the SN parameter  
 ; of the WFSU remote command.  
 <144> SUBARRAY\_COUNT: long ; for Sequence, acquired segment count,  
 ; between 0 and NOM\_SUBARRAY\_COUNT  
 <148> SWEEPS\_PER\_ACQ: long ; for Average or Extrema,  
 ; number of sweeps accumulated  
 ; else 1  
 <152> POINTS\_PER\_PAIR: word ; for Peak Detect waveforms (which  
 always ; include data points in DATA\_ARRAY\_1  
 and ; min/max pairs in DATA\_ARRAY\_2).  
 ; Value is the number of data points for

```

; each min/max pair.

<154>    PAIR_OFFSET: word      ; for Peak Detect waveforms only
; Value is the number of data points by
; which the first min/max pair in
; DATA_ARRAY_2 is offset relative to the
; first data value in DATA_ARRAY_1.

<156>    VERTICAL_GAIN: float

<160>    VERTICAL_OFFSET: float ; to get floating values from raw data :
; VERTICAL_GAIN * data - VERTICAL_OFFSET

<164>    MAX_VALUE: float      ; maximum allowed value. It corresponds
; to the upper edge of the grid.

<168>    MIN_VALUE: float      ; minimum allowed value. It corresponds
; to the lower edge of the grid.

<172>    NOMINAL_BITS: word    ; a measure of the intrinsic precision
; of the observation: ADC data is 8 bit
; averaged data is 10-12 bit, etc.

<174>    NOM_SUBARRAY_COUNT: word ; for Sequence, nominal segment count
; else 1

<176>    HORIZ_INTERVAL: float ; sampling interval for time domain
; waveforms

<180>    HORIZ_OFFSET: double  ; trigger offset for the first sweep of
; the trigger, seconds between the
; trigger and the first data point

<188>    PIXEL_OFFSET: double  ; needed to know how to display the
; waveform

<196>    VERTUNIT: unit_definition ; units of the vertical axis

<244>    HORUNIT: unit_definition ; units of the horizontal axis

<292>    HORIZ_UNCERTAINTY: float ; uncertainty from one acquisition to
the ; next, of the horizontal offset in
seconds

<296>    TRIGGER_TIME: time_stamp ; time of the trigger

<312>    ACQ_DURATION: float    ; duration of the acquisition (in sec)
; in multi-trigger waveforms.
; (e.g. sequence, RIS, or averaging)

<316>    RECORD_TYPE: enum
        _0      single_sweep
        _1      interleaved
        _2      histogram
        _3      graph
        _4      filter_coefficient
        _5      complex
        _6      extrema
        _7      sequence_obsolete
        _8      centered_RIS
        _9      peak_detect
        endenum

<318>    PROCESSING_DONE: enum
        _0      no_processing
        _1      fir_filter
        _2      interpolated

```

```
_3      sparsed
_4      autoscaled
_5      no_result
_6      rolling
_7      cumulative
endenum
```

<320> RESERVED5: word ; expansion entry

<322> RIS\_SWEEPS: word ; for RIS, the number of sweeps  
; else 1

The following variables describe the basic acquisition conditions used when the waveform was acquired

<324> TIMEBASE: enum

```
_0      1_ns/div
_1      2.5_ns/div
_2      5_ns/div
_3      10_ns/div
_4      25_ns/div
_5      50_ns/div
_6      100_ns/div
_7      250_ns/div
_8      500_ns/div
_9      1_us/div
_10     2.5_us/div
_11     5_us/div
_12     10_us/div
_13     25_us/div
_14     50_us/div
_15     100_us/div
_16     250_us/div
_17     500_us/div
_18     1_ms/div
_19     2.5_ms/div
_20     5_ms/div
_21     10_ms/div
_22     25_ms/div
_23     50_ms/div
_24     100_ms/div
_25     250_ms/div
_26     500_ms/div
_27     1_s/div
_28     2.5_s/div
_29     5_s/div
_30     10_s/div
_31     25_s/div
_32     50_s/div
_100    EXTERNAL
endenum
```

<326> VERT\_COUPLING: enum

```
_0      DC_50_ohms
_1      ground
_2      DC_1MOhm
_3      ground
_4      AC_1MOhm
endenum
```

<328> PROBE\_ATT: float

<332> FIXED\_VERT\_GAIN: enum

```
_0      2_mV/div
_1      5_mV/div
_2      10_mV/div
_3      20_mV/div
_4      50_mV/div
```

```
_5      100_mv/div
_6      200_mv/div
_7      500_mv/div
_8      1_v/div
_9      2_v/div
_10     5_v/div
_11     10_v/div
endenum
```

```
<334>   BANDWIDTH_LIMIT: enum
        _0      off
        _1      on
endenum
```

```
<336>   VERTICAL_VERNIER: float
```

```
<340>   ACQ_VERT_OFFSET: float
```

```
<344>   WAVE_SOURCE: enum
        _0      CHANNEL_1
        _1      CHANNEL_2
        _2      CHANNEL_3
        _3      CHANNEL_4
        _9      UNKNOWN
endenum
```

```
/00      ENDBLOCK
```

```
=====  
DAT1: ARRAY
```

Explanation of the data array DAT1.  
This is an optional secondary data array for special types of waveforms,  
and it has not been implemented in current DSO,  
so when you query it, it will always return 'ALL'.

```
< 0>      MEASUREMENT: data      ; the actual format of a data is
                                     ; given in the WAVEDESC descriptor
                                     ; by the COMM_TYPE variable.
```

```
/00      ENDARRAY
```

```
=====  
DAT2: ARRAY
```

Explanation of the data array DAT2.  
This main data array is always present. It is the only data array for  
waveforms.  
The data item is repeated for each acquired or computed data point  
of the first data array of any waveform.

```
< 0>      MEASUREMENT: data      ; the actual format of a data is
                                     ; given in the WAVEDESC descriptor
                                     ; by the COMM_TYPE variable.
```

```
/00      ENDARRAY
```

```
=====  
ALL: BLOCK
```

Explanation of the ALL.  
This data is identical to DESC block, followed by DAT1 and DAT2 array.  
ALL is an accepted alias name for the combined arrays DESC, DAT1 and  
DAT2.

```
< 0>      MEASUREMENT_1: data      ; data in DATA_ARRAY_1.  
< 0>      MEASUREMENT_2: data      ; data in DATA_ARRAY_2.  
/00          ENDARRAY  
  
000000          ENDTEMPLATE
```